# CONDITIONAL OSCILLATION OF HALF－LINEAR DIFFERENTIAL EQUATIONS WITH PERIODIC COEFFICIENTS 

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Abstract．We show that the half－linear differential equation

$$
\begin{equation*}
\left[r(t) \Phi\left(x^{\prime}\right)\right]^{\prime}+\frac{s(t)}{t^{p}} \Phi(x)=0 \tag{*}
\end{equation*}
$$

with $\alpha$－periodic positive functions $r, s$ is conditionally oscillatory，i．e．，there exists a constant $K>0$ such that $⿴ 囗 十$ with $\frac{\gamma s(t)}{t^{p}}$ instead of $\frac{s(t)}{t^{p}}$ is oscillatory for $\gamma>K$ and nonoscillatory for $\gamma<K$ ．

## 1．Introduction

In this paper we study oscillatory properties of the half－linear equation

$$
\begin{equation*}
\left[r(t) \Phi\left(x^{\prime}\right)\right]^{\prime}+s(t) \Phi(x)=0, \quad \Phi(x)=x|x|^{p-2} \tag{1.1}
\end{equation*}
$$

where $r$ and $s$ are $\alpha$－periodic $(\alpha>0)$ positive continuous functions and $p>1$ is a real number conjugated with $q$ ，which means，that

$$
\frac{1}{p}+\frac{1}{q}=1
$$

Our research is motivated by the paper of K．M．Schmidt［2］．In that paper，the author studies oscillatory properties of the linear differential equation

$$
\begin{equation*}
\left[r(t) x^{\prime}\right]^{\prime}+\frac{\gamma s(t)}{t^{2}} x=0, \quad t>0 \tag{1.2}
\end{equation*}
$$

where $r, s$ are positive $\alpha$－periodic functions and $\gamma$ is a real parameter．The main result of［2］（after a minor reformulation）reads as follows．

Theorem 1．1．Let

$$
K=\frac{1}{4}\left(\frac{1}{\alpha} \int_{0}^{\alpha} \frac{\mathrm{d} \tau}{r}\right)^{-1}\left(\frac{1}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau\right)^{-1}
$$

then 1．2 is oscillatory for $\gamma>K$ and nonoscillatory for $\gamma<K$ ．

[^0]The result presented in the previous theorem is interesting from the following point of view. It is known that the Euler equation

$$
\begin{equation*}
x^{\prime \prime}+\frac{\gamma}{t^{2}} x=0 \tag{1.3}
\end{equation*}
$$

is conditionally oscillatory (i.e. there exists a constant $\gamma_{0}$ such that equation is oscillatory for $\gamma>\gamma_{0}$ and nonoscillatory for $\gamma<\gamma_{0}$ ) with the oscillation constant $\gamma_{0}=\frac{1}{4}$. Theorem 1.1 shows that constant coefficients in (1.3) can be replaced by periodic functions and resulting equation remains conditionally oscillatory.

In our paper we show that a similar situation we have for half-linear equations. The Euler type half-linear differential equation

$$
\begin{equation*}
\left[\Phi\left(x^{\prime}\right)\right]^{\prime}+\frac{\gamma}{t^{p}} \Phi(x)=0 \tag{1.4}
\end{equation*}
$$

is conditionally oscillatory (with $\gamma_{0}=\left(\frac{p-1}{p}\right)^{p}$ ). The main result of our paper shows that also in half-linear case constant coefficients can be replaced by periodic ones, i.e., the equation

$$
\left[r(t) \Phi\left(x^{\prime}\right)\right]^{\prime}+\frac{\gamma s(t)}{t^{p}} \Phi(x)=0
$$

with periodic functions $r, s$ remains conditionally oscillatory.
The basic difference between linear and half-linear differential equations is the fact that the solution space of half-linear equations is not additive (but remains homogeneous). The missing additivity (more or less) induces further differences as the absence of Wronskian-type identity, transform theory or reduction of order formula. Despite that, many results from linear equations may be extended to 1.1 (see e.g. [1).

## 2. Preliminary results

We start with elements of oscillation theory of half-linear equation (1.1). It is known, see e.g. [1], that the linear Sturmian theory extends verbatim to half-linear equations. In particular, we have the following statements.

Proposition 2.1 (Sturmian separation theorem). Let $t_{1}<t_{2}$ be two consecutive zeros of a nontrivial solution $x$ of (1.1). Then any other solution of this equation, which is not proportional to $x$, has exactly one zero in $\left(t_{1}, t_{2}\right)$.

Proposition 2.2 (Sturmian comparison theorem). Let $t_{1}<t_{2}$ be two consecutive zeros of a nontrivial solution $x$ of (1.1) and suppose, that

$$
\begin{equation*}
S(t) \geq s(t), \quad r(t) \geq R(t)>0 \tag{2.1}
\end{equation*}
$$

for $t \in\left[t_{1}, t_{2}\right]$. Then any solution of the equation

$$
\begin{equation*}
\left[R(t) \Phi\left(x^{\prime}\right)\right]^{\prime}+S(t) \Phi(x)=0 \tag{2.2}
\end{equation*}
$$

has a zero in $\left(t_{1}, t_{2}\right)$ or it is a multiple of the solution $x$. The last possibility is excluded if one of the inequalities in (2.1) is strict on a set of positive measure.

If (2.1) are satisfied in a given interval $I$, then $(2.2)$ is said to be the majorant equation of 1.1 on $I$ and 1.1 is said to be the minorant equation of 2.2 on $I$.

Proposition 2.1 implies that (1.1) can be classified as oscillatory or nonoscillatory. Recall, that points $t_{1}, t_{2} \in \mathbb{R}$ are said to be conjugate relative to equation (1.1), if there exists a nontrivial solution $x$ of this equation, such that $x\left(t_{1}\right)=x\left(t_{2}\right)=0$. Then, equation (1.1) is said to be disconjugate on an interval $I$, if this interval does not contain two points conjugate relative to equation 1.1). In the opposite case, equation (1.1) is said to be conjugate on $I$.

Now, let us recall the definition of oscillation and nonoscillation of equation 1.1) at zero and infinity.

Definition 1. Equation (1.1) is said to be nonoscillatory at 0 , if there exists $\varepsilon>0$ such that equation (1.1) is disconjugate on $[0, \varepsilon]$. In the opposite case, equation (1.1) is said to be oscillatory at 0 .

Definition 2. Equation (1.1) is said to be nonoscillatory at $\infty$, if there exists $T_{0} \in \mathbb{R}$ such that equation $(1.1)$ is disconjugate on $\left[T_{0}, T\right]$ for every $T>T_{0}$. In the opposite case, equation 1.1 is said to be oscillatory at $\infty$.

If equation (1.1) is nonoscillatory at zero, then there exists a solution $v_{\max }$ of the Riccati equation

$$
\begin{equation*}
v^{\prime}+s(t)+(p-1) r^{1-q}(t)|v|^{q}=0 \tag{2.3}
\end{equation*}
$$

associated to equation (1.1) such that $v_{\max }(t)>v(t)$ for $t$ from a right neighbourhood of 0 for any other solution $v$ of 2.3 which is defined in a right neighbourhood of 0 . If equation (1.1) is nonoscillatory at infinity, then there exists a solution $v_{\text {min }}$ of Riccati equation (2.3) such that $v_{\min }(t)<v(t)$ for any other solution for large $t$. We call $v_{\max }$ the maximal solution of 2.3 and $v_{\min }$ the minimal solution of 2.3).

Then, we define the principal solution of (1.1) at zero [infinity] as the nontrivial solution of the equation

$$
x^{\prime}=\Phi^{-1}\left(\frac{v_{\max }(t)}{r(t)}\right) x, \quad\left[x^{\prime}=\Phi^{-1}\left(\frac{v_{\min }(t)}{r(t)}\right) x\right]
$$

Now, let us briefly recall some basic facts concerning the half-linear Euler equation (1.4).

As mentioned in Introduction, equation (1.4) is conditionally oscillatory both at $t=0$ and $t=\infty$ with the oscillation constant $\gamma_{0}=\left(\frac{p-1}{p}\right)^{p}$ (see [1]).

Let $0<\gamma<\gamma_{0}$, then (1.4) is not only nonoscillatory at 0 and $\infty$ but also disconjugated on $(0, \infty)$. Substituting $x(t)=t^{\lambda}$ into (1.4), we obtain an algebraic equation for $\lambda$

$$
|\lambda|^{p}-\Phi(\lambda)+\frac{\gamma}{p-1}=0
$$

and solving this equation, we find, that its roots $\lambda_{2}<\lambda_{1}$ satisfy

$$
0<\lambda_{2}<\frac{p-1}{p}<\lambda_{1}<1
$$

The principal solution of (1.4) at zero is $t^{\lambda_{1}}$, principal solution of (1.4) at infinity is $t^{\lambda_{2}}$, maximal and minimal solutions of the associated Riccati equation

$$
w^{\prime}+\frac{\gamma}{t^{p}}+(p-1)|w|^{q}=0
$$

are

$$
w_{\max }=\Phi\left(\lambda_{1}\right) t^{1-p}, \quad w_{\min }=\Phi\left(\lambda_{2}\right) t^{1-p}
$$

respectively.
Using the change of independent variable $t=\mathrm{e}^{s}, s \in \mathbb{R}$, we convert equation (1.4) into the equation with constant coefficients

$$
\begin{equation*}
\left[\Phi\left(y^{\prime}\right)\right]^{\prime}-(p-1) \Phi\left(y^{\prime}\right)+\gamma \Phi(y)=0 \tag{2.4}
\end{equation*}
$$

The corresponding Riccati equation is

$$
\begin{equation*}
u^{\prime}-(p-1) u+(p-1)|u|^{q}+\gamma=0 . \tag{2.5}
\end{equation*}
$$

Denote

$$
F(u):=\gamma-(p-1) u+(p-1)|u|^{q} .
$$

Following lemmas and theorems will be useful in the next section of our paper.
Lemma 2.1. Consider the Riccati equation

$$
\begin{equation*}
w^{\prime}+\frac{\gamma}{t^{p}}+(p-1)|w|^{p}=0, \quad \gamma<\left(\frac{p-1}{p}\right)^{p} \tag{2.6}
\end{equation*}
$$

associated with the nonoscillatory Euler half-linear equation (1.4). If $w(T) \geq 1$ for some $T>0$, then there exists $\tau \in\left(T \mathrm{e}^{-\int_{1}^{\infty} \frac{\mathrm{d} u}{F(u)}}, T\right)$ such that $w(\tau+)=\infty$.

Proof. We convert equation (1.4) into equation (2.4) with associated Riccati equation 2.5. Suppose, by contradiction, that there exists a solution $u$ of 2.5 extensible to $-\infty$ which satisfies $u(S) \geq 1$, where $S=\log T$, and integrate equation (2.5) on the interval [ $s, S$ ], where $S \in \mathbb{R}$ is fixed. Any solution, different from maximal and minimal ones (for which is $F(u)=0$ ), is implicitly given by the formula

$$
-\int_{u(s)}^{u(S)} \frac{\mathrm{d} u}{F(u)}=\int_{u(S)}^{u(s)} \frac{\mathrm{d} u}{F(u)}=S-s
$$

Hence

$$
\int_{1}^{\infty} \frac{\mathrm{d} u}{F(u)}>S-s=\log T-\log t=-\log \frac{t}{T}
$$

i.e., $t>T \mathrm{e}^{-\int_{1}^{\infty} \frac{\mathrm{d} u}{F(u)}}$ which implies the existence of $\tau \in\left(T \mathrm{e}^{-\int_{1}^{\infty} \frac{\mathrm{d} u}{F(u)}}, T\right)$ such that $w(\tau+)=\infty$.

Lemma 2.2. Consider Riccati equation (2.6) associated with the nonoscillatory half-linear Euler equation 1.4. If $v(T) \leq 0$ for some $T>0$, then there exists $\tau \in\left(T, T \mathrm{e}^{\int_{-\infty}^{0} \frac{\mathrm{~d} u}{F(u)}}\right)$ such that $v(\tau-)=-\infty$.

Proof. Similarly as in the Proof of Lemma 2.1, we use conversion to equations (2.4) and 2.5). Suppose the existence of a solution $u$ of 2.5) extensible to $\infty$ that satisfies $u(S) \leq 0$ and integrate equation (2.5) on the interval $[S, s]$, where $S \in \mathbb{R}$ is fixed. Any solution, different from maximal and minimal ones, is implicitly

$$
\begin{equation*}
\int_{u(s)}^{u(S)} \frac{\mathrm{d} u}{F(u)}=s-S \tag{2.7}
\end{equation*}
$$

Again, this contradicts the existence of such a solution $u$, because the left hand side of equation (2.7) is bounded and the right hand side tends to infinity as $s \rightarrow \infty$.

We finish this section with formulating a couple of lemmas and theorems without proofs (see e.g. [1).

Lemma 2.3. Consider a pair of equations

$$
\begin{align*}
& v^{\prime}+C(t)+(p-1)|v|^{q}=0,  \tag{2.8}\\
& w^{\prime}+c(t)+(p-1)|w|^{q}=0 \tag{2.9}
\end{align*}
$$

where $C(t) \geq c(t)>0$ for $t \in(a, b)$. If $\tau, T \in(a, b), \tau<T$, and a solution $w$ of (2.9) exists on $(\tau, T]$ and satisfies $w(\tau+)=\infty$, then there exists $\widetilde{\tau} \in[\tau, T)$ such that the solution $v$ of 2.8 given by the initial condition $v(T)=w(T)$ satisfies $v(\widetilde{\tau}+)=\infty$.

Lemma 2.4. Consider a pair of equations 2.8, 2.9). If $\tau, T \in(a, b), T<\tau$, and a solution $w$ of $(2.9)$ exists on $[T, \tau)$ and satisfies $w(\tau-)=-\infty$, then there exists $\widetilde{\tau} \in(T, \tau]$ such that the solution $v$ of (2.8) given by the initial condition $v(T)=w(T)$ satisfies $v(\widetilde{\tau}-)=-\infty$.

Following theorems compare solutions of a pair of Riccati equations associated with nonoscillatory half-linear differential equations.
Theorem 2.1. Consider a pair of half-linear differential equations

$$
\begin{align*}
{\left[r(t) \Phi\left(x^{\prime}\right)\right]^{\prime}+c(t) \Phi(x) } & =0  \tag{2.10}\\
{\left[R(t) \Phi\left(y^{\prime}\right)\right]^{\prime}+C(t) \Phi(y) } & =0 \tag{2.11}
\end{align*}
$$

and suppose that (2.11) is a Sturmian majorant of 2.10 for large $t$, i.e., there exists $T \in \mathbb{R}$ such that $0<R(t) \leq r(t), c(t) \leq C(t)$ for $t \in[T, \infty)$. Suppose that the majorant equation (2.11 is nonoscillatory and denote $v_{\min }, w_{\min }$ minimal solutions of

$$
\begin{align*}
v^{\prime}+c(t)+(p-1) r^{1-q}(t)|v|^{q} & =0,  \tag{2.12}\\
w^{\prime}+C(t)+(p-1) R^{1-q}(t)|w|^{q} & =0, \tag{2.13}
\end{align*}
$$

respectively. Then $v_{\min }(t) \leq w_{\min }(t)$ for large $t$.
Theorem 2.2. Consider a pair of half-linear differential equations (2.10, (2.11) and suppose that (2.11) is a Sturmian majorant of 2.10 for $t$ from a right neighbourhood of 0 , i.e., there exists $\varepsilon \in \mathbb{R}$ such that $0<R(t) \leq r(t), c(t) \leq$
$C(t)$ for $t \in(0, \varepsilon]$. Suppose that the majorant equation 2.11 is nonoscillatory and denote $v_{\max }$, $w_{\max }$ maximal solutions of 2.12, 2.13), respectively. Then $v_{\max }(t) \geq w_{\max }(t)$ for $t$ from a right neighbourhood of 0 .

## 3. Conditional oscillation of equations with periodic coefficients

The main result of our paper reads as follows.
Theorem 3.1. Consider the equation

$$
\begin{equation*}
\left[r(t) \Phi\left(x^{\prime}\right)\right]^{\prime}+\gamma \frac{s(t)}{t^{p}} \Phi(x)=0 \tag{3.1}
\end{equation*}
$$

where $r$ and $s$ are $\alpha$-periodic $(\alpha>0)$ positive continuous functions, and $\gamma \in \mathbb{R}$. Let

$$
\begin{equation*}
K:=q^{-p}\left(\frac{1}{\alpha} \int_{0}^{\alpha} \frac{\mathrm{d} \tau}{r^{q-1}}\right)^{1-p}\left(\frac{1}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau\right)^{-1} \tag{3.2}
\end{equation*}
$$

Then equation (3.1) is oscillatory if $\gamma>K$ and nonoscillatory if $\gamma<K$.
Proof. Let $\gamma>K$. Suppose, by contradiction, that (3.1) is nonoscillatory. It means that the associated Riccati equation (2.3) has a solution, which exists on some interval $[T, \infty)$. Because $r$ and $s$ are $\alpha$-periodic, positive and continuous, the equation

$$
\left[r_{\max } \Phi\left(x^{\prime}\right)\right]^{\prime}+\gamma \frac{s_{\min }}{t^{p}} \Phi(x)=0
$$

where

$$
\begin{aligned}
r_{\max } & =\max \{r(t), t \geq 0\} \\
s_{\min } & =\min \{s(t), t \geq 0\}
\end{aligned}
$$

is a minorant of 3.1, hence it is also nonoscillatory.
Denote $\mu:=\frac{s_{\text {min }}}{r_{\text {max }}}$. Solving the Euler-type equation

$$
\begin{equation*}
\left[\Phi\left(x^{\prime}\right)\right]^{\prime}+\gamma \frac{\mu}{t^{p}} \Phi(x)=0 \tag{3.3}
\end{equation*}
$$

with $\mu \gamma \leq\left(\frac{p-1}{p}\right)^{p}$ we find, that the principal solutions at zero and infinity are $t^{\lambda_{1}}$, $t^{\lambda_{2}}$, respectively, where $0<\lambda_{2}<\lambda_{1}<1$ are roots of the equation

$$
|\lambda|^{p}-\Phi(\lambda)+\gamma \frac{\mu}{p-1}=0
$$

see Section 2
Denote the maximal solution near $t=0$ of the Riccati equation associated to equation (3.3) by

$$
v_{\max }(t):=t^{1-p} \Phi\left(\lambda_{1}\right)
$$

and the minimal solution for large $t$ by

$$
v_{\min }(t):=t^{1-p} \Phi\left(\lambda_{2}\right)
$$

Introducing the function $w=\frac{r \Phi\left(x^{\prime}\right)}{\Phi(x)}$, we may transform equation (3.1) to the Riccati equation

$$
w^{\prime}+\gamma \frac{s(t)}{t^{p}}+(p-1) r^{1-q}(t)|w|^{q}=0
$$

with the maximal solution (at $t=0) w_{\max }$ and the minimal solution (at $t=\infty$ ) $w_{\text {min }}$ and denote

$$
\begin{equation*}
\zeta(t):=-w t^{p-1}, \quad \xi(t):=\frac{1}{\alpha} \int_{t}^{t+\alpha} \zeta(\tau) \mathrm{d} \tau \tag{3.4}
\end{equation*}
$$

First, suppose that there exists $t_{n} \rightarrow \infty$ such that $\zeta\left(t_{n}\right) \leq-1$, i.e.,

$$
w\left(t_{n}\right)=-t_{n}^{1-p} \zeta\left(t_{n}\right) \geq t_{n}^{1-p}>\Phi\left(\lambda_{1}\right) t_{n}^{1-p}=v_{\max }\left(t_{n}\right) \geq w_{\max }\left(t_{n}\right)
$$

Consider the solution of (3.3) given by the initial condition $v\left(t_{n}\right)=t_{n}^{1-p}$, i.e.,

$$
v\left(t_{n}\right)-v_{\max }\left(t_{n}\right)=\left[1-\Phi\left(\lambda_{1}\right)\right] t_{n}^{1-p}
$$

Then, by Lemma 2.1. there exists $\tau_{n} \rightarrow \infty, \tau_{n}<t_{n}$, such that $v\left(\tau_{n}+\right)=\infty$. But this means, by Lemma 2.3 that $w\left(\widetilde{\tau}_{n}+\right)=\infty$ for some $\tau_{n} \leq \widetilde{\tau}_{n}<t_{n}$, which is a contradiction.

Next, suppose that there exists a sequence $\hat{t}_{n} \rightarrow \infty$ such that $\zeta\left(\hat{t}_{n}\right) \geq 0$, i.e.,

$$
w\left(\hat{t}_{n}\right) \leq 0<v_{\min }\left(\hat{t}_{n}\right)=\Phi\left(\lambda_{2}\right) \hat{t}_{n}^{1-p} \leq w_{\min }\left(\hat{t}_{n}\right)
$$

This means (from Lemma 2.2 and Lemma 2.4, that there exists $\widehat{\tau}_{n}>\hat{t}_{n}$ such that $w\left(\widehat{\tau}_{n}-\right)=\infty$, which contradicts the fact, that $w(t)$ exists on $[T, \infty)$.

Hence, there exists $T_{0}>T$ such that

$$
v_{\min }=\Phi\left(\lambda_{2}\right) t^{1-p} \leq w \leq \Phi\left(\lambda_{1}\right) t^{1-p}=v_{\max }
$$

for $t \geq T_{0}$. Multiplying the last inequality by $-t^{p-1}$, we obtain

$$
0>-\Phi\left(\lambda_{2}\right) \geq \zeta(t) \geq-\Phi\left(\lambda_{1}\right)>-1
$$

Let us denote

$$
A:=(p-1)\left(\frac{p}{\alpha} \int_{0}^{\alpha} \frac{1}{r^{q-1}(\tau)} \mathrm{d} \tau\right)^{-\frac{1}{q}}, \quad B:=|\xi(t)|\left(\frac{p}{\alpha} \int_{0}^{\alpha} \frac{1}{r^{q-1}(\tau)} \mathrm{d} \tau\right)^{\frac{1}{q}}
$$

We have

$$
\begin{aligned}
\zeta^{\prime}(t) & =\left[-w(t) t^{p-1}\right]^{\prime}=-\left[w^{\prime}(t) t^{p-1}+(p-1) w(t) t^{p-2}\right] \\
& =\frac{1}{t}\left[(p-1) \zeta(t)+s(t) \gamma+(p-1) \frac{|\zeta(t)|^{q}}{r^{q-1}(t)}\right]
\end{aligned}
$$

Next, for $t \geq T_{0}$

$$
\begin{align*}
\int_{t}^{t+\alpha}\left|\zeta^{\prime}(\tau)\right| \mathrm{d} \tau & \leq \frac{1}{t} \int_{t}^{t+\alpha}\left|(p-1) \zeta(\tau)+\gamma s(\tau)+(p-1) \frac{|\zeta(\tau)|^{q}}{r^{q-1}(\tau)}\right| \mathrm{d} \tau \\
& \leq \frac{1}{t} \int_{t}^{t+\alpha}\left[(p-1)+\gamma s(\tau)+\frac{p-1}{r^{q-1}(\tau)}\right] \mathrm{d} \tau=\frac{C}{t} \tag{3.5}
\end{align*}
$$

where

$$
C:=\int_{t}^{t+\alpha}\left[(p-1)+\gamma s(\tau)+\frac{p-1}{r^{q-1}(\tau)}\right] \mathrm{d} \tau .
$$

Hence, for every $t>T_{0}$ and $\tau_{1}, \tau_{2} \in[t, t+\alpha]$ we have

$$
\left|\zeta\left(\tau_{1}\right)-\zeta\left(\tau_{2}\right)\right| \leq \int_{t}^{t+\alpha}\left|\zeta^{\prime}(\tau)\right| \mathrm{d} \tau \leq \frac{C}{t}
$$

Due to the continuity of the function $\zeta$, there exists $\tau_{0} \in[t, t+\alpha]$ such that

$$
\xi(t)=\zeta\left(\tau_{0}\right) \quad \Rightarrow \quad|\zeta(\tau)-\xi(t)| \leq \frac{C}{t}
$$

where $\tau \in[t, t+\alpha]$.
Now, we estimate the value of the function $\xi^{\prime}$.

$$
\begin{aligned}
\xi^{\prime}(t)= & \frac{1}{\alpha}[\zeta(t+\alpha)-\zeta(t)]=\frac{1}{\alpha} \int_{t}^{t+\alpha} \zeta^{\prime}(\tau) \mathrm{d} \tau \\
= & \frac{1}{\alpha} \int_{t}^{t+\alpha} \frac{1}{\tau}\left[(p-1) \zeta(\tau)+s(\tau) \gamma+(p-1) \frac{|\zeta(\tau)|^{q}}{r^{q-1}(\tau)}\right] \mathrm{d} \tau \\
\geq & \frac{1}{t+\alpha}\left[(p-1) \xi(t)+\frac{\gamma}{\alpha} \int_{0}^{\alpha} s(\tau) \mathrm{d} \tau+\frac{p-1}{\alpha} \int_{t}^{t+\alpha} \frac{|\zeta(\tau)|^{q}}{r^{q-1}(\tau)} \mathrm{d} \tau\right] \\
& +\frac{(p-1) \alpha}{t(t+\alpha)} \xi(t) \\
= & \frac{1}{t+\alpha}\left[(p-1) \xi(t)+\frac{A^{p}}{p}+\frac{B^{q}}{q}+\frac{\gamma}{\alpha} \int_{0}^{\alpha} s(\tau) \mathrm{d} \tau-\frac{A^{p}}{p}+\frac{(p-1) \alpha}{t} \xi(t)\right. \\
& \left.+\frac{p-1}{\alpha} \int_{t}^{t+\alpha} \frac{|\zeta(\tau)|^{q}}{r^{q-1}(\tau)} \mathrm{d} \tau-\frac{B^{q}}{q}\right] .
\end{aligned}
$$

Denote

$$
\begin{align*}
X & :=(p-1) \xi(t)+\frac{A^{p}}{p}+\frac{B^{q}}{q} \\
Y & :=\frac{\gamma}{\alpha} \int_{0}^{\alpha} s(\tau) \mathrm{d} \tau-\frac{A^{p}}{p}+\frac{(p-1) \alpha}{t} \xi(t)  \tag{3.6}\\
Z & :=\frac{p-1}{\alpha} \int_{t}^{t+\alpha} \frac{|\zeta(\tau)|^{q}}{r^{q-1}(\tau)} \mathrm{d} \tau-\frac{B^{q}}{q}
\end{align*}
$$

Next, we estimate quantities appearing in (3.6). It follows from Young's inequality, that $\frac{A^{p}}{p}+\frac{B^{q}}{q}-A B \geq 0$, so (using $\xi \leq 0$ )

$$
X=\frac{A^{p}}{p}+\frac{B^{q}}{q}+(p-1) \xi=\frac{A^{p}}{p}+\frac{B^{q}}{q}-(p-1)|\xi|=\frac{A^{p}}{p}+\frac{B^{q}}{q}-A B \geq 0
$$

As for the term $Y$, we denote

$$
K_{\gamma}:=Y=\frac{\gamma}{\alpha} \int_{0}^{\alpha} s(\tau) \mathrm{d} \tau-\frac{A^{p}}{p}+\frac{(p-1) \alpha}{t} \xi(t)
$$

and show, that $K_{\gamma} \geq 0$.

$$
\begin{aligned}
K_{\gamma} & =\frac{\gamma}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau-\frac{(p-1)^{p}}{p}\left(\frac{p}{\alpha} \int_{0}^{\alpha} \frac{1}{r^{q-1}} \mathrm{~d} \tau\right)^{-\frac{p}{q}}+\frac{(p-1) \alpha}{t} \xi \\
& =\frac{\gamma}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau-q^{-p} \frac{\frac{1}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau}{\left(\frac{1}{\alpha} \int_{0}^{\alpha} \frac{1}{r^{q-1}} \mathrm{~d} \tau\right)^{\frac{p}{q}} \frac{1}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau}+\frac{(p-1) \alpha}{t} \frac{1}{\alpha} \int_{t}^{t+\alpha} \zeta \mathrm{d} \tau \\
& \geq \frac{1}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau\left[\gamma-q^{-p}\left(\frac{1}{\alpha} \int_{0}^{\alpha} \frac{1}{r^{q-1}} \mathrm{~d} \tau\right)^{-\frac{p}{q}}\left(\frac{1}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau\right)^{-1}\right]-\frac{p-1}{t} \\
& =\frac{1}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau(\gamma-K)-\frac{p-1}{t}>0
\end{aligned}
$$

for $t \geq T_{1}$, because $\gamma>K$.
Finally, to estimate the last expression in (3.6), let us introduce the function

$$
F(x, y):= \begin{cases}\frac{|x|^{q}-|y|^{q}}{|x|-|y|}, & x \neq y,[x, y] \in M \\ q \Phi^{-1}(|x|), & x=y\end{cases}
$$

where $M:=[-1,0] \times[-1,0]$.

Then, we have

$$
\begin{aligned}
Z & =\frac{p-1}{\alpha} \int_{t}^{t+\alpha} \frac{|\zeta|^{q}}{r^{q-1}} \mathrm{~d} \tau-\frac{B^{q}}{q}=\frac{p-1}{\alpha} \int_{t}^{t+\alpha} \frac{|\zeta|^{q}}{r^{q-1}} \mathrm{~d} \tau-\frac{|\xi|^{q}}{q} \frac{q(p-1)}{\alpha} \int_{t}^{t+\alpha} \frac{1}{r^{q-1}} \mathrm{~d} \tau \\
& =-\frac{p-1}{\alpha} \int_{t}^{t+\alpha} \frac{|\xi|^{q}-|\zeta|^{q}}{r^{q-1}} \mathrm{~d} \tau \geq-\frac{p-1}{\alpha} \int_{t}^{t+\alpha}|\xi-\zeta| \frac{|\xi|^{q}-|\zeta|^{q}}{|\xi|-|\zeta|} \frac{1}{r^{q-1}} \mathrm{~d} \tau \\
& \geq-\frac{(p-1) C D}{\alpha t} \int_{0}^{\alpha} \frac{1}{r^{q-1}} \mathrm{~d} \tau,
\end{aligned}
$$

where we have used (3.5) and $D:=\max _{M} F(\xi, \zeta)<\infty$.
Altogether for $t \geq T:=\max \left\{T_{0}, T_{1}, T_{2}\right\}$, where

$$
T_{2}:=\frac{2 C D(p-1)}{\alpha K_{\gamma}} \int_{0}^{\alpha} \frac{1}{r^{q-1}(\tau)} \mathrm{d} \tau
$$

we obtain

$$
\begin{aligned}
\xi^{\prime}(t) & \geq \frac{1}{t+\alpha}\left[K_{\gamma}-\frac{C D(p-1)}{\alpha t} \int_{0}^{\alpha} \frac{1}{r^{q-1}(\tau)} \mathrm{d} \tau\right] \\
& \geq \frac{1}{t+\alpha}\left(K_{\gamma}-\frac{K_{\gamma}}{2}\right)=\frac{K_{\gamma}}{2(t+\alpha)}
\end{aligned}
$$

which means, that

$$
\xi(t) \geq \xi(T)+\frac{K_{\gamma}}{2} \log \frac{t+\alpha}{T+\alpha} \rightarrow \infty \quad \text { as } \quad t \rightarrow \infty
$$

which is a contradiction. Thus, equation (3.1) is oscillatory for $\gamma>K$.
In the next part of the proof, we show, that (3.1) is nonoscillatory for $\gamma<K$. Denote $\mu:=\frac{s_{\text {max }}}{r_{\text {min }}}$. Equation (3.3) is now a majorant equation of equation (3.1). We show that the majorant equation (3.3) is nonoscillatory, which implies, that equation (3.1) is also nonoscillatory.

Denote

$$
\xi_{0}:=-\left[\frac{p}{\alpha(p-1)} \int_{0}^{\alpha} \frac{1}{r^{q-1}(\tau)} \mathrm{d} \tau\right]^{1-p}
$$

We will show that there exists $T$ such that $\xi(t)$ defined by (3.4) in the previous part of the proof satisfies $\xi(t) \leq \xi_{0},(t \geq T)$. By contradiction, assume that

$$
t_{0}:=\sup \left\{t \geq T, \xi(\tau) \leq \xi_{0}, \tau \in[T, t]\right\}<\infty .
$$

Then $\xi^{\prime}\left(t_{0}\right) \geq 0$ and $\xi\left(t_{0}\right)=\xi_{0}$. We estimate the value of $\xi^{\prime}\left(t_{0}\right)$. We obtain

$$
\begin{aligned}
\xi^{\prime}\left(t_{0}\right)= & \frac{1}{\alpha} \int_{t_{0}}^{t_{0}+\alpha} \frac{1}{\tau}\left[(p-1) \zeta(\tau)+\gamma s(\tau)+(p-1) \frac{|\zeta(\tau)|^{q}}{r^{q-1}(\tau)}\right] \mathrm{d} \tau \\
\leq & \frac{1}{t_{0}}\left[(p-1) \xi\left(t_{0}\right)+\frac{\gamma}{\alpha} \int_{0}^{\alpha} s(\tau) \mathrm{d} \tau+\frac{p-1}{\alpha} \int_{t_{0}}^{t_{0}+\alpha} \frac{|\zeta(\tau)|^{q}}{r^{q-1}(\tau)} \mathrm{d} \tau\right] \\
& -\frac{(p-1) \alpha}{t_{0}\left(t_{0}+\alpha\right)} \xi\left(t_{0}\right) \\
= & \frac{1}{t_{0}}\left[(p-1) \xi\left(t_{0}\right)+\frac{A^{p}}{p}+\frac{B^{q}}{q}+\frac{\gamma}{\alpha} \int_{0}^{\alpha} s(\tau) \mathrm{d} \tau-\frac{A^{p}}{p}-\frac{(p-1) \alpha}{t_{0}+\alpha} \xi\left(t_{0}\right)\right. \\
& \left.+\frac{p-1}{\alpha} \int_{t_{0}}^{t_{0}+\alpha} \frac{|\zeta(\tau)|^{q}}{r^{q-1}(\tau)} \mathrm{d} \tau-\frac{B^{q}}{q}\right]
\end{aligned}
$$

Again, we denote

$$
\begin{align*}
X & :=(p-1) \xi\left(t_{0}\right)+\frac{A^{p}}{p}+\frac{B^{q}}{q} \\
Y & :=\frac{\gamma}{\alpha} \int_{0}^{\alpha} s(\tau) \mathrm{d} \tau-\frac{A^{p}}{p}-\frac{(p-1) \alpha}{t+\alpha} \xi\left(t_{0}\right),  \tag{3.7}\\
Z & :=\frac{p-1}{\alpha} \int_{t_{0}}^{t_{0}+\alpha} \frac{|\zeta(\tau)|^{q}}{r^{q-1}(\tau)} \mathrm{d} \tau-\frac{B^{q}}{q}
\end{align*}
$$

with $A, B$ given by

$$
A:=(p-1)\left(\frac{p}{\alpha} \int_{0}^{\alpha} \frac{1}{r^{q-1}(\tau)} \mathrm{d} \tau\right)^{-\frac{1}{q}}, \quad B:=\left|\xi\left(t_{0}\right)\right|\left(\frac{p}{\alpha} \int_{0}^{\alpha} \frac{1}{r^{q-1}(\tau)} \mathrm{d} \tau\right)^{\frac{1}{q}}
$$

and we estimate quantities appearing in 3.7.
Since $A^{p}=B^{q}$, we have

$$
\frac{A^{p}}{p}+\frac{B^{q}}{q}=A^{p}\left(\frac{1}{p}+\frac{1}{q}\right)=A^{1+\frac{p}{q}}=A\left(B^{q}\right)^{\frac{1}{q}}=A B=-(p-1) \xi
$$

which means, that $X=0$ in 3.7.
Next, we denote

$$
-K_{\gamma}:=Y=\frac{\gamma}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau-\frac{A^{p}}{p}-\frac{(p-1) \alpha}{t_{0}+\alpha} \xi
$$

Then

$$
\begin{aligned}
-K_{\gamma} & =\frac{\gamma}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau-\frac{(p-1)^{p}}{p}\left(\frac{p}{\alpha} \int_{0}^{\alpha} \frac{1}{r^{q-1}} \mathrm{~d} \tau\right)^{-\frac{p}{q}}-\frac{(p-1) \alpha}{t_{0}+\alpha} \xi \\
& \leq \frac{1}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau\left[\gamma-q^{-p}\left(\frac{1}{\alpha} \int_{0}^{\alpha} \frac{1}{r^{q-1}} \mathrm{~d} \tau\right)^{-\frac{p}{q}}\left(\frac{1}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau\right)^{-1}\right]+\frac{p-1}{t_{0}+\alpha} \\
& =\frac{1}{\alpha} \int_{0}^{\alpha} s \mathrm{~d} \tau(\gamma-K)+\frac{p-1}{t_{0}+\alpha}<0
\end{aligned}
$$

because $\gamma<K$, i.e., $K_{\gamma}>0$.
Finally, similarly as in the previous computation, we have

$$
\begin{aligned}
Z & =\frac{p-1}{\alpha} \int_{t_{0}}^{t_{0}+\alpha} \frac{|\zeta|^{q}}{r^{q-1}} \mathrm{~d} \tau-\frac{B^{q}}{q} \\
& =\frac{p-1}{\alpha} \int_{t_{0}}^{t_{0}+\alpha} \frac{|\zeta|^{q}}{r^{q-1}} \mathrm{~d} \tau-\frac{|\xi|^{q}}{q} \frac{q(p-1)}{\alpha} \int_{t_{0}}^{t_{0}+\alpha} \frac{1}{r^{q-1}} \mathrm{~d} \tau \\
& =\frac{p-1}{\alpha} \int_{t_{0}}^{t_{0}+\alpha} \frac{|\zeta|^{q}-|\xi|^{q}}{r^{q-1}} \mathrm{~d} \tau \leq \frac{C D(p-1)}{\alpha t_{0}} \int_{0}^{\alpha} \frac{1}{r^{q-1}} \mathrm{~d} \tau .
\end{aligned}
$$

Altogether for $t_{0} \geq T:=\max \left\{T_{0}, T_{1}, T_{2}\right\}$, where $T_{0}, T_{1}, T_{2}$ are defined earlier, we obtain

$$
\begin{aligned}
\xi^{\prime}\left(t_{0}\right) & \leq \frac{1}{t_{0}}\left[-K_{\gamma}+\frac{C D(p-1)}{\alpha t_{0}} \int_{0}^{\alpha} \frac{1}{r^{q-1}(\tau)} \mathrm{d} \tau\right] \\
& \leq \frac{1}{t_{0}}\left(-K_{\gamma}+\frac{K_{\gamma}}{2}\right)=-\frac{K_{\gamma}}{2 t_{0}}<0
\end{aligned}
$$

which is a contradiction.

Remark 1. It is still an open problem to decide whether equation (3.1) is oscillatory or not in the case, $\gamma=K$, with $K$ given by (3.2).
Remark 2. For $r(t) \equiv 1 \equiv s(t)$, equation (3.1) reduces to Euler equation 1.4) and our oscillation constant $K$ defined by (3.2) reduces to the well known constant $\gamma_{0}=\left(\frac{p-1}{p}\right)^{p}$.

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