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Some Common Fixed Point Theorems on G-Metric Space

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Abstract

The purpose of this paper is to present some common fixed point theorems in G-Metric spaces, by employing the notion of Common limit in the range property and to demonstrate suitable examples. These results extend and generalizes several well known results in the literature.

Keywords: *Coincidence point, Fixed point, G-Metric Space, CLR_g Property, Weakly compatible maps.*

1 Introduction and Preliminaries

Inspired by the fact that metric fixed point theory has a wide application in almost all fields of quantitative sciences, many authors have directed their attention to generalize the notion of a metric space. In this respect, several generalized metric spaces have come through by many authors, in the last decade. Among all the generalized metric spaces, the notion of G-Metric space has attracted considerable attention from fixed point theorists. The concept of a G-Metric space was introduced by Mustafa and Sims in [19], wherein the authors discussed the topological properties of this space and proved the analog

of the banach contraction principle in the context of G-metric spaces. Following these results, many authors have studied and developed several common fixed point theorems in this framework.

In 2002, M.Aamri and D.El Moutawakil[9] introduced the property (E.A), which is a true generalization of noncompatible maps in metric spaces. Under this notion many common fixed point theorems were studied in the literature (see [1,3,5,9,14,15] and the references therein). In 2011, the concept of Common limit in the range of g (CLR_g) property for a pair of self mappings in Fuzzy metric space was introduced by Sintunavarat et al.[17]. The importance of this property is, it ensures that one does not require the closeness of the range subspaces and hence, now a days, authors are giving much attention to this property for generalizing the results present in the literature(see [11]-[13] and the references therein). Very recently, this was extended to two pairs of self mappings as $CLR_{(S,T)}$ property by E.Karampur et al.[4].

In the present paper, by employing the notions of common limit in the range property for two as well as four self maps and weak compatibility , which is an efficient tool in providing the common fixed points, we derive some common fixed point theorems in the realm of G-metric space, which generalizes various comparable results in [2,7,9,10,14,16,18]and others. At the same time, we present suitable examples to exhibit the utility of the main results presented.

The following are the basic definitions needed in the main results.

Definition 1.1 [19] *Let X be a nonempty set and $G : X \times X \times X \rightarrow [0, \infty)$ be a function satisfying the following properties:*

G1 $G(x, y, z) = 0$ if $x = y = z$.

G2 $0 < G(x, x, y)$ for all $x, y \in X$ with $x \neq y$.

G3 $G(x, x, y) \leq G(x, y, z)$ for all $x, y, z \in X$ with $z \neq y$.

G4 $G(x, y, z) = G(x, z, y) = G(y, z, x) = \dots$ (symmetry in all three variables).

G5 $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$ for all $x, y, z, a \in X$ (rectangle inequality).

Then the function G is called a generalized metric or, more specifically, a G-metric on X , and the pair (X, G) is called a G-metric space.

Definition 1.2 [19] *A G-Metric space (X, G) is said to be symmetric if $G(x, y, y) = G(y, x, x)$ for all $x, y \in X$.*

Example : Let (X, d) be the usual metric space Then the function $G : X \times X \times X \rightarrow [0, \infty)$ defined by $G(x, y, z) = \max\{d(x, y), d(y, z), d(z, x)\}$ for all $x, y, z \in X$, is a G-Metric space.

In their initial paper Mustafa and Sims [19] also proved the following proposition.

Proposition 1.3 *Let (X, G) be a G -metric space. Then, for any $x, y, z, a \in X$, it follows that*

1. if $G(x, y, z) = 0$, then $x = y = z$.
2. $G(x, y, z) \leq G(x, x, y) + G(x, x, z)$.
3. $G(x, y, y) \leq 2G(y, x, x)$.
4. $G(x, y, z) \leq G(x, a, z) + G(a, y, z)$.
5. $G(x, y, z) \leq \frac{2}{3}[G(x, y, a) + G(x, a, z) + G(a, y, z)]$.
6. $G(x, y, z) \leq G(x, a, a) + G(y, a, a) + G(z, a, a)$

Definition 1.4 [9] *Let f, g be two self mappings of a metric space (X, d) . Then we say that f and g satisfy the property (E.A), if there exists a sequence $\{x_n\}$ in X such that $\lim_n f x_n = \lim_n g x_n = t$ for some $t \in X$.*

Definition 1.5 [4] *Let f, g, S, T be four self mappings defined on a symmetric space (X, d) . Then the pairs (f, S) and (g, T) are said to have the common limit range property (with respect to S and T) often denoted by $CLR_{(S,T)}$ property, if there exists two sequences $\{x_n\}$ and $\{y_n\}$ in X such that $\lim_n f x_n = \lim_n S x_n = \lim_n g y_n = \lim_n T y_n = t$ with $t = S u = T w$ for some $t, u, w \in X$.*

If $f = g$ and $S = T$, then the above definition implies CLR_g property due to Sintunavarat et al.[17].

2 Main Result

The first result is a common fixed point theorem for a pair of self mappings using a generalized strict contractive condition, which extend Theorem 1 of [9].

Theorem 2.1 *Let (X, G) be a symmetric G -Metric space and f, g be two weakly compatible self mappings on X satisfying*

1. CLR_g property.
2. $G(fx, fy, fz) < \max\left\{G(gx, gy, gz), \frac{G(fx, gx, gx) + G(fy, gy, gy) + G(fz, gz, gz)}{3}, \frac{G(fy, gx, gx) + G(fz, gy, gy) + G(fx, gz, gz)}{3}\right\} \forall x, y, z \in X$ with $x \neq y$.

Then f and g have a unique common fixed point.

Proof: Since f and g satisfies CLRg property, there exists a sequence $\{x_n\}$ in X such that $\lim_n fx_n = \lim_n gx_n = gx$ for some $x \in X$. Consider $G(fx_n, fx, fx) < \max\{G(gx_n, gx, gx), \frac{G(fx_n, gx_n, gx_n) + G(fx, gx, gx) + G(fx, gx, gx)}{3}, \frac{G(fx, gx_n, gx_n) + G(fx, gx, gx) + G(fx_n, gx, gx)}{3}\}$

Letting $n \rightarrow \infty$, we obtain $G(gx, fx, fx) \leq \frac{2}{3}G(gx, fx, fx)$ which implies $gx = fx$. Thus x is the coincidence point of f and g . Let $z = fx = gx$.

Since (f, g) are weakly compatible, we have $fz = fgz = gfgz = gz$.

Now we will prove that $fz = z$. Suppose $fz \neq z$, then

$$G(fz, z, z) = G(fz, fx, fx) < \max\{G(gz, gx, gx), \frac{G(fz, gz, gz) + G(fx, gx, gx) + G(fx, gx, gx)}{3}, \frac{G(fx, gz, gz) + G(fx, gx, gx) + G(fz, gx, gx)}{3}\} < G(fz, z, z),$$

which is a contradiction.

Hence $fz = z = gz$. Thus z is the common fixed point of f and g . The uniqueness of the fixed point can be proved easily.

We now illustrate this theorem by giving an example.

Example 1: Let $X = [2, 20]$ and $G : X \times X \times X \rightarrow [0, \infty)$ defined by $G(x, y, z) = 0$ if $x = y = z$ and $G(x, y, z) = \max\{x, y, z\}$ in all other cases. Then (X, G) is a symmetric G-Metric space. Let f, g be two self maps on X defined by

$$fx = 5 \text{ if } x \leq 5, \quad fx = 3 \text{ if } x > 5 \text{ and } gx = \frac{x+5}{2} \text{ if } x \leq 5, \quad gx = 10 \text{ if } x > 5.$$

Here f and g satisfies the CLRg property. To see this, consider a sequence $\{x_n\} = \{5 - \frac{1}{n}\} \forall n$. Then $fx_n = f(5 - \frac{1}{n}) \rightarrow 5$ and $gx_n = g(5 - \frac{1}{n}) = \frac{5 - \frac{1}{n} + 5}{2} \rightarrow 5$. Therefore $\lim_n fx_n = \lim_n gx_n = 5 = g5$.

Further, (f, g) are weakly compatible and

$$G(fx, fy, fz) < \max\{G(gx, gy, gz), \frac{G(fx, gx, gx) + G(fy, gy, gy) + G(fz, gz, gz)}{3}, \frac{G(fy, gx, gx) + G(fz, gy, gy) + G(fx, gz, gz)}{3}\} \forall x, y, z \in X \text{ with } x \neq y.$$

Thus f and g satisfy all the conditions of Theorem 2.1 and have a unique common fixed point at $x = 5$.

In 1977, Mathkowski[8] introduced the Φ -map as the following:

Let Φ be the set of auxiliary functions ϕ such that $\phi : [0, \infty) \rightarrow [0, \infty)$ is a nondecreasing function satisfying $\lim_n \phi^n(t) = 0$ for all $t \in (0, \infty)$. If $\phi \in \Phi$, then ϕ is called a Φ -map. Further $\phi(t) < t$ for all $t \in (0, \infty)$ and $\phi(0) = 0$.

In the next result, we extracted a unique common fixed point for two pairs of self mappings which involves a ϕ -map under the lipschitz type of contractive condition. This result extend and generalize Theorem 2 of M.Aamri and El Moutawakil [9] and Theorem 2.1 of S Manro et al.[14].

Theorem 2.2 Let (X, G) be a symmetric G-Metric space and f, g, S, T be four self mappings on X such that

1. (f, S) and (g, T) satisfies $CLR_{(S, T)}$ property.
2. $G(fx, gy, gz) \leq \phi(\max\{G(Sx, Ty, Tz), G(Sx, gy, gz), G(Ty, gy, gz), G(gy, Ty, Tz)\}) \forall x, y, z \in X$.
3. (f, S) and (g, T) are weakly compatible.

Then f, g, S and T have a unique common fixed point.

Proof: Since (f, S) and (g, T) satisfies $CLR_{(S, T)}$ property, there exists two sequences $\{x_n\}$ and $\{y_n\}$ such that $\lim_n fx_n = \lim_n Sx_n = \lim_n gy_n = \lim_n Ty_n = t$ with $t = Sx = Ty$ for some $t, x, y \in X$. Consider,

$$G(fx, gy_n, gy_n) \leq \phi(\max\{G(Sx, Ty_n, Ty_n), G(Sx, gy_n, gy_n), G(Ty_n, gy_n, gy_n), G(gy_n, Ty_n, Ty_n)\})$$

on letting $n \rightarrow \infty$, we obtain $G(fx, t, t) \leq \phi(0) = 0$ which implies $fx = t = Sx$. Hence x is the coincidence point of f and S . Since (f, S) are weakly compatible, we have $ffx = fSx = Sfx = SSx$.

Now we prove that $Ty = gy$. Consider,

$$G(fx_n, gy, gy) \leq \phi(\max\{G(Sx_n, Ty, Ty), G(Sx_n, gy, gy), G(Ty, gy, gy), G(gy, Ty, Ty)\})$$

As $n \rightarrow \infty$, we have $G(t, gy, gy) \leq \phi(G(t, gy, gy))$ which implies $G(t, gy, gy) = 0$. Therefore $gy = t = Ty$. i.e. y is the coincidence point of g and T .

Since (g, T) are weakly compatible we have $ggy = gTy = Tgy = TTy$. Also note that $fx = Sx = gy = Ty = t$.

Now we prove that $ffx = fx$. Suppose $fx \neq ffx$, then

$$\begin{aligned} G(ffx, fx, fx) &= G(ffx, gy, gy) \\ &\leq \phi(\max\{G(Sfx, Ty, Ty), G(Sfx, gy, gy), G(Ty, gy, gy), G(gy, Ty, Ty)\}) \\ &< G(ffx, fx, fx), \text{ a contradiction.} \end{aligned}$$

Hence $ffx = fx = Sfx$, which implies fx is the common fixed point of f and S . Similarly one can prove gy is the common fixed point of g and T . Since $fx = gy, z = fx$ is the common fixed point of f, g, S and T . The uniqueness of the fixed point follows easily.

As a corollary of Theorem 2.2, we derive the following sharpened version of Theorem 2.1 contained in S.Manro[14], as conditions on the ranges of involved mappings are relatively lightened.

Corollary 2.3 Let (X, G) be a symmetric G -Metric space and f, g, S, T be four self mappings on X such that

1. (f, S) and (g, T) satisfies $CLR_{(S, T)}$ property.
2. $G(fx, gy, gy) \leq \phi(\max\{G(Sx, Ty, Ty), G(Sx, gy, gy), G(Ty, gy, gy), G(gy, Ty, Ty)\}) \forall x, y \in X$.

3. (f,S) and (g,T) are weakly compatible.

Then f, g, S and T have a unique common fixed point.

Proof: Put $z = y$ in Theorem 2.2.

By restricting f, g, S, T suitably, one can derive the corollaries involving two as well as three self mappings as follows:

Corollary 2.4 Let (X, G) be a symmetric G -Metric space and f, g, S be three self mappings on X such that

1. (f,S) and (g,S) satisfies CLR_S property.
2. $G(fx, gy, gz) \leq \phi(\max\{G(Sx, Sy, Sz), G(Sx, gy, gz), G(Sy, gy, gz), G(gy, Sy, Sz)\}) \forall x, y, z \in X$.
3. (f,S) and (g,S) are weakly compatible.

Then f, g and S have a unique common fixed point.

Proof: Follows from Theorem 2.2 by setting $S = T$.

We now demonstrate this theorem by the following example.

Example 2: Let $X = [0, 6]$ and $G : X \times X \times X \rightarrow [0, \infty)$ defined by $G(x, y, z) = 0$ if $x = y = z$ and $G(x, y, z) = \max\{x, y, z\}$ in all other cases. Then clearly (X, G) is a symmetric G -Metric space. Let f, g, S, T be four self maps on X defined by

$fx = 3$ if $x \leq 3$, $fx = 4$ if $x > 3$ and $Sx = 6 - x$ if $x \leq 3$, $Sx = 5$ if $x > 3$
 $gx = 4$ if $x < 3$, $gx = \frac{x+3}{2}$ if $x \geq 3$, and $Tx = 6$ if $x < 3$, $Tx = \frac{2x+3}{3}$ if $x \geq 3$.
 Now (f, S) and (g, T) satisfy the $CLR_{(S,T)}$ property. To see this, choose two sequences $\{x_n\} = \{3 - \frac{1}{n}\}$ and $\{y_n\} = \{3 + \frac{1}{n}\} \forall n$. Then $fx_n = f(3 - \frac{1}{n}) \rightarrow 3$,
 $Sx_n = S(3 - \frac{1}{n}) = 6 - (3 - \frac{1}{n}) \rightarrow 3$, $gy_n = g(3 + \frac{1}{n}) = \frac{3 + \frac{1}{n} + 3}{2} \rightarrow 3$ and
 $Ty_n = T(3 + \frac{1}{n}) = \frac{2(3 + \frac{1}{n}) + 3}{3} \rightarrow 3$. Therefore $\lim_n fx_n = \lim_n Sx_n = \lim_n gy_n = \lim_n Ty_n = t = 3$ with $3 = S3 = T3$. Also (f, S) and (g, T) are weakly compatible. Let $\phi : [0, \infty) \rightarrow [0, \infty)$ be a function defined by $\phi(t) = \frac{t}{2}, \forall t \in [0, \infty)$. Then $\phi(0) = 0$ and $0 < \phi(t) < t, \forall t \in (0, \infty)$.

Further, $G(fx, gy, gz) \leq \phi(\max\{G(Sx, Ty, Tz), G(Sx, gy, gz), G(Ty, gy, gz), G(gy, Ty, Tz)\}) \forall x, y, z \in X$.

Thus all the conditions of Theorem 2.2 are satisfied and $x = 3$ is the unique common fixed point of f, g, S and T .

The next two theorems involved with Hardy Roger's type of contractive condition for two pairs of self mappings, which extend the results contained in Theorem 2.8 of [10], Theorem 3.1 of [7] and Theorem 2.2 of [10], Theorem 3.11 of [18].

Theorem 2.5 *Let (X, G) be a G -Metric space and f, g, S, T be four self mappings on X such that*

1. (f, S) and (g, T) satisfies $CLR_{(S, T)}$ property.
2. $G(fx, gy, gz) \leq pG(fx, Sx, Sx) + qG(Sx, Ty, Ty) + rG(Ty, gz, gz) + t[G(fx, Ty, Ty) + G(Sx, gy, gz)], \forall x, y, z \in X$
where $p, q, r, t \in [0, 1)$ satisfying $p + q + r + 2t < 1$.

Then (f, S) and (g, T) have a unique point of coincidence in X . Moreover, if (f, S) and (g, T) are weakly compatible, then f, g, S and T have a unique common fixed point.

Proof: Since (f, S) and (g, T) satisfies $CLR_{(S, T)}$ property, there exists two sequences $\{x_n\}$ and $\{y_n\}$ such that $\lim_n fx_n = \lim_n Sx_n = \lim_n gy_n = \lim_n Ty_n = u$ with $u = Sx = Ty$ for some $u, x, y \in X$. Consider

$$G(fx, gy_n, gy_n) \leq pG(fx, Sx, Sx) + qG(Sx, Ty_n, Ty_n) + rG(Ty_n, gy_n, gy_n) + t[G(fx, Ty_n, Ty_n) + G(Sx, gy_n, gy_n)]$$

On letting $n \rightarrow \infty$, we obtain $[1 - (p + t)]G(fx, u, u) \leq 0$ which gives $fx = u = Sx$, since $p + q + r + 2t < 1$.

Hence x is the coincidence point of f and S . Similarly y is the coincidence point of g and T . Thus $u = fx = Sx = gy = Ty$.

Uniqueness of coincidence point:

Let u_1 and u_2 be two points of coincidence of (f, S) and (g, T) .

$$\Rightarrow u_1 = fx_1 = Sx_1 = gy_1 = Ty_1 \text{ and } u_2 = fx_2 = Sx_2 = gy_2 = Ty_2. \text{ Consider } G(u_1, u_1, u_2) = G(fx_1, gy_2, gy_2) \leq pG(fx_1, Sx_1, Sx_1) + qG(Sx_1, Ty_2, Ty_2) + rG(Ty_2, gy_2, gy_2) + t[G(fx_1, Ty_2, Ty_2) + G(Sx_1, gy_2, gy_2)]$$

which implies $[1 - (q + 2t)]G(u_1, u_1, u_2) \leq 0$ i.e. $u_1 = u_2$.

Since (f, S) and (g, T) are weakly compatible, we have

$$ffx = fSx = Sfx = SSx \text{ and } ggy = gTy = Tgy = TTy.$$

Now we prove that $ffx = fx$. Consider

$$G(ffx, fx, fx) = G(ffx, gy, gy) \leq pG(ffx, Sfx, Sfx) + qG(Sfx, Ty, Ty) + rG(Ty, gy, gy) + t[G(ffx, Ty, Ty) + G(Sfx, gy, gy)]$$

which gives $[1 - (q + 2t)]G(ffx, fx, fx) \leq 0$. Hence $fx = ffx = Sfx$.

i.e. fx is the common fixed point of f and S . Similarly we can prove gy is the common fixed point of g and T . Hence $z = fx$ is the common fixed point of f, g, S and T . The uniqueness of the fixed point can be proved easily.

We now furnish an example to illustrate Theorem 2.5.

Example 3: Let $X = [0, 4]$ and $G : X \times X \times X \rightarrow [0, \infty)$ defined by $G(x, y, z) = \max\{d(x, y), d(y, z), d(z, x)\}$, where d is the usual metric on X . Then clearly (X, G) is a G-Metric space. Let f, g, S, T be four self maps on X defined by

$$fx = 2, \quad Sx = 4 - x, \quad gx = \frac{5x+12}{11} \quad \text{and} \quad Tx = \frac{x+2}{2} \quad \forall x \in X.$$

Now (f, S) and (g, T) satisfy the $CLR_{(S,T)}$ property. To see this, choose two sequences $\{x_n\} = \{2 + \frac{1}{n}\}$ and $\{y_n\} = \{2 - \frac{1}{n}\} \forall n$. Then $fx_n = f(2 + \frac{1}{n}) \rightarrow 2$, $Sx_n = S(2 + \frac{1}{n}) = 4 - (2 + \frac{1}{n}) \rightarrow 2$, $gy_n = g(2 - \frac{1}{n}) = \frac{5(2 - \frac{1}{n}) + 12}{11} \rightarrow 2$ and $Ty_n = T(2 - \frac{1}{n}) = \frac{2 - \frac{1}{n} + 2}{2} \rightarrow 2$. Therefore $\lim_n fx_n = \lim_n Sx_n = \lim_n gy_n = \lim_n Ty_n = t = 2$ with $2 = S2 = T2$. Further, (f, S) and (g, T) are weakly compatible and f, g, S and T satisfy the contractive condition (2) for $p = \frac{1}{8}, q = \frac{1}{3}, r = \frac{1}{8}, t = \frac{1}{7}$. Thus all the conditions of Theorem 2.5 are satisfied and $x = 2$ is the unique common fixed point of f, g, S and T .

Theorem 2.6 Let (X, G) be a G-Metric space and f, g, S, T be four self mappings on X such that

1. (f, S) and (g, T) satisfies $CLR_{(S,T)}$ property.
2. $G(fx, gy, gz) \leq hu(x, y, z)$ where $h \in (0, 1)$ and $\forall x, y, z \in X$
 $u(x, y, z) \in \left\{ G(fx, Sx, Sx), G(Sx, Ty, Ty), G(Ty, gz, gz), \right.$
 $\left. \frac{G(fx, Ty, Tz) + G(Sx, gy, gz)}{2} \right\}$.
3. (f, S) and (g, T) are weakly compatible

Then f, g, S and T have a unique common fixed point.

Proof: Since (f, S) and (g, T) satisfies $CLR_{(S,T)}$ property, there exists two sequences $\{x_n\}$ and $\{y_n\}$ such that $\lim_n fx_n = \lim_n Sx_n = \lim_n gy_n = \lim_n Ty_n = t$ with $t = Sx = Ty$ for some $t, x, y \in X$.

Consider $G(fx, gy_n, gy_n) \leq hu(x, y_n, y_n)$

where $u(x, y_n, y_n) \in \left\{ G(fx, Sx, Sx), G(Sx, Ty_n, Ty_n), G(Ty_n, gy_n, gy_n), \right.$
 $\left. \frac{G(fx, Ty_n, Ty_n) + G(Sx, gy_n, gy_n)}{2} \right\}$

On letting $n \rightarrow \infty$, we obtain

$$G(fx, t, t) \leq hu(x, y_n, y_n), \text{ where } u(x, y_n, y_n) \in \left\{ G(fx, t, t), \frac{G(fx, t, t)}{2} \right\}.$$

If $u(x, y_n, y_n) = G(fx, t, t)$, then $G(fx, t, t) \leq hG(fx, t, t)$ which gives $fx = t = Sx$. If $u(x, y_n, y_n) = \frac{G(fx, t, t)}{2}$, then $G(fx, t, t) \leq h \frac{G(fx, t, t)}{2}$ which also gives $fx = t = Sx$.

Therefore in both the cases $fx = Sx = t$. Hence x is the coincidence point of f and S . Similarly y is the coincidence point of g and T . Thus $t = fx = Sx = gy = Ty$.

Since (f, S) and (g, T) are weakly compatible, we have

$$ffx = fSx = Sfx = SSx \text{ and } ggy = gTy = Tgy = TTy.$$

Now we prove that $ffx = fx$.

Consider $G(ffx, fx, fx) = G(ffx, gy, gy) \leq hu(fx, y, y)$,

where $u(fx, y, y) \in \left\{ G(ffx, Sfx, Sfx), G(Sfx, Ty, Ty), G(Ty, gy, gy), \frac{G(ffx, Ty, Ty) + G(Sfx, gy, gy)}{2} \right\}$

i.e. $u(fx, y, y) = G(ffx, fx, fx)$.

Therefore $G(ffx, fx, fx) \leq hG(ffx, fx, fx)$ which implies $fx = ffx = Sfx$.

Hence fx is the common fixed point of f and S . Similarly we can prove gy is the common fixed point of g and T . Since $fx = gy$, $z = fx$ is the common fixed point of f, g, S and T . The uniqueness of the fixed point can be proved easily.

Example 4: Let $X = [0, 4]$ and $G : X \times X \times X \rightarrow [0, \infty)$ defined by $G(x, y, z) = \max\{d(x, y), d(y, z), d(z, x)\}$, where d is the usual metric on X . Then clearly (X, G) is a G-Metric space. Let f, g, S, T be four self maps on X defined by

$$fx = 3, Sx = x, gx = \frac{x+24}{9} \text{ and } Tx = \frac{x+3}{2} \quad \forall x \in X.$$

Now (f, S) and (g, T) satisfy the $CLR_{(S,T)}$ property. To see this, choose two sequences $\{x_n\} = \{3 + \frac{1}{n}\}$ and $\{y_n\} = \{3 - \frac{1}{n}\} \forall n$. Then $fx_n = f(3 + \frac{1}{n}) \rightarrow 3$, $Sx_n = S(3 + \frac{1}{n}) = 3 + \frac{1}{n} \rightarrow 3$, $gy_n = g(3 - \frac{1}{n}) = \frac{3 - \frac{1}{n} + 24}{9} \rightarrow 3$ and $Ty_n = T(3 - \frac{1}{n}) = \frac{3 - \frac{1}{n} + 3}{2} \rightarrow 3$. Therefore $\lim_n fx_n = \lim_n Sx_n = \lim_n gy_n = \lim_n Ty_n = t = 3$ with $3 = S3 = T3$. Further, (f, S) and (g, T) are weakly compatible and f, g, S and T satisfies the contractive condition (2) for $h = \frac{1}{2}$. Thus all the conditions of Theorem 2.6 are satisfied and $x = 3$ is the unique common fixed point of f, g, S and T .

Our last result is also a common fixed point theorem but for expansive type of contractive condition, which extend and improve the results of Theorem 2.1 of [16] and Theorem 3.1 of [18].

Theorem 2.7 *Let f, g be two self maps of a G-Metric space (X, G) satisfying CLR_g property and*

$G(gx, gy, gz) \geq aG(fx, fy, fz) + bG(fx, gx, gx) + cG(fy, gy, gy) + eG(fz, gz, gz) \forall x, y, z \in X$ where $a, b, c, e > 0$. Then f and g have a coincidence point. If $a > 1$, then the coincidence point is unique. Moreover, if f and g are weakly compatible, then they have a unique common fixed point.

Proof: Since f and g satisfies CLR_g property, there exist a sequence $\{x_n\}$ in X such that $\lim_n fx_n = \lim_n gx_n = gx$ for some $x \in X$.

$$\text{Consider } G(gx_n, gx, gx) \geq aG(fx_n, fx, fx) + bG(fx_n, gx_n, gx_n) + cG(fx, gx, gx) + eG(fx, gx, gx).$$

On letting $n \rightarrow \infty$, we obtain $(\frac{a}{2} + c + e)G(fx, gx, gx) \leq 0$ which implies $fx = gx$. Thus x is the coincidence point of f and g .

Uniqueness of the coincidence point:

Let $z = fx = gx$ and $w = fy = gy$ be the two points of coincidence of f and g . Then, $G(z, w, w) = G(gx, gy, gy)$

$$\geq aG(fx, fy, fy) + bG(fx, gx, gx) + cG(fy, gy, gy) + eG(fy, gy, gy)$$

i.e. $(a - 1)G(z, w, w) \leq 0$. Since $a > 1$, we get $z = w$.

Now (f, g) are weakly compatible implies $ffx = fgx = gfx = ggx$.

To prove that $fx = ffx$. Consider

$$G(ffx, fx, fx) = G(gfx, gx, gx)$$

$$\geq aG(ffx, fx, fx) + bG(ffx, gfx, gfx) + cG(fx, gx, gx) + eG(fx, gx, gx)$$

which implies $ffx = fx = gfx$. Hence fx is the common fixed point of f and g . The uniqueness of the fixed point can be proved easily.

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