# ON THE EXISTENCE OF UNIQUE COMMON FIXED POINTS FOR CERTAIN CLASSES OF WEAKLY COMPATIBLE MAPS IN NORMED LINEAR SPACE 

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#### Abstract

In this work, we obtain some common fixed points and coincidence points results for weakly compatible selfmaps $A, S$ and $B, T$ of a normed linear space, satisfying certain contractive conditions of integral type. Our results generalize those of Pathak et al [16], Jungck [6] and others.


## 1. Introduction and Preliminaries

In 1976, Jungck [6] used commuting mapping concept as a tool to generalize the Banach fixed point theorem. This was followed by variety of extensions, generalizations and their applications, giving rise to different notions such as weak commutativity (S. Sessa [17]), compatibility, compatibility of types (A), (B), (C) and (P) (see [1], [3], [14], [15], [16], etc). The concept of R -weakly commuting pairs, i.e., the pair $(f, g)$ of maps satisfying $d(f g x, g f x) \leq R d(f x, g x), x \in X, R>0$, where $X$ is a metric space, was introduced by Pant [14]. In 1998, Jungck and Rhoades [9] defined two maps $f$ and $g$ of a metric space to be weakly compatible if and only if they commute at their coincidence points. Since then the study of common fixed points for contractive-type maps has been centered on this notion of weak compatibility. For more on the relationship between compatibility and its weaker forms, see Djoudi and Aliouche [3], P. P. Murthy [12].

Recently, Pathak et al. [16], in 2006, obtained some existence and uniqueness results for a class of weakly compatible, parametrically $\varphi(\epsilon, \delta ; a)$-contraction mappings in metric space.

Throughout this paper, we shall always refer to $\mathbf{R}_{+}$as the set of nonnegative real numbers.

[^0]Definition 1.1 (Pathak et al. [16]). Let $A, B, S, T$ be selfmappings of a metric space $(X, d)$ such that $A X \subseteq T X$ and $B X \subseteq S X$. Define a function $\delta:(0, \infty) \rightarrow(0, \infty)$ such that $\delta(\epsilon)>\epsilon$ for all $\epsilon>0$. The pair $(A, B)$ is said to be parametrically $\varphi(\epsilon, \delta ; a)$-contraction with respect to the pair $(S, T)$ if for some $a \in\left(\frac{1}{2}, 1\right]$ and for all $x, y \in X$, the following are satisfied:

$$
\begin{equation*}
a d(A x, B y)+(1-a) d(B y, T y) \leq \varphi(a d(S x, T y)+(1-a) d(A x, S x)) \tag{1.1}
\end{equation*}
$$

where $\varphi: \mathbf{R}_{+} \rightarrow \mathbf{R}_{+}$is such that
(a) $\varphi$ is continuous;
(b) $\varphi(t)<t$ for all $t>0$;
(c) $\epsilon \leq d(B y, T y)<\delta(\epsilon)$ implies $\varphi(d(A x, S x))<\epsilon$;
(d) $\varphi(0)=0$.

Definition 1.2 (Jungck and Rhoades [9]). A pair of mappings $(A, S)$ is called weakly compatible if they commute at their coincidence points. (A coincidence point of $A$ and $S$ is any point $u$ satisfying $A u=S u$.)

The following result was obtained by Pathak et al. [16].
Theorem 1.1 (Pathak et al. [16]). Let $S$ and $T$ be selfmaps of a metric space $(X, d)$ and the pair $(A, B)$ is parametrically $\varphi(\epsilon, \delta ; a)$-contraction with respect to the mappings $(S, T)$. Let $T X$ be complete, then there exist $u, v, w \in X$ such that $A u=S u=w=B v=T v$.

Furthermore, if the pair $(A, S)$ and $(B, T)$ are weakly compatible, then $w$ is the unique common fixed point of the mappings $A, B, S$ and $T$.

In proving Theorem 1.1, the following iteration procedure was used.
Definition 1.3. Let $A, B, S$ and $T$ be selfmaps of a metric space $X$ satisfying

$$
\begin{equation*}
A X \subseteq T X \text { and } B X \subseteq S X \tag{1.2}
\end{equation*}
$$

Then for any $x_{0} \in X$ there exists a point $x_{1} \in X$ such that $y_{0}=A x_{0}=T x_{1}$ and for this point $x_{1}$, we can choose a point $x_{2} \in X$ such that $y_{1}=B x_{1}=S x_{2}$ and so on. In general, we can define a sequence $\left\{y_{n}\right\}$ in $X$ such that

$$
\begin{equation*}
y_{2 n}=A x_{2 n}=T x_{2 n+1} \text { and } y_{2 n+1}=B x_{2 n+1}=S x_{2 n+2}, \quad n=0,1,2, \ldots \tag{1.3}
\end{equation*}
$$

This is called $(S, T)$-iteration on $X$.
Remark 1.1. Observe that if we choose $a=1, A=B$ and $S=T=I$, where $I$ is the identity mapping, then $A$ reduces to a $\varphi$-contraction and (1.3) reduces to the Picard iteration.

If, in addition, we set $\varphi(t)=t, A$ is a nonexpansive mapping and (1.3) becomes the Krasnoselskij iteration, see [10].

This sequence has been proved to converge to the unique common fixed point of $A, B, S$ and $T$ by several authors under various conditions (See Jungck [6], Chugh and Kumar [2], Pathak et al. [15, 16], Babu and Prasad [1], Djoudi and Aliouche [3]).

In this paper we do away with condition (c) of Definition 1.1 and employ the iteration process (1.3).

## 2. Main Results

We now present our main results in this paper.
Theorem 2.1. Let $A, B, S$ and $T$ be selfmaps of a normed linear space $X$ with $A X \subseteq T X$ and $B X \subseteq S X$ satisfying the following condition.
$h\|A x-B y\|^{p}+(1-h)\|B y-T y\|^{p} \leq \varphi\left(h\|S x-T y\|^{p}+(1-h)\|A x-S x\|^{p}\right)$,
where, $p>0, h \in\left(\frac{1}{2}, 1\right]$ and $\varphi: \mathbf{R}_{+} \rightarrow \mathbf{R}_{+}$is such that:
(a) $\varphi$ is continuous;
(b) $\varphi(t)<t$ for all $t>0$;

Let $S X$ or $T X$ be a complete subspace of $X$ and the pairs $(A, S)$ and $(B, T)$ be weakly compatible, then $A, B, S$ and $T$ have a unique common fixed point.
We shall require the following Lemmas in the proof of Theorem 2.1. Our method of proof is almost the same as that of Pathak et al. [10].

Lemma 2.1. Let the mappings $A, B, S$ and $T$ be as in Theorem 2.1. Then the $(S, T)$-iteration defined on $X$ is a Cauchy sequence.

Proof. Since $A X \subseteq T X$ and $B X \subseteq S X$, we can define the $(S, T)$-iteration on $x_{0} \in X$ as in (1.3). Therefore, choosing $k=2 n, q=2 m-1, k$ and $q$ are of different parities, and we have

$$
\begin{aligned}
& h\left\|A x_{2 n}-B x_{2 m-1}\right\|^{p}+(1-h)\left\|B x_{2 m-1}-T x_{2 m-1}\right\|^{p} \\
& =h\left\|y_{2 n+1}-y_{2 m}\right\|^{p}+(1-h)\left\|y_{2 m}-y_{2 m-1}\right\|^{p} \\
& \quad=h\left\|y_{k+1}-y_{q+1}\right\|^{p}+(1-h)\left\|y_{q+1}-y_{q}\right\|^{p}
\end{aligned}
$$

and

$$
\begin{aligned}
& h\left\|S x_{2 n}-T x_{2 m-1}\right\|^{p}+(1-h)\left\|S x_{2 n}-A x_{2 n}\right\|^{p} \\
& =h\left\|y_{2 n}-y_{2 m-1}\right\|^{p}+(1-h)\left\|y_{2 n}-y_{2 n+1}\right\|^{p} \\
& \quad=h\left\|y_{k}-y_{q}\right\|^{p}+(1-h)\left\|y_{k}-y_{q+1}\right\|^{p}
\end{aligned}
$$

Hence, from (2.1),

$$
\begin{align*}
& h\left\|y_{k+1}-y_{q+1}\right\|^{p}+(1-h)\left\|y_{q+1}-y_{q}\right\|^{p}  \tag{2.2}\\
& \leq \varphi\left(h\left\|y_{k}-y_{q}\right\|^{p}+(1-h)\left\|y_{k}-y_{q+1}\right\|^{p}\right)
\end{align*}
$$

Now, let $x_{0}$ be an arbitrary point in $X$. Then from (2.2) and (2.1)(b), choosing $k=2 n, q=2 m-1$,

$$
\begin{aligned}
h\left\|y_{2 n+1}-y_{2 n}\right\|^{p} & +(1-h)\left\|y_{2 n}-y_{2 n-1}\right\|^{p} \\
& \leq \varphi\left(h\left\|y_{2 n}-y_{2 n-1}\right\|^{p}+(1-h)\left\|y_{2 n}-y_{2 n+1}\right\|^{p}\right)
\end{aligned}
$$

$$
<h\left\|y_{2 n}-y_{2 m-1}\right\|^{p}+(1-h)\left\|y_{2 n}-y_{2 n+1}\right\|^{p}
$$

That is,

$$
(2 h-1)\left\|y_{2 n+1}-y_{2 n}\right\|^{p}<(2 h-1)\left\|y_{2 n}-y_{2 n-1}\right\|^{p}
$$

Since $h \in\left(\frac{1}{2}, 1\right]$, we have

$$
\left\|y_{2 n+1}-y_{2 n}\right\|^{p}<\left\|y_{2 n}-y_{2 n-1}\right\|^{p} .
$$

Similarly for $p=2 n+1$ and $q=2 n$, we have

$$
\left\|y_{2 n+2}-y_{2 n+1}\right\|^{p}<\left\|y_{2 n+1}-y_{2 n}\right\|^{p} .
$$

Since $p>0$, then $\left\{\left\|y_{n}-y_{n+1}\right\|\right\}_{n=0}^{\infty}$ is a decreasing sequence which converges to its greatest lower bound, say, $t \geq 0$.

Suppose $t>0$, from (2.1), for $x=x_{2 n}, y=x_{2 n-1}$, we obtain

$$
\begin{aligned}
h\left\|A x_{2 n}-B x_{2 n-1}\right\|^{p}+ & (1-h)\left\|B x_{2 n-1}-T x_{2 n-1}\right\|^{p} \\
& \leq \varphi\left(h\left\|S x_{2 n}-T x_{2 n-1}\right\|^{p}+(1-h)\left\|A x_{2 n}-S x_{2 n}\right\|^{p}\right)
\end{aligned}
$$

That is,

$$
\begin{aligned}
h\left\|y_{2 n}-y_{2 n-1}\right\|^{p}+(1-h) & \left\|y_{2 n-1}-y_{2 n-2}\right\|^{p} \\
& \leq \varphi\left(h\left\|y_{2 n}-y_{2 n-2}\right\|^{p}+(1-h)\left\|y_{2 n}-y_{2 n-1}\right\|^{p}\right)
\end{aligned}
$$

Letting $n \rightarrow \infty$, we have $t^{p} \leq \varphi\left(t^{p}\right)<t^{p}$. This is a contradiction. Therefore $t=0$. Hence,

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|y_{n}-y_{n+1}\right\|=0 \tag{2.3}
\end{equation*}
$$

We now show that the sequence $\left\{y_{n}\right\}$ defined by (1.3) is Cauchy. By virtue of (2.3) it suffices to show that the subsequence $\left\{y_{2 n}\right\}$ of $\left\{y_{n}\right\}$ is Cauchy. Suppose not. Then there exist $\epsilon>0$ such that $\left\|y_{2 n_{i}}-y_{2 m_{i}}\right\| \rightarrow \epsilon$, as $i \rightarrow \infty$. Also, as in Djoudi and Nisse [4],

$$
\begin{equation*}
\left\|y_{2 n_{i}+1}-y_{2 m_{i}}\right\|,\left\|y_{2 n_{i}}-y_{2 m_{i}-1}\right\| \rightarrow \epsilon, \text { as } i \rightarrow \infty . \tag{2.4}
\end{equation*}
$$

Therefore,

$$
\begin{aligned}
& h\left\|A x_{2 n_{i}}-B x_{2 m_{i}-1}\right\|^{p}+(1-h)\left\|B x_{2 m_{i}-1}-T x_{2 m_{i}-1}\right\|^{p} \\
& \leq \varphi\left(h\left\|S x_{2 n_{i}}-T x_{2 m_{i}-1}\right\|^{p}+(1-h)\left\|A x_{2 n_{i}}-S x_{2 n_{i}}\right\|^{p}\right)
\end{aligned}
$$

so that

$$
\begin{aligned}
& h\left\|y_{2 n_{i}+1}-y_{2 m_{i}}\right\|^{p}+(1-h)\left\|y_{2 m_{i}}-y_{2 m_{i}-1}\right\|^{p} \\
& \leq \varphi\left(h\left\|y_{2 n_{i}}-y_{2 m_{i}-1}\right\|^{p}+(1-h)\left\|y_{2 n_{i}+1}-y_{2 n_{i}}\right\|^{p}\right) .
\end{aligned}
$$

Letting $i \rightarrow \infty$, by (2.3) and (2.4),

$$
h \epsilon^{p} \leq \varphi\left(h \epsilon^{p}\right)<h \epsilon^{p},
$$

which is also a contradiction. Therefore, $\left\{y_{n}\right\}$ is Cauchy.

Lemma 2.2. Let $\varphi: \mathbf{R}_{+} \longrightarrow \mathbf{R}_{+}$be a continuous function satisfying $\varphi(t)<t$ for all $t>0$. Then, $\varphi(0)=0$. Hence, $\varphi(t) \leq t$ for all $t \geq 0$.

We are now in a convenient position to prove Theorem 2.1.
Proof of Theorem 2.1. Since the subsequence $\left\{y_{2 n}\right\}$ of $\left\{y_{n}\right\}$ which is in $S X$ is Cauchy, and $S X$ is complete, then $\left\{y_{2 n}\right\}$ converges to a point $x^{*}=S u \in S X$ for some $u \in X$.

If we substitute $x=u, y=x_{2 n-1}$ into (2.1),

$$
\begin{aligned}
h\left\|A u-B x_{2 n-1}\right\|^{p}+(1-h) & \left\|B x_{2 n-1}-T x_{2 n-1}\right\|^{p} \\
& \leq \varphi\left(h\left\|S u-T x_{2 n-1}\right\|^{p}+(1-h)\|A u-S u\|^{p}\right)
\end{aligned}
$$

or,

$$
\begin{aligned}
h\left\|A u-y_{2 n}\right\|^{p}+(1-h) \| y_{2 n}- & y_{2 n-1} \|^{p} \\
& \leq \varphi\left(h\left\|x^{*}-y_{2 n-1}\right\|^{p}+(1-h)\left\|A u-x^{*}\right\|^{p}\right)
\end{aligned}
$$

Letting $n \rightarrow \infty$,

$$
h\left\|A u-x^{*}\right\|^{p}+(1-h)\left\|x^{*}-x^{*}\right\|^{p} \leq \varphi\left(h\left\|x^{*}-x^{*}\right\|^{p}+(1-h)\left\|A u-x^{*}\right\|^{p}\right)
$$

or,

$$
h\left\|A u-x^{*}\right\|^{p} \leq \varphi\left((1-h)\left\|A u-x^{*}\right\|^{p}\right) \leq(1-h)\left\|A u-x^{*}\right\|^{p},
$$

by Lemma 2.2. This yields

$$
(2 h-1)\left\|A u-x^{*}\right\|^{p} \leq 0 .
$$

But since $h \in(1 / 2,1],\left\|A u-x^{*}\right\|^{p}=0$. Hence, $A u=x^{*}=S u$.
Since $A X \subseteq T X$, there exists some $v \in X$ such that $A u=T v$, so that $x^{*}=S u=A u=T v$. If we now put $x=u, y=v$ into (2.1), we obtain
$h\|A u-B v\|^{p}+(1-h)\|B v-T v\|^{p} \leq \varphi\left(h\|S u-T v\|^{p}+(1-h)\|A u-S u\|^{p}\right)$, yielding

$$
h\left\|x^{*}-B v\right\|^{p}+(1-h)\left\|B v-x^{*}\right\|^{p} \leq \varphi\left(h\left\|x^{*}-x^{*}\right\|^{p}+(1-h)\left\|x^{*}-x^{*}\right\|^{p}\right) .
$$

That is,

$$
\left\|x^{*}-B v\right\|^{p}=0 .
$$

Hence,

$$
\begin{equation*}
S u=A u=x^{*}=B v=T v . \tag{2.5}
\end{equation*}
$$

Since the pair $(A, S)$ is weakly compatible, that is, they commute at their coincidence point $u$, then

$$
\begin{equation*}
A A u=A S u=S A u . \tag{2.6}
\end{equation*}
$$

Now, substituting $x=A u, y=v$ into (2.1), by (2.5) and (2.6) we obtain

$$
h\left\|A A u-x^{*}\right\|^{p} \leq \varphi\left(h\left\|A A u-x^{*}\right\|^{p}\right) \leq h\left\|A A u-x^{*}\right\|^{p}
$$

Thus, $A A u=x^{*}=A u$, that is, $A u=u$. This, together with the first equality in (2.6), yields $S u=u$. Therefore, $u \in X$ is a common fixed point of $A$ and $S$.

Considering that $B$ and $T$ are also weakly compatible, by a similar process it is easy to see that $v \in X$ is a common fixed point of $B$ and $T$, using (2.1) and (2.5).

It is obvious that $u=v$. Indeed, putting $x=u, y=v$ back in (2.1), we see that $h\|u-v\|^{p} \leq \varphi\left(h\|u-v\|^{p}\right)$, that is $\|u-v\|=0$. Consequently, $u=v=x^{*}$ is a common fixed point of $A, B, S$ and $T$.

Finally for uniqueness, let if possible, $x^{\prime}$ be another common fixed point of $A, B, S$ and $T$ such that $x^{*} \neq x^{\prime}$. Then $\left\|x^{*}-x^{\prime}\right\|>0$, and

$$
\begin{aligned}
\left\|x^{*}-x^{\prime}\right\|^{p} & =h\left\|x^{*}-x^{\prime}\right\|^{p}+(1-h)\left\|x^{*}-x^{\prime}\right\|^{p} \\
& =h\left\|A x^{*}-B x^{\prime}\right\|^{p}+(1-h)\left\|B x^{*}-T x^{\prime}\right\|^{p} \\
& \leq \varphi\left(h\left\|S x^{*}-T x^{\prime}\right\|^{p}+(1-h)\left\|A x^{*}-S x^{\prime}\right\|^{p}\right) \\
& =\varphi\left(h\left\|x^{*}-x^{\prime}\right\|^{p}+(1-h)\left\|x^{*}-x^{\prime}\right\|^{p}\right) \\
& =\varphi\left(\left\|x^{*}-x^{\prime}\right\|^{p}\right) \\
& <\left\|x^{*}-x^{\prime}\right\|^{p} .
\end{aligned}
$$

This is a contradiction. Hence, $x^{*}$ is the unique common fixed point of $A, B, S$ and $T$. This completes the proof.

Theorem 2.1. is a special case of Theorem 2.2. below. For the latter reduces to the former when $\psi(t)=1$.
Theorem 2.2. Let $A, B, S$ and $T$ be selfmaps of a normed linear space $X$ such that

$$
A X \subseteq T X, \quad B X \subseteq S X
$$

and

$$
\begin{align*}
& h\left(\int_{0}^{\|A x-B y\|} \psi(t) d t\right)^{p}+(1-h)\left(\int_{0}^{\|B y-T y\|} \psi(t) d t\right)^{p}  \tag{2.7}\\
& \quad \leq \varphi\left[h\left(\int_{0}^{\|S x-T y\|} \psi(t) d t\right)^{p}+(1-h)\left(\int_{0}^{\|A x-S x\|} \psi(t) d t\right)^{p}\right]
\end{align*}
$$

where $p>0, h \in\left(\frac{1}{2}, 1\right], \varphi$ is as in Theorem 2.1.1 and $\psi: \mathbf{R}_{+} \rightarrow \mathbf{R}_{+}$is a Lebesgue integrable mapping which is summable nonnegative and such that

$$
\begin{equation*}
\int_{0}^{\epsilon} \psi(t) d t>0 \text { for each } \epsilon>0 \tag{2.8}
\end{equation*}
$$

Suppose that one of $S X$ and $T X$ is complete and the pairs $(A, S)$ and $(B, T)$ are weakly compatible. Then $A, B, S$ and $T$ have a unique common fixed point in $X$.

We first state the following useful lemma before proving Theorem 2.2.
Lemma 2.3. Let $A, B, S$ and $T$ be selfmaps of a normed linear space $X$ satisfying (2.7) for all $x, y$ in $X$, where $0<h \leq 1, p \geq 1$ and $\psi$ satisfies (2.8). Then, the sequence $\left\{y_{n}\right\}$ defined by (1.3) is Cauchy in $X$.

Proof of Theorem 2.2. By Lemma 2.3. the subsequence

$$
\left\{y_{2 n-1}\right\}=\left\{T x_{2 n-1}\right\} \subseteq T X
$$

is a Cauchy sequence. Since $T X$ is complete, it converges to a point $z=T u$ for some $u \in X$. Hence, subsequences $\left\{A x_{2 n-2}\right\}$, $\left\{B x_{2 n-1}\right\},\left\{S x_{2 n}\right\}$ also converge to $z$.

If $B u \neq z$, using (2.7), we get

$$
\begin{aligned}
& h\left(\int_{0}^{\left\|A x_{2 n}-B u\right\|} \psi(t) d t\right)^{p}+(1-h)\left(\int_{0}^{\|B u-T u\|} \psi(t) d t\right)^{p} \\
& \quad \leq \varphi\left[h\left(\int_{0}^{\left\|S x_{2 n}-T u\right\|} \psi(t) d t\right)^{p}+(1-h)\left(\int_{0}^{\left\|A x_{2 n}-S x_{2 n}\right\|} \psi(t) d t\right)^{p}\right]
\end{aligned}
$$

Letting $n \rightarrow \infty$, we have

$$
\left(\int_{0}^{\|z-B u\|} \psi(t) d t\right)^{p} \leq \varphi(0)=0
$$

which contradicts (2.8).
Therefore

$$
\int_{0}^{\|z-B u\|} \psi(t) d t=0
$$

and (2.8) implies that $z=B u=T u$. Since $B X \subseteq S X$, there exists $v \in X$ such that $z=B u=S v$. If $z \neq A v$, using (2.7) we have

$$
\begin{aligned}
& h\left(\int_{0}^{\|A v-B u\|} \psi(t) d t\right)^{p}+(1-h)\left(\int_{0}^{\|B u-T u\|} \psi(t) d t\right)^{p} \\
& \quad \leq \varphi\left[h\left(\int_{0}^{\|S v-T u\|} \psi(t) d t\right)^{p}+(1-h)\left(\int_{0}^{\|A v-S v\|} \psi(t) d t\right)^{p}\right]
\end{aligned}
$$

that is,

$$
\begin{aligned}
& h\left(\int_{0}^{\|A v-z\|} \psi(t) d t\right)^{p} \leq \varphi\left[(1-h)\left(\int_{0}^{\|A v-z\|} \psi(t) d t\right)^{p}\right] \\
& \leq(1-h)\left(\int_{0}^{\|A v-z\|} \psi(t) d t\right)^{p}
\end{aligned}
$$

which implies that

$$
(2 h-1)\left(\int_{0}^{\|A v-z\|} \psi(t) d t\right)^{p}<0
$$

This is also a contradiction. Therefore, $T u=B u=z=A v=S v$.

Since the pair $(B, T)$ is weakly compatible, we have $B z=B T u=T B u=$ $T z$, and putting $x=v, y=z$ into (2.7), we obtain

$$
h\left(\int_{0}^{\|z-B z\|} \psi(t) d t\right)^{p} \leq \varphi\left(h\left(\int_{0}^{\|z-B z\|} \psi(t) d t\right)^{p}\right)
$$

yielding $z=B z=T z$.
Similarly, we can show that $z=A z=S z$ from the weak compatibility of $(A, S)$ and (2.7).

Hence, $z$ is a common fixed point of $A, B, S$ and $T$.
The uniqueness of $z$ follows from (2.7).
Corollary 2.1. Let $A$ and $S$ be selfmaps of a normed linear space $X$ satisfying $A X \subseteq S X$ and

$$
\begin{aligned}
& h\left(\int_{0}^{\|A x-A y\|} \psi(t) d t\right)^{p}+(1-h)\left(\int_{0}^{\|A y-S y\|} \psi(t) d t\right)^{p} \\
& \quad \leq \varphi\left[h\left(\int_{0}^{\|S x-S y\|} \psi(t) d t\right)^{p}+(1-h)\left(\int_{0}^{\|A x-S x\|} \psi(t) d t\right)^{p}\right]
\end{aligned}
$$

for all $x, y$ in $X, 0<h \leq 1, p \geq 1$ and $\psi$ satisfies (2.8). Suppose $S X$ is complete and $(A, S)$ is weakly compatible. Then, $A$ and $S$ have a unique common fixed point in $X$.

Proof. Put $B=A$ and $T=S$ in Theorem 2.2.

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