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# SYMMETRIES IN HEXAGONAL QUASIGROUPS

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ABSTRACT. Hexagonal quasigroup is idempotent, medial and semisymmetric quasigroup. In this article we define and study symmetries about a point, segment and ordered triple of points in hexagonal quasigroups. The main results are the theorems on composition of two and three symmetries.

#### 1. Introduction

Hexagonal quasigroups are defined in [3].

**Definition.** A quasigroup  $(Q, \cdot)$  is said to be *hexagonal* if it is idempotent, medial and semisymmetric, i.e. if its elements a, b, c satisfy:

(id) 
$$a \cdot a = a$$

(med) 
$$(a \cdot b) \cdot (c \cdot d) = (a \cdot c) \cdot (b \cdot d)$$

(ss) 
$$a \cdot (b \cdot a) = (a \cdot b) \cdot a = b.$$

From (id) and (med) easily follows distributivity

(ds) 
$$a \cdot (b \cdot c) = (a \cdot b) \cdot (a \cdot c), \quad (a \cdot b) \cdot c = (a \cdot c) \cdot (b \cdot c)$$

When it doesn't cause confusion, we can omit the sign "·", e.g. instead of  $(a \cdot b) \cdot (c \cdot d)$  we may write  $ab \cdot cd$ .

In this article, Q will always be a hexagonal quasigroup.

The basic example of hexagonal quasigroup is formed by the points of Euclidean plane, with the operation  $\cdot$  such that the points a, b and  $a \cdot b$  form a positively oriented regular triangle. This structure was used for all the illustrations in this article.

Motivated by this example, Volenec in [3] and [4] introduced some geometric terms to any hexagonal quasigroup. Some of these terms can be defined in any idempotent medial quasigroup (see [2]) or even medial quasigroup (see [1]).

The elements of hexagonal quasigroup are called *points*, and pairs of points are called *segments*.

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**Definition.** We say that the points a, b, c and d form a parallelogram, and we write Par(a, b, c, d) if  $bc \cdot ab = d$  holds. (Fig. 1)

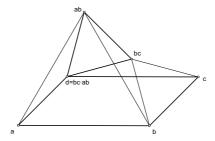


FIGURE 1. Parallelogram (definition)

Accordingly to [3], the structure  $(Q, \operatorname{Par})$  is a parallelogram space. In other words,  $\operatorname{Par}$  is a quaternary relation on Q (instead of  $(a,b,c,d) \in \operatorname{Par}$  we write  $\operatorname{Par}(a,b,c,d)$ ) such that:

- 1. Any three of the four points a, b, c, d uniquely determine the fourth, such that Par(a, b, c, d).
- 2. If (e, f, g, h) is any cyclic permutation of (a, b, c, d) or (d, c, b, a), then Par (a, b, c, d) implies Par (e, f, g, h).
- 3. From Par (a, b, c, d) and Par (c, d, e, f) it follows Par (a, b, f, e). (Fig. 2)

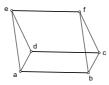


FIGURE 2. Property 3 of the relation Par

Accordingly to [3]:

**Theorem 1.** From Par  $(a_1, b_1, c_1, d_1)$  and Par  $(a_2, b_2, c_2, d_2)$  it follows Par  $(a_1a_2, b_1b_2, c_1c_2, d_1d_2)$ .

In the rest of this section we present some definitions and results from [5].

**Definition.** The point m is a *midpoint* of the segment  $\{a,b\}$ , if Par(a,m,b,m) holds. This is denoted by M(a,m,b).

**Remark.** For given a, b such m can exist or not; and it can be unique or not.

**Theorem 2.** Let M(a, m, c). Then M(b, m, d) and Par(a, b, c, d) are equivalent.

**Definition.** The point m is called a *center of a parallelogram*  $\operatorname{Par}(a,b,c,d)$  if  $\operatorname{M}(a,m,c)$  and  $\operatorname{M}(b,m,d)$ .

**Definition.** The function  $T_{a,b}: Q \to Q$ ,

$$T_{a,b}(x) = ab \cdot xa$$

is called *transfer* by the vector [a, b]. (Fig. 3)

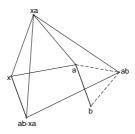


FIGURE 3. Transfer by the vector [a, b]

**Lemma 1.** For any  $a, b, x \in Q$ ,  $Par(x, a, b, T_{a,b}(x))$ . The equality  $T_{a,b} = T_{c,d}$  is equivalent to Par(a, b, d, c).

**Theorem 3.** The set of all transfers is a commutative group. Specially, the composition of two transfers is a transfer. The inverse of  $T_{a,b}$  is  $T_{b,a}$ .

## 2. Symmetries in hexagonal quasigroup

**Lemma 2.** For any points  $a, b, c, x \in Q$ , the following equalities hold

$$(xa \cdot a)a = a(a \cdot ax) = xa \cdot ax$$
$$(xa \cdot b)a = a(b \cdot ax) = xa \cdot bx = xb \cdot ax = b(a \cdot bx) = (xb \cdot a)b$$
$$(xa \cdot b)c = a(b \cdot cx) = (x \cdot ac) \cdot bx = xb \cdot (ac \cdot x)$$

**Proof.** Since Q is semisymmetric quasigroup, pq = r is equivalent to qr = p. First, we prove the last set of equalities.

From  $(b \cdot cx) \cdot (xa \cdot b)c \stackrel{\text{(med)}}{=} b(xa \cdot b) \cdot (cx \cdot c) \stackrel{\text{(ss)}}{=} xa \cdot x \stackrel{\text{(ss)}}{=} a$ , it follows  $a(b \cdot cx) = (xa \cdot b)c$ .

From  $(ac \cdot x) \cdot (x(ac) \cdot bx) \stackrel{\text{(med)}}{=} (ac \cdot x(ac))(x \cdot bx) \stackrel{\text{(ss)}}{=} xb$ , it follows  $(x \cdot ac) \cdot bx = xb \cdot (ac \cdot x)$ .

From  $((x \cdot ac) \cdot bx)(xa \cdot b) \stackrel{\text{(med)}}{=} ((x \cdot ac) \cdot xa)(bx \cdot b) \stackrel{\text{(med)}}{=} ((xx) \cdot (ac)a)(bx \cdot b) \stackrel{\text{(id,ss)}}{=} (xc)x \stackrel{\text{(ss)}}{=} c$ , it follows  $(xa \cdot b)c = (x \cdot ac) \cdot bx$ .

Now putting a=b=c we obtain the first line of equalities, and putting a=c the second line.  $\Box$ 

**Definition.** Symmetry with respect to the point a is the function  $\sigma_a:Q\to Q$  defined by (see Fig. 4)

$$\sigma_a(x) = a(a \cdot ax) = (xa \cdot a)a = xa \cdot ax$$
.

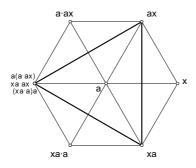


FIGURE 4. Symmetry with respect to the point a

From  $\sigma_a(x) = xa \cdot ax$  it follows  $\operatorname{Par}(a, x, a, \sigma_a(x))$ , so we have:

Corollary 1. The equality  $\sigma_m(a) = b$  is equivalent to M(a, m, b).

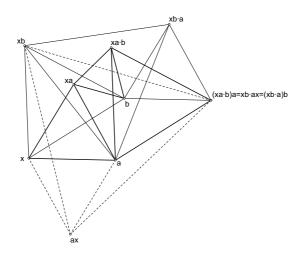


FIGURE 5. Symmetry with respect to the line segment  $\{a,b\}$ 

The function  $\sigma_a(x) = xa \cdot ax$  can be generalised this way:

**Definition.** The function  $\sigma_{a,b}:Q\to Q$  defined by

$$\sigma_{a,b}(x) = xa \cdot bx,$$

is called symmetry with respect to the segment  $\{a,b\}$ . (Fig. 5)

It follows immediately:

Corollary 2. For any  $a, b, x \in Q$ 

$$\sigma_{a,a} = \sigma_a \,, \qquad \sigma_{a,b} = \sigma_{b,a} \,, \qquad \operatorname{Par} \left( a, x, b, \sigma_{a,b}(x) \right).$$

**Theorem 4.** The equality  $\sigma_{a,b} = \sigma_m$  is equivalent to M(a, m, b).

**Proof.** Let M(a, m, b) and let  $x \in Q$ . From Par  $(a, x, b, \sigma_{a,b}(x))$  and M(a, m, b) and Theorem 2 we obtain  $M(x, m, \sigma_{a,b}(x))$ , and now from Corollary 1  $\sigma_m(x) = \sigma_{a,b}(x)$ .

Inversely, from  $\sigma_{a,b} = \sigma_m$  it follows  $\sigma_m(a) = \sigma_{a,b}(a) = aa \cdot ba = b$ , and now Corollary 1 implies M (a, m, b).

The function  $\sigma_a(x) = a(a \cdot ax)$  can be generalised in another way:

**Definition.** The function  $\sigma_{a,b,c}(x) = (xa \cdot b)c$  is called *symmetry with respect to the ordered triple of points* (a,b,c). (Fig. 6)

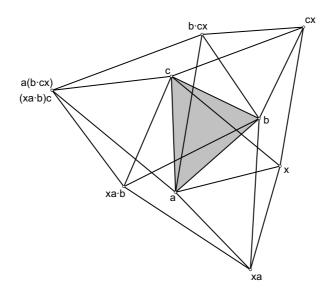


FIGURE 6. Symmetry with respect to the ordered triple of points (a, b, c)

Lemma 2 implies

$$\sigma_{a,b,c}(x) = (xa \cdot b)c = a(b \cdot cx) = (x \cdot ac) \cdot bx = xb \cdot (ac \cdot x) \,.$$

It immediately follows:

Corollary 3. For any  $a, b, c, x \in Q$ 

$$\sigma_a = \sigma_{a,a,a}, \quad \sigma_{a,b} = \sigma_{a,b,a} = \sigma_{b,a,b}, \quad \sigma_{a,b,c} = \sigma_{ac,b}, \quad \operatorname{Par}\left(ac, x, b, \sigma_{a,b,c}(x)\right).$$

Note that different order of points (e.g. (b, a, c)) produces different symmetry.

**Theorem 5.** The symmetry  $\sigma_{a,b,c}$  is an involutory automorphism of the hexagonal quasigroup  $(Q,\cdot)$ .

**Proof.** We first show that  $\sigma_{a,b,c} \circ \sigma_{a,b,c}$  is identity:

$$\sigma_{a,b,c}\big(\sigma_{a,b,c}(x)\big) = \sigma_{a,b,c}\big((xa \cdot b)c\big) = a \cdot b\big(c \cdot (xa \cdot b)c\big) \stackrel{\text{(ss)}}{=} a \cdot b(xa \cdot b) \stackrel{\text{(ss)}}{=} a \cdot xa \stackrel{\text{(ss)}}{=} x.$$

It follows that  $\sigma_{a,b,c}$  is a bijection. Further:

$$\begin{split} \sigma_{a,b,c}(xy) &= (xy \cdot a)b \cdot c \overset{\text{(ds)}}{=} (xa \cdot ya)b \cdot c \\ \overset{\text{(ds)}}{=} (xa \cdot b)(ya \cdot b) \cdot c \overset{\text{(ds)}}{=} (xa \cdot b)c \cdot (ya \cdot b)c = \sigma_{a,b,c}(x) \cdot \sigma_{a,b,c}(y) \,, \end{split}$$

so  $\sigma_{a,b,c}$  is an automorphism.

From Theorem 5 and Corollary 3, it follows:

Corollary 4. Symmetries  $\sigma_a$  and  $\sigma_{a,b}$  are involutory automorphisms of the hexagonal quasigroup  $(Q, \cdot)$ .

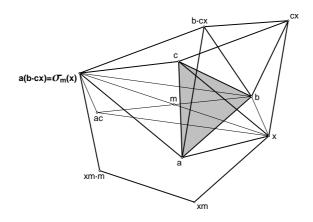


FIGURE 7. Theorem 6

**Theorem 6.** The equality  $\sigma_{a,b,c} = \sigma_m$  is equivalent to M (ac, m, b). (Fig. 7)

**Proof.** The statement follows immediately from  $\sigma_{a,b,c} = \sigma_{ac,b}$  (Corollary 3) and Theorem 4.

The following two theorems are about the compositions of two and three symmetries.

**Theorem 7.** The composition of two symmetries is a transfer (Fig. 8). More precisely, for any  $a_1, a_2, a_3, b_1, b_2, b_3$ 

$$\sigma_{b_1,b_2,b_3} \circ \sigma_{a_1,a_2,a_3} = T_{a_1a_3,b_1b_3} \circ T_{a_2,b_2}$$
.

**Proof.** Since composition of two transfers is a transfer (Theorem 3), it's enough to prove the above equality.

Let  $x \in Q$  be any point, and let  $y = \sigma_{a_1,a_2,a_3}(x)$ ,  $z = \sigma_{b_1,b_2,b_3}(y)$ , and  $w = T_{a_2,b_2}(x)$ . We need to prove that  $T_{a_1a_3,b_1b_3}(w) = z$ .

Lemma 1 implies  $Par(x, a_2, b_2, w)$ , and from Corollary 3 it follows  $Par(a_1a_3, x, a_2, y)$  and  $Par(b_1b_3, y, b_2, z)$ .

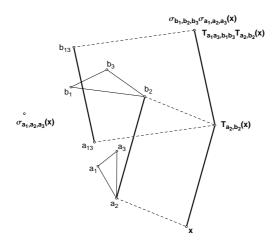


FIGURE 8. Theorem 7

Property 2 of Par implies  $Par(b_2, w, x, a_2)$  and  $Par(x, a_2, y, a_1a_3)$ , and now from Property 3 it follows  $Par(b_2, w, a_1a_3, y)$ .

Similarly, Property 2 implies  $Par(w, a_1a_3, y, b_2)$  and  $Par(y, b_2, z, b_1b_3)$ , and because of Property 3 it follows  $Par(w, a_1a_3, b_1b_3, z)$ .

From this relation and Lemma 1 it finally follows  $z = T_{a_1 a_3, b_1 b_3}(w)$ .

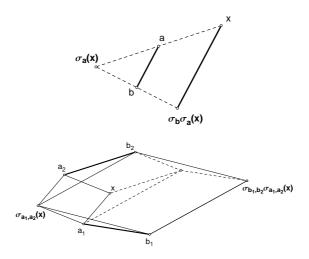


Figure 9. Corollary 5

Using Corollary 3 we obtain (see Fig. 9):

Corollary 5. For  $a, b \in Q$ ,  $\sigma_b \circ \sigma_a = T_{a,b} \circ T_{a,b}$ . For  $a_1, a_2, b_1, b_2 \in Q$ ,  $\sigma_{b_1, b_2} \circ \sigma_{a_1, a_2} = T_{a_1, b_1} \circ T_{a_2, b_2}$ . Corollary 6. The equation  $\sigma_{a_1,a_2,a_3} = \sigma_{b_1,b_2,b_3}$  is equivalent to  $\operatorname{Par}(a_1a_3,b_1b_3,a_2,b_2)$ .

**Proof.** By Theorem 5,  $\sigma_{a_1,a_2,a_3} = \sigma_{b_1,b_2,b_3}$  is equivalent to  $\sigma_{b_1,b_2,b_3} \circ \sigma_{a_1,a_2,a_3} =$  identity. From Theorem 7 we know  $\sigma_{b_1,b_2,b_3} \circ \sigma_{a_1,a_2,a_3} = T_{a_1a_3,b_1b_3} \circ T_{a_2,b_2}$ , so the initial equality is equivalent to  $T_{a_1a_3,b_1b_3} \circ T_{a_2,b_2} =$  identity. Because of Theorem 3 this is equivalent to  $T_{a_1a_3,b_1b_3} = T_{b_2,a_2}$ , and further because of Lemma 1 to  $T_{a_1a_3,b_1b_3,a_2,b_2}$ .

**Theorem 8.** The composition of three symmetries is a symmetry. More precisely, for any  $a_1, a_2, a_3, b_1, b_2, b_3, c_1, c_2, c_3$ , and for  $d_1, d_2, d_3$  such that  $Par(a_i, b_i, c_i, d_i)$ , for i = 1, 2, 3,

$$\sigma_{c_1,c_2,c_3} \circ \sigma_{b_1,b_2,b_3} \circ \sigma_{a_1,a_2,a_3} = \sigma_{d_1,d_2,d_3}$$
.

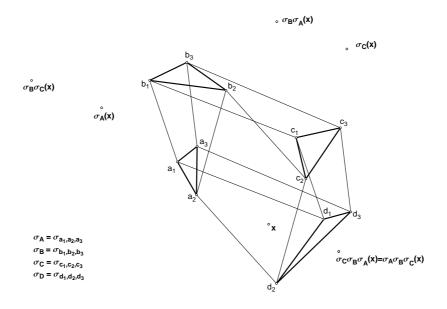


FIGURE 10. Corollary 7

**Proof.** Let  $x \in Q$  be any point, and let  $y, z, t \in Q$  be such that

$$y = \sigma_{a_1,a_2,a_3}(x)$$
 i.e.  $Par(a_1a_3, x, a_2, y)$   
 $z = \sigma_{b_1,b_2,b_3}(y)$  i.e.  $Par(b_1b_3, y, b_2, z)$   
 $t = \sigma_{c_1,c_2,c_3}(z)$  i.e.  $Par(c_1c_3, z, c_2, t)$ 

and let  $w \in Q$  be such that  $Par(d_2, a_2, y, w)$ . We need to prove that  $\sigma_{d_1, d_2, d_3}(x) = t$ , i.e.  $Par(d_1d_3, x, d_2, t)$ .

From Par  $(a_1, b_1, c_1, d_1)$  and Par  $(a_3, b_3, c_3, d_3)$ , because of Theorem 1 we get Par  $(a_1a_3, b_1b_3, c_1c_3, d_1d_3)$ .

Now we use Property 3 of the relation Par to conclude:

The relations on the left hand side are valid because of the assumptions, previous conclusions and Property 2 of Par .

The last obtained relation is equivalent to  $Par(d_1d_3, x, d_2, t)$ .

Corollary 7. For any  $a_i, b_i, c_i \in Q$ , i = 1, 2, 3 (see Fig. 10)

$$\sigma_{a_1,a_2,a_3} \circ \sigma_{b_1,b_2,b_3} \circ \sigma_{c_1,c_2,c_3} = \sigma_{c_1,c_2,c_3} \circ \sigma_{b_1,b_2,b_3} \circ \sigma_{a_1,a_2,a_3}.$$

Corollary 8. For any  $a, b, c \in Q$ ,  $\sigma_a \circ \sigma_b \circ \sigma_c = \sigma_c \circ \sigma_b \circ \sigma_a$ .

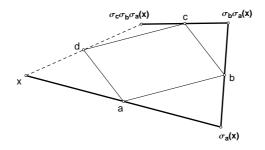


Figure 11. Corollary 9

Corollary 9. For  $a, b, c, d \in Q$ , if Par(a, b, c, d) then  $\sigma_c \circ \sigma_b \circ \sigma_a = \sigma_d$ . (Fig. 11)

It is known (in Euclidean geometry) that midpoints of sides of any quadrilateral form a parallelogram. We can state the same fact in terms of hexagonal quasigroup in the following way:

**Theorem 9.** From M(x, a, y), M(y, b, z), M(z, c, t) and Par(a, b, c, d) it follows M(x, d, t).

**Proof.** M (x, a, y), M (y, b, z) and M (z, c, t) are equivalent to  $\sigma_a(x) = y$ ,  $\sigma_b(y) = z$  and  $\sigma_c(z) = t$  respectively. Therefore, the three assumptions can be written as:  $\sigma_c(\sigma_b(\sigma_a(x))) = t$ . From the preceding corollary it follows  $\sigma_d(x) = t$ , i.e. M (x, d, t).

**Theorem 10.** Let  $a_i, b_i, c_i, d_i$ , i = 1, 2, 3 be points such that  $Par(a_i, b_i, c_i, d_i)$ , for i = 1, 2, 3, and a, b, c, d points satisfying Par(a, b, c, d). Then

Par 
$$(\sigma_{a_1,a_2,a_3}(a), \sigma_{b_1,b_2,b_3}(b), \sigma_{c_1,c_2,c_3}(c), \sigma_{d_1,d_2,d_3}(d))$$
.

**Proof.** From Par  $(a_1, b_1, c_1, d_1)$  and Par  $(a_3, b_3, c_3, d_3)$  and Theorem 1 it follows Par  $(a_1a_3, b_1b_3, c_1c_3, d_1d_3)$ , and from Par (a, b, c, d) and Par  $(a_2, b_2, c_2, d_2)$  it follows Par  $(a_2a, b_2b, c_2c, d_2d)$ . Similarly we obtain Par  $(a \cdot a_1a_3, b \cdot b_1b_3, c \cdot c_1c_3, d \cdot d_1d_3)$ , and finally Par  $((a \cdot a_1a_3) \cdot a_2a, (b \cdot b_1b_3) \cdot b_2b, (c \cdot c_1c_3) \cdot c_2c, (d \cdot d_1d_3) \cdot d_2d)$ , which proves the Theorem.

We immediately have:

**Corollary 10.** From Par (a, b, c, d) and Par (p, q, r, s) it follows

Par 
$$(\sigma_p(a), \sigma_q(b), \sigma_r(c), \sigma_s(d))$$
.

Corollary 11. For  $p, q, r \in Q$ , from Par(a, b, c, d) it follows

$$\operatorname{Par}\left(\sigma_{p,q,r}(a),\sigma_{p,q,r}(b),\sigma_{p,q,r}(c),\sigma_{p,q,r}(d)\right).$$

Corollary 12. For  $p \in Q$ , from Par (a, b, c, d) it follows

Par 
$$(\sigma_p(a), \sigma_p(b), \sigma_p(c), \sigma_p(d))$$
.

Corollary 13. For  $p, q, r \in Q$ , from M(a, b, c) it follows

$$M\left(\sigma_{p,q,r}(a),\sigma_{p,q,r}(b),\sigma_{p,q,r}(c)\right).$$

Corollary 14. For  $p \in Q$ , from M(a,b,c) it follows  $M(\sigma_p(a),\sigma_p(b),\sigma_p(c))$ .

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