

## SOLUTION OF STEFAN PROBLEMS BY FULLY DISCRETE LINEAR SCHEMES

A. HANDLOVIČOVÁ

ABSTRACT. This paper deals with a class of nonlinear parabolic problems with nonlinear boundary conditions. Stefan problems and porous medium equations are included. The enthalpy formulation and the variational technique are used. Convergence of a fully discrete linear approximation scheme is studied.

### 1. INTRODUCTION

In our paper we shall consider the convergence of a fully discrete linear approximation scheme. This scheme can be used in solving nonlinear Stefan-like parabolic problems with nonlinear boundary conditions:

$$\begin{aligned}\partial_t u - \nabla \cdot (k(\beta(u))\nabla\beta(u)) &= f(t, x, \beta(u)) && \text{on } Q := (0, T) \times \Omega, \\ u(0, x) &= u_p(x) && \text{on } \Omega, \\ -\nu \cdot k(\beta(u))\nabla\beta(u) &= g(t, x, \beta(u)) && \text{for } x \in \Gamma, t \in (0, T),\end{aligned}$$

where  $\Omega \subset \mathbb{R}^d$  is a polygonal convex domain with the boundary  $\Gamma$ ,  $T < \infty$ ,  $\nu$  is the outward normal to  $\Gamma$ , the functions  $f, g, \beta, k$  are Lipschitz continuous,  $\beta: \mathbb{R} \rightarrow \mathbb{R}$  is nondecreasing and  $k(s)$  is a positive definite symmetric  $d \times d$ -matrix for any  $s \in \mathbb{R}$ .

The use of linear approximation schemes for solving these problems from both the theoretical and numerical point of view has been extensively studied. A linear approximation scheme based on the so-called nonlinear Chernoff formula with constant relaxation parameter  $\mu$  was studied in [1], [12], [14], [8].

Another linear approximation scheme was investigated in [5], [6], [7], [3]. There the authors used an approximation scheme of the type

$$\begin{aligned}\mu_i(\theta_i - \beta(u_{i-1})) - \tau\Delta\theta_i &= \tau f(t_i, x, \beta(u_{i-1})) && \text{in } \Omega, \\ -\partial_\nu\theta_i &= g(t_i, x, \theta_{i-1}) \text{ or } u_i = 0 && \text{on } \Gamma, \\ |\beta(u_{i-1} + \mu_i(\theta_i - \beta(u_{i-1}))) - \beta(u_{i-1})| &\leq \alpha|\theta_i - \beta(u_{i-1})| + o\left(\frac{1}{\sqrt{n}}\right), \\ u_i &:= u_{i-1} + \mu_i(\theta_i - \beta(u_{i-1})), && i = 1, \dots, n\end{aligned}$$

---

Received March 20, 1998.

1980 *Mathematics Subject Classification* (1991 *Revision*). Primary 65M15, 35K55.

where  $\theta_i$  is an approximation of the function  $\beta(u)$  at time  $t_i$ ,  $\mu_i \in L_\infty(\Omega)$ ,  $0 < \delta \leq \mu_i \leq K$  and where  $K^{-1}$ ,  $1 - 2\alpha$  and  $\delta$  are sufficiently small constants. This scheme has the disadvantage of not being explicit with respect to  $\theta_i$  and  $\mu_i$  and therefore some iterative method for determining them must be used. In the papers mentioned above, the convergence and energy error estimates for this semi-discretization scheme were established for both strictly monotone ([5]) and nondecreasing ([7]) function  $\beta$ . The idea of our linear approximation scheme is similar but we introduce the following two novelties:

- We consider a fully discrete scheme, that means we discretize not only in time, but we also use the finite element method for space discretization.
- We linearize not only the function  $\beta$  but also nonlinearities in the right hand side of the equation and the nonlinearity in the boundary condition.

In Subsection 4, we prove the convergence of an iterative method for finding the functions  $\mu_i, \theta_i$  at each time step  $t_i$ . In Subsections 5 and 6, the convergence of our linear approximation scheme is proved.

Some of our proofs are only sketched; the details can be found in [4].

## 2. BASIC NOTATIONS, ASSUMPTIONS AND BASIC RESULTS OF THE FINITE ELEMENT METHOD

We denote

$$(H_\Omega) \quad \begin{cases} \Omega \subset \mathbb{R}^d \ (d \geq 1) \text{ is polygonal convex domain with boundary } \Gamma, \\ Q := I \times \Omega, \text{ where } I = (0, T), \ 0 < T < \infty \text{ and } T \text{ is fixed.} \end{cases}$$

Further we shall use function spaces in [10]:  $L_2(\Omega)$  with norm  $\|\cdot\|$ ,  $L_2(I, L_2(\Omega)) = L_2(Q)$  with norm  $\|\cdot\|_{L_2(I, L_2(\Omega))}$  and  $H^1(\Omega) := W^{1,2}(\Omega)$  with norm  $\|\cdot\|_H$ . We denote the dual space to  $H^1(\Omega)$  by  $H^*(\Omega)$ . Finally, we shall use function space  $L_2(\Gamma)$  with norm  $\|\cdot\|_\Gamma$  and inner product  $\langle \cdot, \cdot \rangle_\Gamma$ . We use the notation  $\langle \cdot, \cdot \rangle$  both for the inner product in  $L_2(\Omega)$  and the duality pairing between  $H^1(\Omega)$  and  $H^*(\Omega)$ .

We shall assume that:

$$(H_\beta) \quad \begin{cases} \beta: \mathbb{R} \rightarrow \mathbb{R} \text{ is a nondecreasing Lipschitz continuous function,} \\ \beta(0) = 0, \ 0 \leq l_\beta \leq \beta'(s) \leq L_\beta < \infty \text{ for almost all } s \in \mathbb{R}, \\ \text{there exists } \lim_{|s| \rightarrow \infty} \beta'(s) = c_1 > 0, \end{cases}$$

$$(H_f) \quad \begin{cases} f: I \times \Omega \times \mathbb{R} \rightarrow \mathbb{R} \text{ is a Lipschitz continuous function with} \\ \text{Lipschitz constant } L_f, \text{ and there exists a constant } C \text{ such that:} \\ |f(t, x, 0)| \leq C \text{ for a.a. } t \in I, \ x \in \Omega, \end{cases}$$

$$(H_g) \quad \begin{cases} g: I \times \Gamma \times \mathbb{R} \rightarrow \mathbb{R} \text{ is a Lipschitz continuous function with} \\ \text{Lipschitz constant } L_g, \text{ and there exists a constant } C \text{ such that:} \\ |g(t, x, 0)| \leq C \text{ for a.a. } t \in I, x \in \Gamma, \end{cases}$$

$$(H_{u_p}) \quad u_p \in H^1(\Omega), \beta(u_p) \in H^1(\Omega),$$

$$(H_k) \quad \begin{cases} k: \mathbb{R} \rightarrow \mathbb{R}^{d \times d} \text{ is Lipschitz continuous and bounded,} \\ k(s) \text{ is a symmetric and (uniformly) positive definite matrix;} \\ \text{that is there exist positive constants } k_0, K_0 \in \mathbb{R} \text{ such that} \\ k_0 |\xi|^2 \leq \xi^T k(s) \xi \leq K_0 |\xi|^2 \text{ for all } \xi \in \mathbb{R}^d \text{ and } s \in \mathbb{R} \end{cases}$$

Let  $\{S_h\}_h$  be a family of decompositions

$$S_h = \{S_k\}_{k=1}^{K_h}$$

of  $\Omega$  into closed  $d$ -simplices so that:  $\bar{\Omega} = \cup_{k=1}^{K_h} S_k$  where  $h$  is the mesh size:  $h = \sup_{k=1, \dots, K_h} \text{diam } S_k$ .

We assume that

$$(H_{S_h}) \quad \begin{cases} \text{the family } \{S_h\} \text{ has the usual properties of finite elements,} \\ \text{i.e. it is regular and also the assumption of inverse inequality} \\ \text{holds in the sense of Ciarlet ([2, p. 134, p. 142]).} \end{cases}$$

The assumptions above will be simply denoted by (H), that is

$$(H) \quad (H_\Omega), (H_\beta), (H_k), (H_f), (H_g), (H_{S_h}), (H_{u_p})$$

Further we denote:

$$V_h^1 := \{\psi \in C^0(\bar{\Omega}) : \psi|_{S_k} \text{ is linear for all } k = 1, \dots, K_h\},$$

$$V_h^0 := \{\psi : \psi|_{S_k} \text{ is constant for all } k = 1, \dots, K_h\}.$$

On the boundary  $\Gamma$ , we define the discrete inner product by:

$$(2.1) \quad \langle \psi, \phi \rangle_{h, \Gamma} := \sum_{k=1}^{K_h} \int_{S_k \cap \Gamma} \Pi_h(\psi \phi) ds$$

for any piecewise continuous functions  $\psi, \phi$  in  $\bar{\Omega}$ , where  $\Pi_h$  stands for the local linear interpolation operator ([2]).

For any  $\psi, \varphi \in V_h^1$ , we have ([15]):

$$(2.2) \quad |\langle \psi, \varphi \rangle_{h,\Gamma}| \leq C_3 \|\psi\|_H \|\varphi\|_H$$

and

$$(2.3) \quad |\langle \psi, \varphi \rangle_\Gamma - \langle \psi, \varphi \rangle_{h,\Gamma}| \leq C_5 h \|\psi\|_H \|\varphi\|_H.$$

The estimate (2.3) holds also for functions  $\varphi \in V_h^1$  and  $\psi = b \cdot v$ , where  $v \in V_h^1$  and  $b \in V_h^0$ ;  $\|b\|_{L^\infty} \leq K$ ,  $K > 0$ .

We denote by  $a(\cdot, \cdot)$  the inner product in  $H^1(\Omega)$ :

$$a(w, z) := \langle \nabla w, \nabla z \rangle + \langle w, z \rangle.$$

We now introduce  $L_2$ -projection operator  $P_h^0: L_2(\Omega) \rightarrow V_h^0$ , which is defined by

$$\langle P_h^0 z, \psi \rangle = \langle z, \psi \rangle \text{ for any } \psi \in V_h^0, z \in L_2(\Omega)$$

and satisfies

$$(2.4) \quad \|z - P_h^0 z\|_{H^{-s}(\Omega)} \leq C_8 h^{r+s} \|z\|_{H^r(\Omega)}, \quad 0 \leq s, r \leq 1.$$

We also introduce the discrete  $H^1$ -projection operator  $P_h^1: H^1(\Omega) \rightarrow V_h^1$ , which is defined by

$$a(z - P_h^1 z, \psi) = 0 \text{ for any } \psi \in V_h^1, z \in H^1(\Omega)$$

and satisfies ([15])

$$(2.5) \quad \|z - P_h^1 z\|_{H^s(\Omega)} \leq C_9 h^{2-(r+s)} \|z\|_{H^{2-r}(\Omega)}, \quad 0 \leq s, r \leq 1.$$

We shall use the following well-known facts (see e.g. [13, p. 15].)

$$(2.6) \quad ab \leq \frac{a^2}{2\varepsilon} + \frac{\varepsilon b^2}{2} \text{ for any } a, b \in \mathbb{R} \text{ and } \varepsilon > 0,$$

$$(2.7) \quad 2a(a-b) = a^2 - b^2 + (a-b)^2 \text{ for any } a, b \in \mathbb{R},$$

$$(2.8) \quad \|v\|_\Gamma^2 \leq C_{10} \left( \varepsilon \|\nabla v\|^2 + \frac{1}{\varepsilon} \|v\|^2 \right) \text{ for any } v \in W^{1,2}(\Omega)$$

and  $\varepsilon > 0$  small.

We conclude with some notations concerning the time discretization. Let  $\tau = \frac{T}{n}$  be the time step and  $t_i = i\tau$ ,  $I_i = (t_{i-1}, t_i]$  for  $1 \leq i \leq n$ . We also set  $z^i := z(\cdot, t_i)$  or  $\bar{z}^i := \frac{1}{\tau} \int_{I_i} z(\cdot, t) dt$  for any continuous or integrable (in time) function  $z$  defined in  $Q$ , respectively, and  $\partial z^i := (z^i - z^{i-1})/\tau$ ,  $1 \leq i \leq n$  for any given family  $\{z^i\}_{i=0}^n$ . Similarly we denote  $\delta u_i = (u_i - u_{i-1})/\tau$  for  $i = 1, \dots, n$  and  $u_i, u_{i-1} \in V_h^0$ .

For simplicity we shall denote  $f(s) := f(x, t, s)$  and  $g(s) := g(x, t, s)$ . By  $C$  we denote a generic constant which is independent of time and space discretization  $\tau$  and  $h$ .

3. FORMULATIONS OF PROBLEMS

The variational formulation of our problem is as follows.

**Problem (P):** Find  $\{u(t, x), \theta(t, x)\}$  such that

$$(3.1) \quad u(t, x) \in L_2(I; L_2(\Omega)), \quad \partial_t u(t, x) \in L_2(I; H^*(\Omega)) \text{ and } u(0, x) = u_p(x)$$

$$(3.2) \quad \theta(t, x) \in L_2(I; H^1(\Omega))$$

$$(3.3) \quad \theta(t, x) = \beta(u(t, x)) \text{ for a.e. } (t, x) \in Q$$

and for all  $\varphi \in L_2(I, H^1(\Omega))$ , the following equation holds

$$(3.4) \quad \int_I (\langle \partial_t u, \varphi \rangle + \langle k(\theta) \nabla \theta, \nabla \varphi \rangle + \langle g(\theta), \varphi \rangle_\Gamma) dt = \int_I \langle f(\theta), \varphi \rangle dt.$$

As we have mentioned above, the following approximation scheme is based on the ideas of [5] and [7] (see the approximation scheme in Introduction). The basic idea of this linear scheme consists of determining a variable relaxation parameter  $\mu_i = \mu_i(x)$  to be used in the algebraic correction  $u_i := u_{i-1} + \mu_i(\theta_i - \beta(u_{i-1}))$ ,  $i = 1, \dots, n$ , where  $\theta_i$  is the approximation of  $\beta(u)$  at time  $t_i$ . Moreover, the same iterative method for finding functions  $\mu_i$  and  $\theta_i$  can be used also for improving the approximation of nonlinearities on the boundary and on the right hand side. In the same way as in the case of the nonlinearity  $\beta(u)$  we can use the variable relaxation parameters also for nonlinearities on the boundary (function  $g(\beta(u))$ ) and on the right hand side (function  $f(\beta(u))$ ). We denote these relaxation parameters by  $\omega_i$  (for the function  $g$ ) and  $\rho_i$  (for the function  $f$ ). We use a fully discrete scheme including the finite element method.

Therefore, our discrete problem is of the form:

**Problem  $(P_{h,\tau})$ :** For any  $1 \leq i \leq n$ , find  $\{u_i(x), \theta_i(x)\}$  such that  $u_i \in V_h^0$  and  $\theta_i \in V_h^1$ , and the functions  $\mu_i, \rho_i$  and  $\omega_i \in V_h^0$  which have the following properties:

$$(3.5) \quad u_0 := P_h^0 u_p(x), \quad \theta_0 := P_h^1(\beta(u_p(x))),$$

$$(3.6) \quad \begin{aligned} & \langle \mu_i P_h^0 \theta_i, \psi \rangle + \tau \langle k_{i-1} \nabla \theta_i, \nabla \psi \rangle + \tau \langle g(\theta_{i-1}), \psi \rangle_{h,\Gamma} + \tau \langle \omega_i (\theta_i - \theta_{i-1}), \psi \rangle_{h,\Gamma} \\ & = \langle \mu_i \beta(u_{i-1}), \psi \rangle + \tau \langle f(\beta(u_{i-1})), \psi \rangle + \tau \langle \rho_i (P_h^0 \theta_i - \beta(u_{i-1})), \psi \rangle \\ & \quad + \langle p_i, \psi \rangle \text{ for all } \psi \in V_h^1, \end{aligned}$$

$$(3.7) \quad \begin{aligned} & \| \beta(u_{i-1} + \mu_i (P_h^0 \theta_i - \beta(u_{i-1}))) - \beta(u_{i-1}) \|_{L_2, \mu_i} \\ & \leq \alpha \| P_h^0 \theta_i - \beta(u_{i-1}) \|_{L_2, \mu_i} + o\left(\frac{1}{\sqrt{n}}\right), \quad (\text{convergence condition}) \end{aligned}$$

$$(3.8) \quad u_i := u_{i-1} + \mu_i (P_h^0 \theta_i - \beta(u_{i-1})), \quad (\text{algebraic correction})$$

for  $i = 1, \dots, n$ , where the “error” functional  $p_i$  satisfies

$$(3.9) \quad \begin{aligned} |\langle p_i, \psi \rangle| &\leq \|p_i\|_{H^*(\Omega)} \|\psi\|_H \text{ for all } \psi \in H^1(\Omega) \text{ and} \\ \|p_i\|_{H^*} &= O\left(\frac{1}{n^\sigma}\right), \text{ where } \sigma > 1. \end{aligned}$$

Moreover, we have  $0 < \delta \leq \mu_i \leq K$ ,  $|\rho_i| \leq K$ ,  $|\omega_i| \leq K$  and  $k_{i-1} = k(\beta(u_{i-1}))$  and all members of this matrix are functions from  $V_h^0$ . Further  $\alpha > 0$  and  $K^{-1}, 1 - 2\alpha, \delta$  are sufficiently small positive constants. By  $\|\cdot\|_{L_2, \mu_i}$  we denote the norm in the weighted  $L_2$ -space with the weight function  $\mu_i$  (e.g. [10]). This scheme has the disadvantage of not being explicit with respect to  $\theta_i$  and  $\mu_i$ . We determine the values of the functions  $\theta_i, \mu_i, \rho_i, \omega_i$  by an iterative process that we describe later.

In case the function  $\beta$  is not strictly monotone (e.g. for the Stefan problem), we approximate the function  $\beta$  by a strictly monotone Lipschitz continuous function  $\beta_n$  (with Lipschitz constant  $L_{\beta_n}$ ), such that

$$(3.10) \quad \|\beta_n - \beta\|_{L_\infty(R)} = o\left(\frac{1}{\sqrt{n}}\right), \beta_n \in C^2, 0 < \delta_n < \beta'_n(s) \leq L_{\beta_n} \leq L_\beta$$

for all  $n$ .

#### 4. CONVERGENCE OF AN ITERATIVE METHOD

As we have mentioned above, the approximate scheme (3.5)–(3.8) has the disadvantage of not being explicit with respect to the functions  $\mu_i$  and  $\theta_i$ . There are several iterative schemes for solving this problem (see for example [4]). The scheme that we establish in this paper is based on the idea of an iterative method in [11].

Put:

$$(4.1) \quad \gamma_K(s) = \begin{cases} K & \text{if } s > K, \\ s & \text{if } -K \leq s \leq K, \\ -K & \text{if } s < -K. \end{cases}$$

Let  $1 \leq i \leq n$  be fixed. Then we define our iterative method as follows:

$$(4.2) \quad \begin{aligned} &\langle (\mu_{i,k-1} - \tau\rho_{i,k-1})(P_h^0\theta_{i,k} - \beta(u_{i-1})), \psi \rangle + \tau\langle k_{i-1}\nabla\theta_{i,k}, \nabla\psi \rangle \\ &\quad + \tau\langle \omega_{i,k-1}(\theta_{i,k} - \theta_{i-1}), \psi \rangle_{h,\Gamma} \\ &= \tau\langle f(\beta(u_{i-1})), \psi \rangle - \tau\langle g(\theta_{i-1}), \psi \rangle_{h,\Gamma} \text{ for all } \psi \in V_h^1. \\ \mu_{i,0} &:= \gamma_K\left(\frac{1}{\beta'_n(u_{i-1})}\right), \\ \rho_{i,0} &:= \gamma_K(P_h^0(g'(\theta_{i-1}))), \end{aligned}$$

$$\begin{aligned}
 \omega_{i,0} &:= \gamma_K(P_h^0(f'(\theta_{i-1}))). \\
 \bar{\mu}_{i,k} &:= \gamma_K\left(\frac{\beta_n^{-1}(\beta_n(u_{i-1}) + \alpha(P_h^0\theta_{i,k} - \beta(u_{i-1}))) - u_{i-1}}{P_h^0\theta_{i,k} - \beta(u_{i-1})}\right) \\
 \mu_{i,k} &:= \bar{\mu}_{i,k}, \text{ for } 1 \leq k \leq k_0, k_0 \in N \text{ be fixed} \\
 (4.3) \quad \mu_{i,k} &:= \min\{\bar{\mu}_{i,k}, \mu_{i,k-1}\}, \text{ for } k > k_0. \\
 \omega_{i,k} &:= \gamma_K\left(\frac{g(P_h^0\theta_{i,k}) - g(P_h^0\theta_{i-1})}{P_h^0(\theta_{i,k} - \theta_{i-1})}\right) \\
 \rho_{i,k} &:= \gamma_K\left(\frac{f(P_h^0\theta_{i,k}) - f(\beta(u_{i-1}))}{P_h^0\theta_{i,k} - \beta(u_{i-1})}\right) \text{ for } k = 1, \dots
 \end{aligned}$$

If  $P_h^0\theta_{i,k} = \beta(u_{i-1})$  then  $\mu_{i,k} := \mu_{i,k-1}$  and  $\rho_{i,k} := \rho_{i,k-1}$ . Similarly, if  $P_h^0(\theta_{i,k} - \theta_{i-1}) = 0$  then  $\omega_{i,k} := \omega_{i,k-1}$ .

The solvability of (4.2)–(4.3) follows from the theory of monotone operators (see [4]).

The sequences  $\{\mu_{i,k}\}, \{\rho_{i,k}\}, \{\omega_{i,k}\}, \{\theta_{i,k}\}$  of iterations help us to find functions  $\mu_i, \rho_i, \omega_i, \theta_i$  as it is formulated in the following theorem:

**Theorem 1.** *Assume (H). Let  $1 \leq i \leq n$  be fixed and  $\tau \leq \tau_0, h \leq h_0$  for sufficiently small  $\tau_0, h_0$ . If  $\{\mu_{i,k}\}, \{\rho_{i,k}\}, \{\omega_{i,k}\}$  and  $\{\theta_{i,k}\}$  are sequences from (4.2)–(4.3) then there exists index  $l \in N$  such that the functions  $\mu_i := \mu_{i,l}, \rho_i := \rho_{i,l}, \omega_i := \omega_{i,l}$  from  $V_h^0$  and  $\theta_i := \theta_{i,l} \in V_h^1$  satisfy the equation (3.6) and the inequality (3.7).*

*Proof.*

First we denote  $v_k = \mu_{i,k} - \tau\rho_{i,k}$ . It is obvious that this function is positive for sufficiently small  $\tau_0$ , hence  $v_k \geq \gamma$  for some  $\gamma > 0$ .

The monotonicity of the sequence  $\{\mu_{i,k}\}$  for  $k \geq k_0$  implies  $\mu_{i,k} \rightarrow \mu$  pointwise in  $\Omega$ . Since the functions  $\mu_{i,k}$  are bounded, we have  $\mu_{i,k} \rightarrow \mu$  in  $L_p(\Omega)$  for all  $p > 1$ .

We can easily prove that the sequence  $\{\theta_{i,k}\}$  is bounded in  $H^1(\Omega)$ :

In (4.2) we choose as a test function  $\psi = \theta_{i,k}$  and after some rearrangement we obtain:

$$\begin{aligned}
 &\langle v_{k-1}(P_h^0\theta_{i,k} - \beta(u_{i-1})), \theta_{i,k} \rangle + \tau k_0 \|\nabla\theta_{i,k}\|^2 + \tau \langle \omega_{i,k-1}(\theta_{i,k} - \theta_{i-1}), \theta_{i,k} \rangle_{h,\Gamma} \\
 &\leq \tau \langle f(\beta(u_{i-1})), \theta_{i,k} \rangle - \tau \langle g(\theta_{i-1}), \theta_{i,k} \rangle_{h,\Gamma}.
 \end{aligned}$$

Using the properties of the functions  $v_k$  and  $\omega_{i,k}$ , and due also to (2.2), (2.3), (2.4) and (2.6), we have:

$$\begin{aligned}
 \gamma \|\theta_{i,k}\|^2 + \tau k_0 \|\nabla\theta_{i,k}\|^2 &\leq \frac{\gamma}{2} \|\theta_{i,k}\|^2 + C(h^2 + \tau^2) \|\theta_{i,k}\|_H^2 + C \|\beta(u_{i-1})\|^2 \\
 &\quad + \tau \frac{k_0}{4} \|\nabla\theta_{i,k}\|^2 + C\tau \|\theta_{i,k}\|^2 + C \|\theta_{i-1}\|^2 \\
 &\quad + C \|f(\beta(u_{i-1}))\|^2 + C \|g(\theta_{i-1})\|_H^2.
 \end{aligned}$$

Now using the properties of the functions  $f, g, \theta_{i-1}, \beta(u_{i-1})$ , we obtain for sufficiently small  $h < h_0$ :

$$\|\theta_{i,k}\|_H \leq C.$$

From the properties of the sequence  $\{\mu_{i,k}\}$  it follows that there exists an index  $l$  such that  $\|\mu_{i,l-1} - \mu_{i,l}\|_{L^p(\Omega)} \leq C\tau^\sigma$  for  $\sigma > 1$ . We set  $\theta_i := \theta_{i,l}$ ,  $\mu_i := \mu_{i,l}$ ,  $\rho_i := \rho_{i,l-1}$  and  $\omega_i := \omega_{i,l-1}$ . We must only verify, that for these functions, the conditions (3.6) and (3.7) hold. It is clear that  $\mu_i = \mu_{i,l} \leq \bar{\mu}_{i,l}$  and that is why (3.7) holds.

For  $\theta_i := \theta_{i,l}$  the equation (4.2) holds. We have:

$$\begin{aligned} & \langle \mu_i(P_h^0\theta_i - \beta(u_{i-1})), \psi \rangle + \tau \langle k_{i-1} \nabla \theta_i, \nabla \psi \rangle \\ & \quad + \tau \langle \omega_i(\theta_i - \theta_{i-1}), \psi \rangle_{h,\Gamma} - \tau \langle \rho_i(P_h^0\theta_i - \beta(u_{i-1})), \psi \rangle \\ & = \langle (\mu_{i,l} - \mu_{i,l-1})(P_h^0\theta_i - \beta(u_{i-1})), \psi \rangle + \tau \langle f(\beta(u_{i-1})), \psi \rangle - \tau \langle g(\theta_{i-1}), \psi \rangle_{h,\Gamma}. \end{aligned}$$

We now set  $\langle p_i, \psi \rangle = \langle (\mu_{i,l} - \mu_{i,l-1})(P_h^0\theta_i - \beta(u_{i-1})), \psi \rangle$ . From the properties of  $\mu_{i,k}$ ,  $P_h^0\theta_i$  and  $\beta(u_{i-1})$  using generalized Hölder's inequality we obtain that the functional  $p_i$  satisfies (3.9). This completes the proof.  $\square$

## 5. STABILITY OF THE DISCRETE SCHEME

The problem (3.6)–(3.8) can be rewritten as follows

$$\begin{aligned} (5.1) \quad & \langle \delta u_i, \psi \rangle + \langle k_{i-1} \nabla \theta_i, \nabla \psi \rangle + \langle g(\theta_{i-1}), \psi \rangle_{h,\Gamma} \\ & \quad + \langle \omega_i(\theta_i - \theta_{i-1}), \psi \rangle_{h,\Gamma} \\ & = \langle f(\beta(u_{i-1})), \psi \rangle + \langle \rho_i(P_h^0\theta_i - \beta(u_{i-1})), \psi \rangle + \frac{1}{\tau} \langle p_i, \psi \rangle \\ & \quad \text{for all } \psi \in V_h^1 \text{ and } \|p_i\|_{H^*(\Omega)} = O(\tau^\sigma). \end{aligned}$$

**Lemma 1.** *Assume (H). Then for  $\tau \leq \tau_0$  and  $h \leq h_0$  such that the equation*

$$(5.2) \quad \tau = C_* h^\xi, \text{ for } 0 < \xi \leq 2$$

*is fulfilled and  $\tau_0, h_0$  are sufficiently small, there exists a constant  $C$ , independent of the discretization parameters such that*

$$(5.3) \quad \max_{1 \leq i \leq n} \|\beta(u_i)\| + \sum_{i=1}^n \|u_i - u_{i-1}\|^2 + \sum_{i=1}^n \tau \|\nabla \theta_i\|^2 \leq C.$$



*Proof.* The function  $\tau\theta_i$  is an admissible test function in (5.1) because  $\theta_i \in V_h^1$ . So let  $\tau\theta_i$  be a test function and sum (5.1) over  $i$  from 1 to  $m \leq n$ . We have:

$$\begin{aligned}
 (5.4) \quad & \sum_{i=1}^m \langle u_i - u_{i-1}, \theta_i \rangle + \sum_{i=1}^m \tau \langle k_{i-1} \nabla \theta_i, \nabla \theta_i \rangle + \sum_{i=1}^m \tau \langle g(\theta_{i-1}), \theta_i \rangle_{h,\Gamma} \\
 & + \sum_{i=1}^m \tau \langle \omega_i(\theta_i - \theta_{i-1}), \theta_i \rangle_{h,\Gamma} =: I + II + III + IV \\
 & = \sum_{i=1}^m \tau \langle f(\beta(u_{i-1})), \theta_i \rangle + \sum_{i=1}^m \tau \langle \rho_i(P_h^0 \theta_i - \beta(u_{i-1})), \theta_i \rangle + \sum_{i=1}^m \langle p_i, \theta_i \rangle \\
 & =: V + VI + VII.
 \end{aligned}$$

We shall estimate each resulting term. Some of these terms are similar as in [5] and [7] so we comment them only briefly.

First note that from (3.8) it holds:

$$P_h^0 \theta_i = \frac{u_i - u_{i-1}}{\mu_i} + \beta(u_{i-1}).$$

We use (see e.g. [12]) the convex function

$$\Phi_\lambda(s) = \int_0^s \lambda(z) dz \quad \text{for all } s \in \mathbb{R},$$

where the function  $\lambda: \mathbb{R} \rightarrow \mathbb{R}$  is absolutely continuous,  $\lambda(0) = 0$  and  $0 \leq \lambda' \leq \Lambda < \infty$ . The function  $\Phi_\lambda$  has the following properties:

$$\frac{1}{2\Lambda} \lambda^2(s) \leq \Phi_\lambda(s) \leq \frac{\Lambda}{2} s^2 \quad \text{for } s \in \mathbb{R}.$$

The difference  $u_i - u_{i-1} \in V_h^0$ , hence the definition of  $P_h^0$  and the monotonicity of  $\beta$  imply

$$\begin{aligned}
 & \sum_{i=1}^m \langle u_i - u_{i-1}, \theta_i \rangle = \sum_{i=1}^m \langle u_i - u_{i-1}, P_h^0 \theta_i \rangle \\
 & \geq \sum_{i=1}^m \left\langle u_i - u_{i-1}, \frac{u_i - u_{i-1}}{\mu_i} \right\rangle + \sum_{i=1}^m \int_\Omega (\Phi_\beta(u_i) - \Phi_\beta(u_{i-1})) dX \\
 & \quad - \sum_{i=1}^m \langle u_i - u_{i-1}, \beta(u_i) - \beta(u_{i-1}) \rangle.
 \end{aligned}$$

Further in the same way as in [5] we arrive at

$$(5.5) \quad I \geq (1 - 2\alpha) \sum_{i=1}^m \|u_i - u_{i-1}\|_{L_2, \frac{1}{\mu_i}}^2 + \frac{1}{2L_\beta} \|\beta(u_m)\|^2 - C.$$

We estimate the second term in (5.4) easily using  $(H_k)$ :

$$(5.6) \quad \tau \sum_{i=1}^m \langle k_{i-1} \nabla \theta_i, \nabla \theta_i \rangle \geq \tau k_0 \sum_{i=1}^m \|\nabla \theta_i\|^2.$$

In the third term in (5.4) we use (2.3),  $(H_g)$ ,  $(H_\beta)$ , (2.6), (2.8):

$$\begin{aligned} |III| &\leq \tau \sum_{i=1}^m \left| \langle g(\theta_{i-1}), \theta_i \rangle_\Gamma \right| + \tau \sum_{i=1}^m \left| \langle g(\theta_{i-1}), \theta_i \rangle_\Gamma - \langle g(\theta_{i-1}), \theta_i \rangle_{h,\Gamma} \right| \\ &\leq \tau C \sum_{i=1}^m \|\theta_i\|^2 + \tau \frac{k_0}{8} \sum_{i=1}^m \|\nabla \theta_i\|^2 + \tau h C \sum_{i=1}^m (\|\theta_i\|^2 + \|\nabla \theta_i\|^2) + C. \end{aligned}$$

Now for sufficiently small  $h_0$  we get

$$(5.7) \quad |III| \leq \tau C \sum_{i=1}^m \|\theta_i\|^2 + \tau \frac{k_0}{4} \sum_{i=1}^m \|\nabla \theta_i\|^2 + C.$$

For the fourth term we have:

$$|IV| \leq \tau C \sum_{i=1}^m \|\theta_i\|^2 + \tau \frac{k_0}{8} \sum_{i=1}^m \|\nabla \theta_i\|^2 + \tau h C \sum_{i=1}^m \|\theta_i\|_H^2 + C,$$

where we used (2.3), (2.6), (2.8), (2.7).

Now again for sufficiently small  $h_0$  we have:

$$(5.8) \quad |IV| \leq \tau C \sum_{i=1}^m \|\theta_i\|^2 + \tau \frac{3k_0}{16} \sum_{i=1}^m \|\nabla \theta_i\|^2 + C,$$

In the term  $V$ , we use  $(H_f)$ , the definition of the operator  $P_h^0$  ( $u_i \in V_h^0$ ),  $(H_\beta)$  and the relation for  $\theta_i$  as in the first term:

$$\begin{aligned} (5.9) \quad |V| &\leq \tau L_f \sum_{i=1}^m \left| \left\langle |\beta(u_{i-1})|, \left| \frac{u_i - u_{i-1}}{\mu_i} + \beta(u_{i-1}) \right| \right\rangle \right| \\ &\quad + \tau \frac{\delta}{4} \sum_{i=1}^m \left\| \frac{u_i - u_{i-1}}{\mu_i} + \beta(u_{i-1}) \right\|^2 + \frac{C}{8\delta} \|f(0)\|^2 \\ &\leq \tau C \sum_{i=1}^m \|\beta(u_i)\|^2 + \tau \sum_{i=1}^m \|u_i - u_{i-1}\|_{L^2, \frac{1}{\mu_i}}^2 + C. \end{aligned}$$

For the term  $VI$ , we use the property of  $P_h^0$  and (3.9), (3.8), (2.6):

$$(5.10) \quad |VI| \leq \tau C \sum_{i=1}^m \|u_i - u_{i-1}\|_{L^2, \frac{1}{\mu_i}}^2 + \tau C \sum_{i=1}^m \|\beta(u_i)\|^2 + C.$$

From the property of the functional  $p_i$  in the last term we easily get:

$$(5.11) \quad |VII| \leq \sum_{i=1}^m |\langle p_i, \theta_i \rangle| \leq \frac{4}{\tau k_0} \sum_{i=1}^m \|p_i\|_{H^*(\Omega)}^2 + \tau \frac{k_0}{16} \sum_{i=1}^m \|\theta_i\|_H^2 \\ \leq C + \tau \frac{k_0}{16} \sum_{i=1}^m (\|\nabla \theta_i\|^2 + \|\theta_i\|^2).$$

Now for sufficiently small  $\tau_0$  and from (5.5)–(5.11) we have:

$$\frac{7(1-2\alpha)}{8} \sum_{i=1}^m \|u_i - u_{i-1}\|_{L_2, \frac{1}{\mu_i}}^2 + \frac{1}{2L_\beta} \|\beta(u_m)\|^2 + \frac{k_0}{2} \sum_{i=1}^m \tau \|\nabla \theta_i\|^2 \\ \leq C + C_b \tau \sum_{i=1}^m \|\beta(u_i)\|^2 + \tau C_t \sum_{i=1}^m \|\theta_i\|^2,$$

where  $C_b$  and  $C_t$  are constants independent of time and space discretization.

We rearrange the last term of this inequality using (2.4) and the property of  $P_h^0 \theta_i$  in this way:

$$\tau C_t \sum_{i=1}^m \|\theta_i\|^2 \leq \tau \frac{4C_t}{\delta} \sum_{i=1}^m \|u_i - u_{i-1}\|_{L_2, \frac{1}{\mu_i}}^2 + \tau 4C_t \sum_{i=1}^m \|\beta(u_i)\|^2 \\ + \tau h^2 2C_t C_8^2 \sum_{i=1}^m \|\theta_i\|_H^2.$$

Using this estimate for sufficiently small  $\tau_0$  we have:

$$\frac{3(1-2\alpha)}{4} \sum_{i=1}^m \|u_i - u_{i-1}\|_{L_2, \frac{1}{\mu_i}}^2 + \frac{1}{2L_\beta} \|\beta(u_m)\|^2 + \frac{k_0}{2} \sum_{i=1}^m \tau \|\nabla \theta_i\|^2 \\ \leq C + (C_b + 4C_t) \tau \sum_{i=1}^m \|\beta(u_i)\|^2 + \tau h^2 C \sum_{i=1}^m \|\theta_i\|_H^2.$$

We add to the both sides of this inequality the term  $\frac{k_0}{4} \tau \|\theta_m\|^2$  and we estimate this term on the right hand side as above:

$$\frac{k_0}{4} \tau \|\theta_m\|^2 \leq \tau \frac{k_0}{\delta} \|u_m - u_{m-1}\|_{L_2, \frac{1}{\mu_m}}^2 + \tau k_0 \|\beta(u_{m-1})\|^2 + \tau h^2 k_0 C_8^2 \|\theta_m\|_H^2.$$

Now let the ratio between  $\tau$  and  $h$  be chosen in the following way:

$$\tau = C_* h^\xi, \quad \text{where } 0 < \xi \leq 2.$$

We conclude:

$$\begin{aligned} & \frac{(1-2\alpha)}{2K} \sum_{i=1}^m \|u_i - u_{i-1}\|^2 + \frac{1}{2L_\beta} \|\beta(u_m)\|^2 + \tau \frac{k_0}{4} \|\theta_m\|_H^2 + \frac{k_0}{4} \sum_{i=1}^m \tau \|\nabla \theta_i\|^2 \\ & \leq C + C\tau \sum_{i=1}^m \|\beta(u_i)\|^2 + \tau^2 C h_0^{2-\xi} \sum_{i=1}^m \|\theta_i\|_H^2. \end{aligned}$$

And now for sufficiently small  $\tau_0$  the assertion (5.3) follows as a consequence of the discrete Gronwall inequality.  $\square$

**Consequence.** *Let the assumptions of Lemma 1 hold. Then there exists constant  $C$ , independent of discretization parameters such that:*

$$(5.12) \quad \max_{i=1,\dots,n} \|P_h^0 \theta_i\| + \max_{i=1,\dots,n} \|u_i\| \leq C,$$

$$(5.13) \quad \sum_{i=1}^n \tau \|\theta_i\|^2 \leq C,$$

$$(5.14) \quad \sum_{i=1}^n \tau \|\theta_i\|_H^2 \leq C.$$

*Proof.* From the results of Lemma 1 we have:

$$\|P_h^0 \theta_i\| \leq C$$

uniformly for  $i = 1, \dots, n$ . Now (5.12) follows immediately from Lemma 1 and (H $_\beta$ ). Combining now these results and the results of Lemma 1 we have:

$$\begin{aligned} \sum_{i=1}^n \tau \|\theta_i\|^2 & \leq 2 \sum_{i=1}^n \tau \|\theta_i - P_h^0 \theta_i\|^2 + 2 \sum_{i=1}^n \tau \|P_h^0 \theta_i\|^2 \\ & \leq 2\tau \sum_{i=1}^n C_8^2 h^2 \|\theta_i\|_H^2 + 2TC \leq 2C + 2C\tau h^2 \sum_{i=1}^n (\|\theta_i\|^2 + \|\nabla \theta_i\|^2) \\ & \leq C + Ch^2 \sum_{i=1}^n \tau \|\nabla \theta_i\|^2 + 2C\tau h^2 \sum_{i=1}^n \|\theta_i\|^2. \end{aligned}$$

Using now also (5.3) we have

$$\tau(1 - 2Ch^2) \sum_{i=1}^n \|\theta_i\|^2 \leq C$$

and for  $h \leq h_0$  sufficiently small we get (5.13) and (5.14) too.  $\square$

6. CONVERGENCE OF THE METHOD

We denote  $\gamma := (\tau, h)$  the pair of discretization parameters, where  $\tau$  and  $h$  have the same meaning as before. Then Rothe's function is defined as follows:

$$(6.1) \quad \theta^{(\gamma)}(t, x) := \theta_{i-1}(x) + \frac{t - t_{i-1}}{\tau}(\theta_i - \theta_{i-1})$$

for  $t \in \langle t_{i-1}, t_i \rangle$ ,  $\theta_i \in V_h^1$  a  $i = 1, \dots, n$ .

We define the step function as:

$$(6.2) \quad \begin{aligned} \bar{\theta}^{(\gamma)}(t, x) &= \theta_i(x) \text{ for } t \in (t_{i-1}, t_i), \quad i = 1, \dots, n, \\ \bar{\theta}^{(\gamma)}(0, x) &= \beta(u_0(x)). \end{aligned}$$

We define also the function

$$(6.3) \quad \begin{aligned} P_h^0 \bar{\theta}^{(\gamma)}(t, x) &= P_h^0 \theta_i \text{ for } t \in (t_{i-1}, t_i), \quad i = 1, \dots, n, \\ P_h^0 \bar{\theta}^{(\gamma)}(0, x) &= \beta(u_0(x)). \end{aligned}$$

Analogously, we can define also Rothe's and the step function  $u^{(\gamma)}(t, x)$  and  $\bar{u}^{(\gamma)}(t, x)$ , respectively.

We denote the time derivative of Rothe's function  $u^{(\gamma)}$  by  $u_t^{(\gamma)}$ . For  $t \in (t_{i-1}, t_i)$  we have:

$$u_t^{(\gamma)} = \frac{u_i - u_{i-1}}{\tau}.$$

We denote the dual space of the space  $V_h^1$  by  $V_h^{1,*}$ .

We can prolongate all functions defined on  $Q$  by zero outside  $Q$ .

**Lemma 2.** *Under the assumption (H) and (5.2) there exists a constant  $C > 0$ , independent of mesh parameters, such that*

$$(6.4) \quad \|u_t^{(\gamma)}\|_{L_2(I, V_h^{1,*})} \leq C$$

$$(6.5) \quad \|u^{(\gamma)} - \bar{u}^{(\gamma)}\|_{L_2(I, L_2(\Omega))} + \|\bar{u}^{(\gamma)}(\cdot + \tau) - \bar{u}^{(\gamma)}(\cdot)\|_{L_2(I, L_2(\Omega))} \leq \frac{C}{\sqrt{n}}$$

$$(6.6) \quad \|\theta^{(\gamma)} - \bar{\theta}^{(\gamma)}\|_{L_2(I, L_2(\Omega))} + \|\bar{\theta}^{(\gamma)} - \beta(\bar{u}^{(\gamma)})\|_{L_2(I, L_2(\Omega))} \leq \frac{C}{\sqrt{n}}$$

*Proof.* The proof of (6.4) is very simple using the duality argument in (5.1) and Lemma 1.

We obtain the estimate (6.5) also very easily using the results of Lemma 1. The second part of (6.6) can be estimated as follows:

$$\begin{aligned} \|\bar{\theta}^{(\gamma)} - \beta(\bar{u}^{(\gamma)})\|_{L_2(I, L_2(\Omega))} &= \left( \sum_{i=1}^n \int_{I_i} \|\theta_i - \beta(u_i)\|^2 dt \right)^{\frac{1}{2}} \\ &\leq C\sqrt{\tau} \left( \sum_{i=1}^n \|P_h^0 \theta_i - \beta(u_{i-1})\|^2 + \sum_{i=1}^n \|\beta(u_{i-1}) - \beta(u_i)\|^2 + \sum_{i=1}^n \|\theta_i - P_h^0 \theta_i\|^2 \right)^{\frac{1}{2}} \\ &\leq C\sqrt{\tau} + Ch, \end{aligned}$$

where  $(H_\beta)$ , (2.4), (5.3) and (5.14) were used. The final result can be obtained immediately due to (5.2).

Using this result we obtain

$$\begin{aligned} \|\theta^{(\gamma)} - \bar{\theta}^{(\gamma)}\|_{L_2(I, L_2(\Omega))} &\leq C\sqrt{\tau} \left( \sum_{i=1}^n \|P_h^0 \theta_i - \theta_{i-1}\|^2 + \sum_{i=1}^n \|\theta_i - P_h^0 \theta_i\|^2 \right)^{\frac{1}{2}} \\ &\leq C\sqrt{\tau} \left( \sum_{i=1}^n \|u_i - u_{i-1}\|^2 + \sum_{i=1}^n \|\beta(u_{i-1}) - \theta_{i-1}\|^2 + C_8 h^2 \sum_{i=1}^n \|\theta_i\|_H^2 \right)^{\frac{1}{2}} \\ &\leq C\sqrt{\tau}, \end{aligned} \quad \square$$

**Lemma 3.** *Under the same assumptions of Lemma 2 we have the following estimate:*

$$(6.7) \quad \int_0^{T-z} \|\bar{\theta}^{(\gamma)}(t+z) - \bar{\theta}^{(\gamma)}(t)\|^2 dt \leq C(z + n^{-\frac{1}{2}})$$

uniformly for  $n$  and  $0 < z \leq z_0$ .

*Proof.* Using the results obtained above, the proof is very similar to that in [5] so we can omit it here.  $\square$

**Lemma 4.** *Let the assumptions of Lemma 1 hold. Then the sequence  $\{\theta^{(\gamma)}\}$  defined in (6.1) is relatively compact in  $L_2(Q)$ .*

*Proof.* For the proof we easily verify Kolmogoroff's compactness argument in  $L_2(Q_T)$  (see the Riesz theorem in [10, p. 88], for the proof see also [4, pp. 45–48]).  $\square$

The time derivative can be prolonged as in [7]:

**Definition.** For arbitrary  $\varphi \in L_2(I, H^1(\Omega))$  and for arbitrary  $I' \subset I$ , we define the function  $F_\gamma \in L_2(I, H^*(\Omega))$  by

$$(6.8) \quad \int_{I'} \langle F_\gamma(t), \varphi(t) \rangle dt := \int_{I'} \langle u_t^{(\gamma)}(t), P_h^1 \varphi(t) \rangle dt$$

**Lemma 5.** *The sequence  $F_\gamma$  defined in (6.8) is bounded in  $L_2(I, H^*(\Omega))$ .*

*Proof.* The assertion is a direct consequence of Lemma 2 and (6.8).  $\square$

We denote now by  $\rightarrow$  and  $\rightharpoonup$  the strong and the weak convergence, respectively.

**Lemma 6.** *Assume (H). Then there exists a function  $u \in L_2(I, L_2(\Omega))$  such that  $u_t \in L_2(I, H^*(\Omega))$  and  $\beta(u) \in L_2(I, H^1(\Omega))$ , and a subsequence (which we denote again by  $\{\gamma\}$ ) such that*

$$\begin{aligned} (6.9) \quad & u^{(\gamma)} \rightharpoonup u \text{ v } L_2(I, L_2(\Omega)) \\ (6.10) \quad & F_\gamma \rightharpoonup u_t \text{ v } L_2(I, H^*(\Omega)) \\ (6.11) \quad & \theta^{(\gamma)} \rightarrow \theta = \beta(u) \text{ v } L_2(I, L_2(\Omega)) \\ (6.12) \quad & \bar{\theta}^{(\gamma)} \rightarrow \beta(u) \text{ v } L_2(I, L_2(\Omega)) \\ (6.13) \quad & \beta(\bar{u}^{(\gamma)}) \rightarrow \beta(u) \text{ v } L_2(I, L_2(\Omega)) \\ (6.14) \quad & \bar{\theta}^{(\gamma)} \rightharpoonup \beta(u) \text{ v } L_2(I, H^1(\Omega)). \end{aligned}$$

*Proof.* Lemma 4 directly implies the existence of a function  $\theta \in L_2(I, L_2(\Omega))$  and a subsequence  $\{\gamma_1\}$  such that  $\theta^{(\gamma_1)} \rightarrow \theta$  in  $L_2(I, L_2(\Omega))$ ; moreover,  $\bar{\theta}^{(\gamma_1)} \rightarrow \theta$  and  $\beta(\bar{u}^{(\gamma)}) \rightarrow \theta$  in  $L_2(I, L_2(\Omega))$  due to (6.6). From (5.12), (6.4) and the reflexivity of  $L_2(I, L_2(\Omega))$  it follows that there exists  $u \in L_2(I, L_2(\Omega))$  and a subsequence  $\{\gamma_2\}$  such that  $u^{(\gamma_2)} \rightharpoonup u$ ,  $\bar{u}^{(\gamma_2)} \rightharpoonup u$  in  $L_2(I, L_2(\Omega))$  (where we choose  $\{\gamma_2\}$  as a subsequence of  $\{\gamma_1\}$ ). From the boundedness of  $\bar{\theta}^{(\gamma)}$  in  $L_2(I, H^1(\Omega))$  (see Lemma 1 and its Consequence) and the reflexivity of  $L_2(I, H^1(\Omega))$  we obtain weak convergence of some subsequence  $\{\gamma_3\}$  (chosen as a subsequence of  $\{\gamma_2\}$ ) in this space.

By standard arguments we can obtain the fact that  $\theta$  is identical with  $\beta(u)$  (see [7], [4]). Lemma 5 implies the existence of  $F \in L_2(I, H^*(\Omega))$  and a subsequence  $\{\gamma\}$  (chosen from  $\{\gamma_3\}$ ), such that  $F_{\gamma} \rightharpoonup F$  v  $L_2(I, H^*(\Omega))$ .

We conclude the proof by proving  $\frac{du}{dt} = F$  in  $L_2(I, H^*(\Omega))$ , that means  $\frac{du(t)}{dt} = F(t)$  for a.a.  $t \in I$ .

From the fact that  $F_\gamma \rightharpoonup F$  v  $L_2(I, H^*(\Omega))$  we have for any  $\varphi \in L_2(I, H^1(\Omega))$

$$\int_I \langle u^{(\gamma)} - u_0, \varphi \rangle dt = \int_I \left\langle \int_0^t u_s^{(\gamma)}(s) ds, P_h^1 \varphi(t) \right\rangle dt + \int_I \langle u^{(\gamma)} - u_0, \varphi - P_h^1 \varphi \rangle dt.$$

From the standard properties of Bochner's integral, the definition of  $F_\gamma$ , the boundedness of  $u^{(\gamma)}$  in  $C(I, L_2(\Omega))$  and (2.5) it follows that passing to the limit as  $\gamma \rightarrow 0$  (i.e.  $h \rightarrow 0$ ), we obtain

$$\int_I \langle u(t) - u_p, \varphi(t) \rangle dt \leq \int_I \left\langle \int_0^t F(s) ds, \varphi(t) \right\rangle dt.$$

On the other hand,

$$\begin{aligned} \int_I \int_0^t \langle F_\gamma(s), \varphi(t) \rangle ds dt &= \int_I \int_0^t \langle u_s^{(\gamma)}(s), P_h^1 \varphi(t) \rangle ds dt \\ &= \int_I \langle u^{(\gamma)}(t) - u_0, \varphi(t) \rangle dt + \int_I \langle u^{(\gamma)}(t) - u_0, P_h^1 \varphi(t) - \varphi(t) \rangle dt. \end{aligned}$$

Again, for  $\gamma \rightarrow 0$  we obtain:

$$\int_I \left\langle \int_0^t F(s) ds, \varphi(t) \right\rangle dt \leq \int_I \langle u(t) - u_p, \varphi(t) \rangle dt.$$

Combining these two results and basic properties of abstract functions we obtain

$$u(t) = u_0 + \int_0^t F(s) ds,$$

that means

$$\frac{du(t)}{dt} = F(t)$$

(see [9]). □

For proving strong the convergence of some subsequence  $\bar{\theta}^{(\gamma)}$  to the function  $\beta(u)$  in  $L_2(I, H^1(\Omega))$  we need the following lemma (for its proof see [6] or [4]):

**Lemma A.** *Let  $u$  and a subsequence  $\{\bar{u}^{(\gamma)}\}$  be the same as in Lemma 6. Then for almost all  $t \in I$  it holds:*

$$(i) \lim_{k \rightarrow \infty} \int_0^t \langle u_s^{(\gamma_k)}(s), \bar{\theta}^{(\gamma_k)}(s) \rangle ds \geq \int_{\Omega} \Phi_{\beta}(u(t)) dx - \int_{\Omega} \Phi_{\beta}(u_p) dx,$$

*( $\{\gamma_k\}$  is some subsequence of  $\{\gamma\}$ );*

$$(ii) \int_0^t \langle u_s, \beta(u(s)) \rangle ds = \int_{\Omega} \Phi_{\beta}(u(t)) dx - \int_{\Omega} \Phi_{\beta}(u_p) dx.$$

**Lemma 7.** *Let the assumptions of Lemma 1 hold and let the function  $u$  and the subsequence  $\{\bar{\theta}^{(\gamma)}\}$  be as in Lemma 6. Then it holds:*

$$(6.15) \quad \bar{\theta}^{(\gamma)} \rightarrow \beta(u) \text{ in } L_2(I, H^1(\Omega)).$$

*Proof.* In the notation above, the functions

$$P_h^1 \bar{\beta}^i = \frac{1}{\tau} \int_{I_i} P_h^1 \beta(u(t)) dt, \quad i = 1, \dots, n,$$

belong to  $V_h^1$ . Now we choose the function  $\psi = \theta_i - P_h^1 \bar{\beta}^i$  as a test function in (5.1). After multiplying by  $\tau$  and rearranging we have

$$\begin{aligned} & \int_{I_i} \langle \delta u_i, \theta_i - P_h^1 \beta(u(t)) \rangle dt + \int_{I_i} \langle k_{i-1} \nabla \theta_i, \nabla (\theta_i - P_h^1 \beta(u(t))) \rangle \\ & \quad + \int_{I_i} \langle g(\theta_i), \theta_i - P_h^1 \beta(u(t)) \rangle_{h, \Gamma} dt + \int_{I_i} \langle \omega_i (\theta_i - \theta_{i-1}), \theta_i - P_h^1 \beta(u(t)) \rangle_{h, \Gamma} dt \\ & = \int_{I_i} \langle f(\beta(u_{i-1})), \theta_i - P_h^1 \beta(u(t)) \rangle dt + \int_{I_i} \langle \rho_i (P_h^0 \theta_i - \beta(u_{i-1})), \theta_i - P_h^1 \beta(u(t)) \rangle dt \\ & \quad + \frac{1}{\tau} \int_{I_i} \langle p_i, \theta_i - P_h^1 \beta(u(t)) \rangle dt. \end{aligned}$$



For simplicity, we denote

$$\begin{aligned} k_\gamma(t) &= k_{i-1} \text{ pre } t \in (t_{i-1}, t_i) \\ \bar{\theta}_\tau^{(\gamma)}(t) &= \theta_{i-1} \text{ pre } t \in (t_{i-1}, t_i) \\ f_\gamma(\beta(\bar{u}_\tau^{(\gamma)})) &= f(\beta(u_{i-1})) = f(t_i, \beta(u_{i-1})) \text{ pre } t \in (t_{i-1}, t_i) \\ g_\gamma(\bar{\theta}_\tau^{(\gamma)}) &= g(\theta_{i-1}) = g(t_i, \theta_{i-1}) \text{ pre } t \in (t_{i-1}, t_i) \\ \bar{p}^{(\gamma)}(t) &= p_i \text{ pre } t \in (t_{i-1}, t_i). \end{aligned}$$

After summing over  $i = 1, \dots, n$  we arrive at

$$\begin{aligned} (6.16) \quad & \int_I \langle u_t^{(\gamma)}(t), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle dt \\ & + \int_I \langle k_\gamma(t) \nabla \bar{\theta}^{(\gamma)}(t), \nabla(\bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t))) \rangle dt \\ & + \int_I \langle g_\gamma(\bar{\theta}_\tau^{(\gamma)}(t), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t))) \rangle_{h,\Gamma} dt \\ & + \int_I \langle \bar{\omega}^{(\gamma)}(t)(\bar{\theta}^{(\gamma)}(t) - \bar{\theta}_\tau^{(\gamma)}(t)), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle_{h,\Gamma} dt \\ & = \int_I \langle f_\gamma(\beta(\bar{u}_\tau^{(\gamma)}(t))), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle dt \\ & + \int_I \langle \bar{\rho}^{(\gamma)}(t)(P_h^0 \bar{\theta}^{(\gamma)}(t) - \beta(\bar{u}_\tau^{(\gamma)}(t))), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle dt \\ & + \frac{1}{\tau} \int_I \langle \bar{p}^{(\gamma)}(t), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle dt. \end{aligned}$$

We will estimate each term of the equation (6.16).

In the first term we can use the definition of  $F_\gamma$ , the results of Lemma A, (6.10) and the fact  $\beta(u) \in L_2(I, H^1(\Omega))$  and passing to the limit as  $\gamma \rightarrow 0$  we get

$$\lim_{\gamma \rightarrow 0} \int_I \langle u_t^{(\gamma)}(t), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle dt \geq 0.$$

We rearrange the second term of (6.16) as follows

$$\begin{aligned} & \int_I \langle k_\gamma(t) \nabla \bar{\theta}^{(\gamma)}(t), \nabla(\bar{\theta}^{(\gamma)}(t) - \beta(u(t))) \rangle dt \\ & + \int_I \langle k_\gamma(t) \nabla \bar{\theta}^{(\gamma)}(t), \nabla(\beta(u(t)) - P_h^1 \beta(u(t))) \rangle dt \\ & \geq k_0 \|\nabla(\bar{\theta}^{(\gamma)} - \beta(u))\|_{L_2(I, L_2(\Omega))}^2 + \int_I \langle k_\gamma(t) \nabla \beta(u(t)), \nabla(\bar{\theta}^{(\gamma)}(t) - \beta(u(t))) \rangle dt \\ & + \int_I \langle k_\gamma(t) \nabla \bar{\theta}^{(\gamma)}(t), \nabla(\beta(u) - P_h^1 \beta(u(t))) \rangle dt \end{aligned}$$

Now for  $\gamma \rightarrow 0$ , the second term of this inequality converges to 0 because of the properties of the matrix  $k$ , the results of Lemma 6 and the Lebesgue dominating convergence theorem. The third term can be estimated as follows

$$\begin{aligned} & \int_I \langle k_\gamma(t) \nabla \bar{\theta}^{(\gamma)}(t), \nabla(\beta(u) - P_h^1 \beta(u(t))) \rangle dt \\ & \leq CK_0 \|\bar{\theta}^{(\gamma)}\|_{L_2(I, H^1(\Omega))} \|\beta(u) - P_h^1 \beta(u)\|_{L_2(I, H^1(\Omega))} \\ & \leq C \|\beta(u) - P_h^1 \beta(u)\|_{L_2(I, H^1(\Omega))}, \end{aligned}$$

where we used again the properties of  $k_\gamma$  and (5.14). The convergence for this term now follows from the interpolation property for the finite element method ([2]).

The convergence of the third term in (6.16) is based on the convergence of

$$\left| \int_I \langle g_\gamma(\bar{\theta}_\tau^{(\gamma)}(t)), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle_\Gamma dt \right|$$

which follows similarly as in [7] so we can omit its proof here.

The next term in (6.16) can be estimated similarly:

$$\begin{aligned} & \left| \int_I \langle \bar{\omega}^{(\gamma)}(t) (\bar{\theta}^{(\gamma)}(t) - \bar{\theta}_\tau^{(\gamma)}(t)), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle_\Gamma dt \right| \\ & \leq C\varepsilon \|\nabla \bar{\theta}^{(\gamma)} - \beta(u)\|_{L_2(I, L_2(\Omega))}^2 + \frac{C}{\varepsilon} \|\bar{\theta}^{(\gamma)} - \beta(u)\|_{L_2(I, L_2(\Omega))}^2 \\ & \quad + Ch \|\bar{\theta}^{(\gamma)}\|_{L_2(I, H^1(\Omega))} \|\bar{\theta}^{(\gamma)} - P_h^1 \beta(u)\|_{L_2(I, H^1(\Omega))} \end{aligned}$$

For sufficiently small values  $\varepsilon$  and  $h$  and again due to the strong convergence of  $\{\bar{\theta}^{(\gamma)}\}$  to  $\beta(u)$  in  $L_2(I, L_2(\Omega))$  and the boundedness of  $\bar{\omega}^{(\gamma)}$  and  $\{\bar{\theta}^{(\gamma)}\}$  in  $L_2(I, H^1(\Omega))$  we obtain the convergence to zero for this term.

The convergence of the first term on the right hand side of (6.16)

$$\int_I \langle f_\gamma(\beta(\bar{u}_\tau^{(\gamma)}(t))), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle dt$$

can be omitted again because it is similar as in [7].

The next term can be estimated as follows

$$\begin{aligned} & \int_I \langle \bar{\rho}^{(\gamma)}(t) (P_h^0 \bar{\theta}^{(\gamma)}(t) - \beta(\bar{u}_\tau^{(\gamma)}(t))), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle dt \\ & \leq K (\|P_h^0 \bar{\theta}^{(\gamma)}\|_{L_2(I, L_2(\Omega))} + \|\beta(\bar{u}_\tau^{(\gamma)})\|_{L_2(I, L_2(\Omega))}) \\ & \quad \times (\|\bar{\theta}^{(\gamma)} - \beta(u)\|_{L_2(I, L_2(\Omega))} + \|\beta(u) - P_h^1 \beta(u)\|_{L_2(I, L_2(\Omega))}). \end{aligned}$$

Due to (5.12) and (5.3), we have the boundedness of  $\{P_h^0 \bar{\theta}^{(\gamma)}\}$  and  $\{\beta(\bar{u}_\tau^{(\gamma)})\}$  and conclusion is analogous as above.

The estimation of the last term is straightforward with respect to the properties of  $p_i$  for  $i = 1, \dots, n$ :

$$\begin{aligned} \frac{1}{\tau} \int_I \langle \bar{p}^{(\gamma)}(t), \bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t)) \rangle dt &\leq \frac{1}{\tau} \int_I \|\bar{p}^{(\gamma)}(t)\|_{H^*} \|\bar{\theta}^{(\gamma)}(t) - P_h^1 \beta(u(t))\|_H dt \\ &\leq C\tau^{\sigma-1} \|\bar{\theta}^{(\gamma)} - P_h^1 \beta(u)\|_{L_2(I, H^1(\Omega))}^2, \end{aligned}$$

which converges again to zero.

Now we can conclude:

$$\|\nabla(\bar{\theta}^{(\gamma)} - \beta(u))\|_{L_2(I, L_2(\Omega))}^2 \rightarrow 0 \text{ for } \gamma \rightarrow 0.$$

which together with (6.12) gives the assertion of Lemma. □

**Consequence.** *Let the subsequence  $\{\bar{\theta}^{(\gamma)}\}$  be as in Lemma 6. Then it holds:*

$$\bar{\theta}^{(\gamma)} \rightarrow \beta(u) \text{ in } L_2(I, L_2(\Gamma)).$$

*Proof.* The proof follows in a straightforward way from the imbedding theorem ([10]). □

**Lemma 8.** *Assume (H) and let the subsequence  $\{\bar{\theta}^{(\gamma)}\}$  from (6.1) have the properties as above. Let the subsequence  $\{\bar{\theta}_\tau^{(\gamma)}\}$  be the same as in the proof of Lemma 7. Then it holds:*

$$(6.17) \quad \|\bar{\theta}_\tau^{(\gamma)} - \bar{\theta}^{(\gamma)}\|_{L_2(I, L_2(\Gamma))} \rightarrow 0 \text{ for } \gamma \rightarrow 0.$$

*Proof.* We use (2.7) for  $\varepsilon = \tau^{\frac{1}{3}}$  and the boundedness of  $\bar{\theta}^{(\gamma)}, \bar{\theta}_\tau^{(\gamma)}$  (see Consequence of Lemma 1). We have

$$\begin{aligned} &\int_I \|\bar{\theta}_\tau^{(\gamma)}(t) - \bar{\theta}^{(\gamma)}(t)\|_\Gamma^2 dt \\ &\leq C_{10}\tau^{\frac{1}{3}} \int_I \|\nabla(\bar{\theta}_\tau^{(\gamma)}(t) - \bar{\theta}^{(\gamma)}(t))\|^2 dt + C_{10}\frac{1}{\tau^{\frac{1}{3}}} \int_I \|\bar{\theta}_\tau^{(\gamma)}(t) - \bar{\theta}^{(\gamma)}(t)\|^2 dt \\ &\leq C\tau^{\frac{1}{3}} + C_{10}\frac{1}{\tau^{\frac{1}{3}}} \left( \int_0^{T-\tau} \|\bar{\theta}^{(\gamma)}(t+\tau) - \bar{\theta}^{(\gamma)}(t)\|^2 dt + \int_{-\tau}^0 \|\bar{\theta}^{(\gamma)}(t+\tau)\|^2 dt \right) \\ &\leq C\tau^{\frac{1}{6}} \rightarrow 0, \end{aligned}$$

where similarly as in Lemma 4 we put  $\bar{\theta}^{(\gamma)} := 0$  on  $\langle -\tau, 0 \rangle$  and then we used (6.7) from Lemma 3, (2.5) and Lemma 1. □

Now the main result is:

**Theorem 2.** *Assume (H). Let the ratio between space and time discretization step is as in (5.2). Then there exists a pair of functions  $\{u(t, x), \theta(t, x)\}$  which fulfil the relations (3.1)–(3.3) and the variational formulation (3.4). Moreover, there exist subsequences  $\{\theta^{\bar{\gamma}}\}, \{u^{\bar{\gamma}}\}$  of sequences  $\{\theta^\gamma\}, \{u^\gamma\}$  defined in (6.1) such that*

$$\begin{aligned} u^{\bar{\gamma}} &\rightharpoonup u \quad \text{and} \quad \theta^{\bar{\gamma}} \rightarrow \theta = \beta(u) \quad \text{in } L_2(I, L_2(\Omega)), \\ \bar{\theta}^{\bar{\gamma}} &\rightarrow \beta(u) \quad \text{in } L_2(I, H^1(\Omega)) \end{aligned}$$

for  $\bar{\gamma} \rightarrow 0$ .

*Proof.* Due to Lemma 6 we have the existence of a pair of functions  $u(t, x)$ ,  $\theta(t, x) = \beta(u(t, x))$  and subsequences converging to them. Now we must prove that this pair of functions satisfies the variational identity (3.4).

We define

$$P_h^1 \bar{v}^i = \frac{1}{\tau} \int_{I_i} P_h^1 v(t) dt, \quad i = 1, \dots, n,$$

for arbitrary  $v \in L_2(I, H^1(\Omega))$ . Then  $P_h^1 \bar{v}^i$  belongs to  $V_h^1$ . Now we use the same notation as in Lemma 7 and we choose as a test function  $P_h^1 \bar{v}^i$  for  $i = 1, \dots, n$ . In an analogous way as in Lemma 7, we can get (we denote subsequences  $\{\bar{\gamma}\}$  again by  $\{\gamma\}$ ):

$$\begin{aligned} (6.18) \quad & \int_I \langle u_t^{(\gamma)}(t), P_h^1 v(t) \rangle dt + \int_I \langle k_\gamma(t) \nabla \bar{\theta}^{(\gamma)}(t), \nabla (P_h^1 v(t)) \rangle dt \\ & + \int_I \langle g_\gamma(\bar{\theta}_\tau^{(\gamma)}(t), P_h^1 v(t)) \rangle_{h, \Gamma} dt \\ & + \int_I \langle \bar{\omega}^{(\gamma)}(t) (\bar{\theta}^{(\gamma)}(t) - \bar{\theta}_\tau^{(\gamma)}(t)), P_h^1 v(t) \rangle_{h, \Gamma} dt \\ & = \int_I \langle f_\gamma(\beta(\bar{u}_\tau^{(\gamma)}(t))), P_h^1 v(t) \rangle dt \\ & + \int_I \langle \bar{\rho}^{(\gamma)}(t) (P_h^0 \bar{\theta}^{(\gamma)}(t) - \beta(\bar{u}_\tau^{(\gamma)}(t))), P_h^1 v(t) \rangle dt \\ & + \frac{1}{\tau} \int_I \langle \bar{p}^{(\gamma)}(t), P_h^1 v(t) \rangle dt. \end{aligned}$$

Now we pass to the limit as  $\gamma \rightarrow 0$ :

For the first term we use (6.8), Lemma 6 (6.10):

$$\int_I \langle u_t^{(\gamma)}(t), P_h^1 v(t) \rangle dt = \int_I \langle F_\gamma(t), v(t) \rangle dt \rightarrow \int_I \langle u_t(t), v(t) \rangle dt.$$

In the second term we use the fact  $\bar{\theta}_\tau^{(\gamma)} \rightarrow \beta(u)$  in  $L_2(I, L_2(\Omega))$  (from Lemma 8), the properties of  $k$ , relations (6.13) and (6.14), the boundedness  $\{\bar{\theta}^{(\gamma)}\}$  in

$L_2(I, H^1(\Omega))$  and  $P_h^1 v \rightarrow v$  in  $L_2(I, H^1(\Omega))$ . We have:

$$\int_I \langle k_\gamma(t) \nabla \bar{\theta}^{(\gamma)}(t), \nabla (P_h^1 v(t)) \rangle dt \rightarrow \int_I \langle k(t) \nabla \beta(u(t)), \nabla v(t) \rangle dt.$$

In the third term we use (2.3) and the boundedness of  $\bar{\theta}^{(\gamma)}$  in  $L_2(I, L_2(\Gamma))$  (see Consequence of Lemma 1),  $(H_g)$  and Lemma 8:

$$\int_I \langle g_\gamma(\bar{\theta}_\tau^{(\gamma)}(t), P_h^1 v(t)) \rangle_{h,\Gamma} dt \rightarrow \int_I \langle g(t, \beta(u(t)), v(t)) \rangle_\Gamma dt$$

for  $\gamma \rightarrow 0$ .

If we use (2.3) and the Consequence of Lemma 1, Lemma 8 and the boundedness of  $\bar{\omega}^{(\gamma)}$  for the fourth term, we obtain:

$$\int_I \langle \bar{\omega}^{(\gamma)}(t) (\bar{\theta}^{(\gamma)}(t) - \bar{\theta}_\tau^{(\gamma)}(t)), P_h^1 v(t) \rangle_{h,\Gamma} dt \rightarrow 0.$$

Similarly, in the fifth term, we use  $(H_f)$ ,  $(H_\beta)$ , Lemma 1 and (6.13):

$$\int_I \langle f_\gamma(\beta(\bar{u}_\tau^{(\gamma)}(t))), P_h^1 v(t) \rangle dt \rightarrow \int_I \langle f(t, \beta(u(t))), v(t) \rangle dt.$$

The next term converges to zero due to the boundedness of  $\rho^{(\gamma)}$ , Lemma 6, (6.13), the inequality (2.4) and the boundedness of  $\bar{\theta}^{(\gamma)}$  in  $L_2(I, H^1(\Omega))$ .

The last term also converges to zero due to the properties of the functionals  $p_i$  for  $i = 1, \dots, n$ . So the pair of functions  $u(t, x)$ ,  $\theta(t, x) = \beta(u(t, x))$  satisfies the problem (P). This completes the proof.  $\square$

## References

1. Berger A. E., Brezis H. and Rogers J. C. W., *A numerical method for solving the problem  $u_t - \Delta f(u) = 0$* , R.A.I.R.O Anal.Numer **13** (1979), 297–312.
2. Ciarlet P. F., *The Finite Element Method For Elliptic Problems*, North-Holland Publishing Company, 1978.
3. Handlovičová A., *Error estimates of a linear approximation scheme for nonlinear diffusion problems*, Acta Math. Univ. Comenianae **LXI** (1992), 27–39.
4. ———, *Numerical solution of Stefan problem by linear approximation scheme*, PhD thesis, 1993.
5. Jäger W. and Kačur J., *Solution of porous medium type systems by linear approximation schemes*, Numer. Math. **60** (1991), 407–427.
6. ———, *Approximation of porous medium type systems by nondegenerate elliptic systems*, Preprint 582, Universität Heidelberg SFB 123, 1990.
7. Kačur J., Handlovičová A. and Kačurová M., *Solution of nonlinear diffusion problems by linear approximation schemes*, SIAM Journal Numer. Anal. **30** (1993), 1703–1722.
8. Kačurová M., *Solution of porous medium type problems with nonlinear boundary conditions by linear approximation schemes*, PhD thesis, 1989.
9. Kačur J., *Method of Rothe in Evolution Equations*, Teubner Verlag, 1985.

10. Kufner A., John V. and Fučík S., *Function spaces*, Academia, Prague, 1977.
11. Kačur J. and Mikula K., *Evolution of convex plane curves describing anisotropic motions of phase interfaces*, Preprint of Comenius University No. M4-93, 1993.
12. Magenes E., Nocketto R. H. and Verdi C., *Energy error estimates for a linear scheme to approximate nonlinear parabolic problems*, *Mathematical modelling and numerical analysis* **21** (1987), 655–678.
13. Nečas J., *Les methodes directes en theorie des equationes elliptiques*, Academia, Prague, 1967.
14. Nocketto R. H. and Verdi C., *An efficient scheme to approximate parabolic free boundary problems: error estimates and implementation*, *American Mathematical Society* (1988), 27–53.
15. ———, *Approximation of degenerate parabolic problems using numerical integration*, *SIAM J. NUMER. ANAL.* **25**, no. 4 (1988).

A. Handlovičová, Slovak Technical University, Dept. of Mathematics, Radlinského 11, 813 68 Bratislava, Slovakia