

## Research Article

# A Modified Halpern's Iterative Scheme for Solving Split Feasibility Problems

**Jitsupa Deepho and Poom Kumam**

*Department of Mathematics, Faculty of Science, King Mongkut's University of Technology Thonburi, Bangkok 10140, Thailand*

Correspondence should be addressed to Poom Kumam, [poom.kum@kmutt.ac.th](mailto:poom.kum@kmutt.ac.th)

Received 4 May 2012; Accepted 13 September 2012

Academic Editor: Hong-Kun Xu

Copyright © 2012 J. Deepho and P. Kumam. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

The purpose of this paper is to introduce and study a modified Halpern's iterative scheme for solving the split feasibility problem (SFP) in the setting of infinite-dimensional Hilbert spaces. Under suitable conditions a strong convergence theorem is established. The main result presented in this paper improves and extends some recent results done by Xu (Iterative methods for the split feasibility problem in infinite-dimensional Hilbert space, *Inverse Problem* 26 (2010) 105018) and some others.

## 1. Introduction

Let  $C$  and  $Q$  be nonempty-closed convex subsets of real Hilbert spaces  $H_1$  and  $H_2$ , respectively. Let  $A$  be a linear-bounded operator from  $H_1$  to  $H_2$ . The split feasibility problem (SFP) is finding a point  $\hat{x}$  satisfying the following property:

$$\hat{x} \in C, \quad A\hat{x} \in Q. \quad (1.1)$$

The SFP was introduced by Censor and Elfving [1] for modeling inverse problems which arise from phase retrievals and medical image reconstruction [2], and very well-known iterative algorithms have been invented to solve it [2].

We use  $\Gamma$  to denote the solution set of SFP:

$$\Gamma = \{\hat{x} \in C : A\hat{x} \in Q\}, \quad (1.2)$$

and assume that the SFP (1.1) is consistent (i.e., (1.1) has a solution) so that  $\Gamma$  is closed, convex, and nonempty, it is not hard to see that  $x \in C$  solves (1.1) if and only if it solves the following fixed point equation;

$$x = P_C(I - \gamma A^*(I - P_Q)A)x, \quad x \in C, \quad (1.3)$$

where  $P_C$  and  $P_Q$  are the (orthogonal) projections onto  $C$  and  $Q$ , respectively,  $\gamma > 0$  is any positive constant and  $A^*$  denotes the adjoint of  $A$ . Moreover, for sufficiently small  $\gamma > 0$ , the operator  $P_C(I - \gamma A^*(I - P_Q)A)$  which defines the fixed point equation in (1.3) is nonexpansive.

To solve the SFP (1.1), Byrne [2] proposed his  $CQ$  algorithm (see also [3]) which generates a sequence  $\{x_n\}$  by

$$x_{n+1} = P_C(I - \gamma A^*(I - P_Q)A)x_n, \quad n \geq 0, \quad (1.4)$$

where  $\gamma \in (0, 2/\lambda)$  with  $\lambda$  being the spectral radius of the operator  $A^*A$ .

Very recently, Xu [4] has viewed the  $CQ$  algorithm for averaged mappings and applied Mann's algorithm to solving the SFP, and he also proved that an averaged  $CQ$  algorithm is weakly convergent to a solution of the SFP.

In this paper, we also regard the  $CQ$  algorithm as a fixed point algorithm for averaged mappings and try to study the SFP by the following modified Halpern's iterative scheme;

$$x_{n+1} = \alpha_n u + \beta_n x_n + \gamma_n P_C(I - \xi A^*(I - P_Q)A)x_n, \quad n \geq 0, \quad (1.5)$$

where  $\{\alpha_n\}$ ,  $\{\beta_n\}$ , and  $\{\gamma_n\}$  are three sequences in  $[0, 1]$  satisfying  $\alpha_n + \beta_n + \gamma_n = 1$ . Furthermore, our result extends and improves the result of Xu [4] from weak to strong convergence theorems.

## 2. Preliminaries

Throughout the paper, we adopt the following notation.

Let  $x_n$  be a sequence and  $x$  be a point in a normed space  $X$ . We use  $x_n \rightarrow x$  and  $x_n \rightharpoonup x$  to denote strong and weak convergence to  $x$  of the sequence  $\{x_n\}$ , respectively. In addition, we use  $\omega_w(x_n)$  to denote the weak  $\omega$ -limit set of the sequence  $\{x_n\}$ ; namely,

$$\omega_w(x_n) := \{x : x_{n_i} \rightharpoonup x \text{ for some subsequence } \{x_{n_i}\} \text{ of } \{x_n\}\}. \quad (2.1)$$

Let  $H$  be a real Hilbert space with inner product  $\langle \cdot, \cdot \rangle$  and norm  $\|\cdot\|$ , respectively, and let  $K$  be a nonempty-closed convex subset of  $H$ . For every point  $x \in H$ , there exists a unique nearest point in  $K$ , denoted by  $P_K x$ , such that

$$\|x - P_K x\| \leq \|x - y\|, \quad \forall y \in K, \quad (2.2)$$

$P_K$  is called the metric projection of  $H$  onto  $K$ . It is well known that  $P_K$  is a nonexpansive mapping of  $H$  onto  $K$  and satisfies

$$\langle x - y, P_K x - P_K y \rangle \geq \|P_K x - P_K y\|^2, \quad (2.3)$$

for every  $x, y \in H$ . Moreover,  $P_K x$  is characterized by the following properties:  $P_K x \in K$  and

$$\begin{aligned} \langle x - P_K x, y - P_K x \rangle &\leq 0, \\ \|x - y\|^2 &\geq \|x - P_K x\|^2 + \|y - P_K x\|^2, \end{aligned} \quad (2.4)$$

for all  $x \in H, y \in K$ .

Some important properties of projections are gathered in the following proposition.

**Proposition 2.1.** *Given  $x \in H$  and  $z \in K$ . Then  $z = P_K x$  if and only if*

$$\langle x - z, y - z \rangle \leq 0, \quad \forall y \in K. \quad (2.5)$$

One also needs other sorts of nonlinear operators which are introduced below.

Let  $T, A : H \rightarrow H$  be the nonlinear operators.

- (1)  $T$  is nonexpansive if  $\|Tx - Ty\| \leq \|x - y\|$  for all  $x, y \in H$ .
- (2)  $T$  is firmly nonexpansive if  $2T - I$  is nonexpansive. Equivalent,  $T = (I + S)/2$ , where  $S : H \rightarrow H$  is nonexpansive. Alternatively,  $T$  is firmly nonexpansive if and only if

$$\langle x - y, Tx - Ty \rangle \geq \|Tx - Ty\|^2, \quad x, y \in H. \quad (2.6)$$

- (3)  $T$  is averaged if  $T = (1 - \alpha)I + \alpha S$ , where  $\alpha \in (0, 1)$  and  $S : H \rightarrow H$  is nonexpansive. In this case, one also says that  $T$  is  $\alpha$ -averaged. A firmly nonexpansive mapping is  $(1/2)$ -averaged.
- (4)  $A$  is monotone if  $\langle Ax - Ay, x - y \rangle \geq 0$  for  $x, y \in H$ .
- (5)  $A$  is  $\beta$ -strongly monotone, with  $\beta > 0$ , if

$$\langle x - y, Ax - Ay \rangle \geq \beta \|x - y\|^2, \quad x, y \in H. \quad (2.7)$$

- (6)  $A$  is  $\nu$ -inverse strongly monotone ( $\nu$ -ism), with  $\nu > 0$ , if

$$\langle x - y, Ax - Ay \rangle \geq \nu \|Ax - Ay\|^2, \quad x, y \in H. \quad (2.8)$$

It is well known that both  $P_K$  and  $I - P_K$  are firmly nonexpansive and  $(1/2)$ -ism.

Denote by  $\text{Fix}(T)$  the set of fixed points of a self-mapping  $T$  defined on  $H$ , (i.e.,  $\text{Fix}(T) = \{x \in H : Tx = x\}$ ).

**Proposition 2.2** (see [2, 5]). *One has the following assertions.*

- (1)  *$T$  is nonexpansive if and only if the complement  $I - T$  is  $(1/2)$ -ism.*
- (2) *If  $T$  is  $\nu$ -ism and  $\gamma > 0$ , then  $\gamma T$  is  $(\nu/\gamma)$ -ism.*
- (3)  *$T$  is averaged if and only if the complement  $I - T$  is  $\nu$ -ism, for some  $\nu > (1/2)$ .*

*Indeed, for  $\alpha \in (0, 1)$ ,  $T$  is  $\alpha$ -averaged if and only if  $I - T$  is  $(1/2\alpha)$ -ism.*

- (4) *If  $T_1$  is  $\alpha_1$ -averaged and  $T_2$  is  $\alpha_2$ -averaged, where  $\alpha_1, \alpha_2 \in (0, 1)$ , then the composite  $T_1 T_2$  is  $\alpha$ -averaged, where  $\alpha = \alpha_1 + \alpha_2 - \alpha_1 \alpha_2$ .*
- (5) *If  $T_1$  and  $T_2$  are averaged and have a common fixed point, then  $\text{Fix}(T_1 T_2) = \text{Fix}(T_1) \cap \text{Fix}(T_2)$ .*

**Lemma 2.3** (see [6]). *Let  $K$  be a nonempty-closed convex subset of a real Hilbert space  $H$  and  $T$  be nonexpansive mapping on  $K$  with  $\text{Fix}(T) \neq \emptyset$ . If  $\{x_n\}$  is a sequence in  $K$  which converges weakly to  $x$  and if  $\{(I - T)x_n\}$  converges strongly to  $y$ , then  $y = (I - T)x$ . In particular, if  $y = 0$ , then  $x \in \text{Fix}(T)$ .*

**Lemma 2.4** (see [7]). *Let  $(E, \langle \cdot, \cdot \rangle)$  be an inner product space. Then for all  $x, y, z \in E$  and  $\alpha_n, \beta_n, \gamma_n \in [0, 1]$  with  $\alpha_n + \beta_n + \gamma_n = 1$ , one has*

$$\|\alpha x + \beta y + \gamma z\|^2 = \alpha \|x\|^2 + \beta \|y\|^2 + \gamma \|z\|^2 - \alpha\beta \|x - y\|^2 - \alpha\gamma \|x - z\|^2 - \beta\gamma \|y - z\|^2. \quad (2.9)$$

**Lemma 2.5** (see [8]). *Assume that  $\{a_n\}$  is a sequence of nonnegative real numbers such that*

$$a_{n+1} \leq (1 - \gamma_n) a_n + \delta_n, \quad (2.10)$$

*where  $\{\gamma_n\}$  is a sequence in  $(0, 1)$  and  $\{\delta_n\}$  is a sequence such that*

- (1)  $\sum_{n=0}^{\infty} \gamma_n = \infty$ ;
- (2)  $\limsup_{n \rightarrow \infty} \delta_n / \gamma_n \leq 0$  or  $\sum_{n=0}^{\infty} |\delta_n| < \infty$ .

*Then,  $\lim_{n \rightarrow \infty} a_n = 0$ .*

### 3. Main Result

Let  $C$  be a nonempty closed and convex subset of a Hilbert space  $H$ . For any  $u, x_0 \in C$ , we define the sequence  $\{x_n\}$  by

$$x_{n+1} = \alpha_n u + \beta_n x_n + \gamma_n P_C(I - \xi A^*(I - P_Q)A)x_n, \quad n \geq 0, \quad (3.1)$$

where  $\{\alpha_n\}$ ,  $\{\beta_n\}$ , and  $\{\gamma_n\}$  are three sequences in  $[0, 1]$  and satisfy  $\alpha_n + \beta_n + \gamma_n = 1$ .

**Theorem 3.1.** *Suppose that the SFP is consistent and  $0 < \xi < (2/\|A\|^2)$ . Let  $\{x_n\}$  be a sequence defined as in (3.1). If the following assumptions are satisfied:*

(C1)  $\lim_{n \rightarrow \infty} \alpha_n = 0$  but  $\sum_{n=1}^{\infty} \alpha_n = \infty$ ,

(C2)  $\limsup_{n \rightarrow \infty} \beta_n < 1$ ,

(C3) the sums  $\sum_{n=1}^{\infty} |\alpha_{n+1} - \alpha_n|$ ,  $\sum_{n=1}^{\infty} |\beta_{n+1} - \beta_n|$  and  $\sum_{n=1}^{\infty} |\gamma_{n+1} - \gamma_n|$  are finite.

Then  $\{x_n\}$  converges strongly to a solution of the SFP (1.1).

*Proof.* We firstly show that the sequence  $\{x_n\}$  is bounded. For our convenience, we take  $T := P_C(I - \xi A^*(I - P_Q)A)$ . Then, for any  $x^* \in \Gamma$ , we have  $Tx^* = x^*$ . Now, we observe that

$$\begin{aligned} \|x_{n+1} - x^*\| &\leq \|\alpha_n u + \beta_n x_n + \gamma_n T x_n - x^*\| \\ &\leq \alpha_n \|u - x^*\| + \beta_n \|x_n - x^*\| + \gamma_n \|T x_n - x^*\|. \end{aligned} \quad (3.2)$$

Now, we note that the condition  $0 < \xi < (2/\|A\|^2)$  implies that the operator  $P_C(I - \xi A^*(I - P_Q)A)$  is averaged. Since  $I - P_Q$  is firmly nonexpansive mappings and so is  $(1/2)$ -average, which is 1-ism. Also observe that  $A^*(I - P_Q)A$  is  $(1/\|A\|^2)$ -ism so that  $\xi A^*(I - P_Q)A$  is  $(1/\xi\|A\|^2)$ -ism. Further, from the fact that  $I - \xi A^*(I - P_Q)A$  is  $(\xi\|A\|^2/2)$ -averaged and  $P_C$  is  $(1/2)$ -averaged, we may obtain that  $P_C(I - \xi A^*(I - P_Q)A)$  is  $\chi$ -averaged, where

$$\chi = \frac{1}{2} + \frac{\xi\|A\|^2}{2} - \frac{1}{2} \cdot \frac{\xi\|A\|^2}{2} = \frac{2 + \xi\|A\|^2}{4}. \quad (3.3)$$

This implies that  $T = \chi I + (1 - \chi)S$ , where  $\chi = (2 + \xi\|A\|^2/4) \in (0, 1)$  for some nonexpansive mappings  $S$ . Note that  $T$  is also nonexpansive mappings. Hence, we have

$$\|T x_n - x^*\| = \|T x_n - T x^*\| \leq \|x_n - x^*\|. \quad (3.4)$$

From the inequalities (3.2) and (3.4), we have

$$\begin{aligned} \|x_{n+1} - x^*\| &\leq \alpha_n \|u - x^*\| + (1 - \alpha_n) \|x_n - x^*\| \\ &\leq \max\{\|u - x^*\|, \|x_n - x^*\|\}. \end{aligned} \quad (3.5)$$

Continuing inductively, we may obtain that the inequality

$$\|x_{n+1} - x^*\| \leq \max\{\|u - x^*\|, \|x_0 - x^*\|\}, \quad (3.6)$$

holds for all  $n \geq 0$ . So,  $\{x_n\}$  is bounded so does  $\{T x_n\}$ .

Next, we will show that  $\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = 0$ . Observe that

$$\begin{aligned}
\|x_{n+1} - x_n\| &= \|(\alpha_n u + \beta_n x_n + \gamma_n T x_n) - (\alpha_{n-1} u + \beta_{n-1} x_{n-1} + \gamma_{n-1} T x_{n-1})\| \\
&\leq \|(\alpha_n u + \beta_n x_n + \gamma_n T x_n) - (\alpha_n u + \beta_n x_{n-1} + \gamma_n T x_{n-1})\| \\
&\quad + \|(\alpha_n u + \beta_n x_{n-1} + \gamma_n T x_{n-1}) - (\alpha_{n-1} u + \beta_{n-1} x_{n-1} + \gamma_{n-1} T x_{n-1})\| \quad (3.7) \\
&\leq (1 - \alpha_n) \|x_n - x_{n-1}\| + |\alpha_n - \alpha_{n-1}| \|u\| + |\beta_n - \beta_{n-1}| \|x_{n-1}\| \\
&\quad + |\gamma_n - \gamma_{n-1}| \|T x_{n-1}\|.
\end{aligned}$$

Since  $\{x_n\}$  and  $\{T x_n\}$  are bounded, there exists  $M = \sup(\|u\|, \|x_{n+1}\|, \|T x_{n-1}\|) > 0$  such that

$$\|x_{n+1} - x_n\| \leq (1 - \alpha_n) \|x_n - x_{n-1}\| + M(|\alpha_n - \alpha_{n-1}| + |\beta_n - \beta_{n-1}| + |\gamma_n - \gamma_{n-1}|). \quad (3.8)$$

According to Lemma 2.5 and the condition (C3), we have  $\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = 0$ .

We note that

$$\begin{aligned}
\|x_n - T x_n\| &\leq \|x_n - x_{n+1}\| + \|x_{n+1} - T x_n\| \\
&\leq \|x_n - x_{n+1}\| + \|\alpha_n u + \beta_n x_n + (1 - \alpha_n - \beta_n) T x_n - T x_n\| \\
&= \|x_n - x_{n+1}\| + \|\alpha_n(u - T x_n) + \beta_n(x_n - T x_n)\| \quad (3.9) \\
&\leq \|x_n - x_{n+1}\| + \alpha_n \|u - T x_n\| + \beta_n \|x_n - T x_n\| \\
&= \frac{1}{1 - \beta_n} \|x_{n+1} - x_n\| + \frac{\alpha_n}{1 - \beta_n} \|u - T x_n\|.
\end{aligned}$$

Consequently, by the condition (C1) and (C2), we also have  $\lim_{n \rightarrow \infty} \|x_n - T x_n\| = 0$ . Next, we will show that

$$\limsup_{n \rightarrow \infty} \langle v - z_0, x_{n+1} - z_0 \rangle \leq 0, \quad \text{where } z_0 = P_\Gamma v. \quad (3.10)$$

To show this, we can choose a subsequence  $\{x_{n_k}\}$  of  $\{x_n\}$  such that

$$\limsup_{n \rightarrow \infty} \langle v - z_0, T x_n - z_0 \rangle = \lim_{k \rightarrow \infty} \langle v - z_0, T x_{n_k} - z_0 \rangle. \quad (3.11)$$

As  $\{x_n\}$  is bounded, there exists a subsequence  $\{x_{n_k}\}$  which converges weakly to  $z$ . We may assume without loss of generality that  $x_{n_k} \rightharpoonup z$ . Since  $\|T x_n - x_n\| \rightarrow 0$ , we obtain  $T x_{n_k} \rightharpoonup z$  as  $k \rightarrow \infty$ . By Lemma 2.3, we obtain that  $z \in \text{Fix}(T) = \Gamma$ .

Now from (2.4), observe that

$$\begin{aligned}
\limsup_{n \rightarrow \infty} \langle v - z_0, x_n - z_0 \rangle &= \limsup_{n \rightarrow \infty} \langle v - z_0, Tx_n - z_0 \rangle \\
&= \lim_{k \rightarrow \infty} \langle v - z_0, Tx_{n_k} - z_0 \rangle \\
&= \langle v - z_0, z - z_0 \rangle \leq 0.
\end{aligned} \tag{3.12}$$

Therefore, we compute

$$\begin{aligned}
\|x_{n+1} - z_0\|^2 &= \langle \alpha_n v + \beta_n x_n + \gamma_n Tx_n - z_0, x_{n+1} - z_0 \rangle \\
&= \alpha_n \langle v - z_0, x_{n+1} - z_0 \rangle + \beta_n \langle x_n - z_0, x_{n+1} - z_0 \rangle + \gamma_n \langle Tx_n - z_0, x_{n+1} - z_0 \rangle \\
&\leq \alpha_n \langle v - z_0, x_{n+1} - z_0 \rangle + \frac{1}{2} \beta_n (\|x_n - z_0\|^2 + \|x_{n+1} - z_0\|^2) \\
&\quad + \frac{1}{2} \gamma_n (\|x_n - z_0\|^2 + \|x_{n+1} - z_0\|^2) \\
&\leq \alpha_n \langle v - z_0, x_{n+1} - z_0 \rangle + \frac{1}{2} (1 - \alpha_n) (\|x_n - z_0\|^2 + \|x_{n+1} - z_0\|^2)
\end{aligned} \tag{3.13}$$

which implies that

$$\|x_{n+1} - z_0\|^2 \leq (1 - \alpha_n) (\|x_n - z_0\|^2) + 2\alpha_n \langle v - z_0, x_{n+1} - z_0 \rangle. \tag{3.14}$$

Finally, by (3.12), (3.14), and Lemma 2.5, we conclude that  $\{x_n\}$  converges to  $z_0$ . This completes the proof.  $\square$

Letting  $\beta_n \equiv 0$  of iterative scheme (3.1) in Theorem 3.1, then we obtain the following corollary.

**Corollary 3.2.** *For any  $u, x_0 \in C$ , one defines the sequence  $\{x_n\}$  by*

$$x_{n+1} = \alpha_n u + (1 - \alpha_n) P_C (I - \xi A^* (I - P_Q) A) x_n, \quad n \geq 0, \tag{3.15}$$

where  $\{\alpha_n\}$  is a sequence in  $[0, 1]$ . Suppose that the SFP is consistent and  $0 < \xi < (2/\|A\|^2)$ .

Let  $\{x_n\}$  be defined as in (3.15). If the following assumptions are satisfied:

$$(C1) \lim_{n \rightarrow \infty} \alpha_n = 0 \text{ but } \sum_{n=1}^{\infty} \alpha_n = \infty,$$

$$(C2) \sum_{n=1}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty.$$

Then  $\{x_n\}$  converges to a solution of the SFP (1.1).

**Remark 3.3.** Theorem 3.1 and Corollary 3.2 extend and improve the result of Xu [4] from weak to strong convergence theorems by using the modified Halpern's iterative scheme.

## Acknowledgment

The first author was supported by the Thailand Research Fund through the Royal Golden Jubilee Ph.D. Program (Grant no. PHD/0033/2554).

## References

- [1] Y. Censor and T. Elfving, "A multiprojection algorithm using Bregman projections in a product space," *Numerical Algorithms*, vol. 8, no. 2–4, pp. 221–239, 1994.
- [2] C. Byrne, "Iterative oblique projection onto convex sets and the split feasibility problem," *Inverse Problems*, vol. 18, no. 2, pp. 441–453, 2002.
- [3] Q. Yang, "The relaxed CQ algorithm solving the split feasibility problem," *Inverse Problems*, vol. 20, no. 4, pp. 1261–1266, 2004.
- [4] H.-K. Xu, "Iterative methods for the split feasibility problem in infinite-dimensional Hilbert spaces," *Inverse Problems*, vol. 26, no. 10, Article ID 105018, 2010.
- [5] H.-K. Xu, "Averaged mappings and the gradient-projection algorithm," *Journal of Optimization Theory and Applications*, vol. 150, no. 2, pp. 360–378, 2011.
- [6] F. E. Browder, "Fixed-point theorems for noncompact mappings in Hilbert space," *Proceedings of the National Academy of Sciences of the United States of America*, vol. 53, no. 6, pp. 1272–1276, 1965.
- [7] M. O. Osilike and D. I. Igbokwe, "Weak and strong convergence theorems for fixed points of pseudocontractions and solutions of monotone type operator equations," *Computers & Mathematics with Applications*, vol. 40, no. 4–5, pp. 559–567, 2000.
- [8] H.-K. Xu, "Viscosity approximation methods for nonexpansive mappings," *Journal of Mathematical Analysis and Applications*, vol. 298, no. 1, pp. 279–291, 2004.





# Hindawi

Submit your manuscripts at  
<http://www.hindawi.com>

