## Research Article

# Large Solutions of Quasilinear Elliptic System of Competitive Type: Existence and Asymptotic Behavior 

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We study the existence and asymptotic behavior of positive solutions for a class of quasilinear elliptic systems in a smooth boundary via the upper and lower solutions and the localization method. The main results of the present paper are new and extend some previous results in the literature.

## 1. Introduction

This paper is concerned with the study of positive boundary blow-up solutions to a quasilinear elliptic system of competitive type:

$$
\begin{gather*}
\Delta_{p} u=a(x) u^{a} v^{b} \quad \text { in } \Omega \\
\Delta_{p} v=b(x) u^{c} v^{e} \quad \text { in } \Omega  \tag{1.1}\\
u=v=+\infty \quad \text { on } \partial \Omega
\end{gather*}
$$

where $\Omega$ is a bounded $C^{2}$ domain of $\mathbf{R}^{\mathbf{N}}$ and $\Delta_{p}$ stands for the $p$-Laplacian operator defined by $\Delta_{p} u=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right), p>1$. The exponents $a, b, c, e$ verify $a, e>p-1, b, c>0,(a-p+$ 1) $(e-p+1)>b c$. There exists $C(x), D(x) \in C\left(\bar{\Omega}, R^{+}\right), \gamma(x), \eta(x) \in C\left(\bar{\Omega}, R^{+}\right)$such that

$$
\begin{equation*}
\lim _{x \rightarrow x_{0}} \frac{a(x)}{C\left(x_{0}\right) d(x)^{r\left(x_{0}\right)}}=1, \quad \lim _{x \rightarrow x_{0}} \frac{b(x)}{D\left(x_{0}\right) d(x)^{\eta\left(x_{0}\right)}}=1, \tag{1.2}
\end{equation*}
$$

where $x_{0} \in \partial \Omega, d(x)=\operatorname{dist}(x, \partial \Omega)$.

We must emphasize that the weight functions $a(x), b(x)$ are allowed decaying to zero on $\Omega$ with arbitrary rate, depending upon the particular point of $\partial \Omega$. The boundary condition is to be understood $u(x) \rightarrow \infty, v(x) \rightarrow \infty$ as $d(x) \rightarrow 0^{+}$. Problems like (1.1) are usually known in the literature as boundary blow-up problems, and their solutions are also named large solutions or boundary blow-up solutions.

The problem of the previous form is mathematical models occuring in studies of the $p$-Laplace system, generalized reaction-diffusion theory, non-Newtonian fluid theory [1, 2], non-Newtonian filtration [3], and the turbulent flow of a gas in porous medium. In the nonNewtonian fluid theory, the quantity $p$ is a characteristic of the medium. Media with $p>$ 2 are called dilatant fluids and those with $p<2$ are called pseudoplastics. If $p=2$, they are Newtonian fluids. When $p \neq 2$, the problem becomes more complicated since certain nice properties inherent to the case $p=2$ seem to be lost or at least difficult to verify. The main differences between $p=2$ and $p \neq 2$ can be founded in [4,5].

When $p=2$, system (1.1) becomes

$$
\begin{gather*}
\Delta u=a(x) u^{a} v^{b} \quad \text { in } \Omega \\
\Delta v=b(x) u^{c} v^{e} \quad \text { in } \Omega  \tag{1.3}\\
u=v=+\infty \quad \text { on } \partial \Omega
\end{gather*}
$$

for which the existence, uniqueness, and asymptotic behavior of large solutions have been investigated extensively. We list here, for example, [6-12].

This is a huge amount of literature dealing with single equation with infinite boundary conditions (see, e.g., [13-34]). This problem with more general nonlinearies and weightfunction has been discussed by many authors recently [35-39].

Problem (1.1) is considered in special case. When $p=2$, in [40], problem (1.1) was analyzed with $a(x)=1, b(x)=1$. In the same paper, some existence, uniqueness, and boundary behavior of solutions were obtained under the assumptions

$$
\begin{equation*}
a(x) \sim C_{1} d(x)^{k_{1}}, \quad b(x) \sim C_{2} d(x)^{k_{2}} \tag{1.4}
\end{equation*}
$$

as $d(x) \rightarrow 0^{+}$for some positive constants $C_{1}, C_{2}$ and real numbers $k_{1}, k_{2}>-2$. This problem was later studied in [41] with general form, where

$$
\begin{align*}
& C_{1} d(x)^{r_{1}} \leq a(x) \leq C_{2} d(x)^{r_{1}} \\
& C_{1}^{\prime} d(x)^{r_{1}} \leq b(x) \leq C_{2}^{\prime} d(x)^{r_{1}} \tag{1.5}
\end{align*}
$$

for $x \in \Omega, \gamma_{1}, \gamma_{2} \in \mathbf{R}^{\mathbf{N}}, C_{1}, C_{2}, C_{1}^{\prime}, C_{2}^{\prime}$ are positive constants. The author also obtained uniqueness results.

In [42], Yang extended the quasilinear elliptic system to

$$
\begin{align*}
& \Delta_{p} u=u^{m_{1}} v^{n_{1}} \quad \text { in } \Omega \\
& \Delta_{q} v=u^{m_{2}} v^{n_{2}} \quad \text { in } \Omega  \tag{1.6}\\
& u=v=+\infty \quad \text { on } \partial \Omega
\end{align*}
$$

where $m_{1}>p-1, n_{2}>q-1, m_{2}, n_{1}>0$, and $\Omega \subseteq \mathbf{R}^{\mathbf{N}}$ is a smooth bounded domain, subject to three different types of Dirichlet boundary conditions: $u=\lambda, v=\mu$ or $u=v=+\infty$ or $u=$ $+\infty, v=\mu$ on $\partial \Omega$, where $\lambda, \mu>0$. Under several hypotheses on the parameters $m_{1}, n_{1}, m_{2}, n_{2}$, the author showed the existence of positive solutions and further provided the asymptotic behavior of the solutions near $\partial \Omega$.

When $p \neq 2$, in [43], problem (1.1) was analyzed with $a(x)=1, b(x)=1$ under assumption (1.4). The author obtained the existence, uniqueness, and behavior of solutions to problem (1.1).

Very recently, Huang et al. [12] obtained existence, uniqueness, and asymptotic behavior of problem (1.1) when $p=2$, and $a(x), b(x)$ satisfy condition (1.2). Motivated by the results of the papers [12, 40, 41, 43], we consider the quasilinear elliptic system (1.1). We modify the method developed by Huang et al. [12] and extend the results to a quasilinear elliptic system (1.1) under condition (1.2).

Throughout of this paper, set

$$
\begin{gather*}
C_{1}=\min _{x \in \bar{\Omega}} C(x), \quad C_{2}=\max _{x \in \bar{\Omega}} C(x), \quad D_{1}=\min _{x \in \bar{\Omega}} D(x), \quad D_{2}=\max _{x \in \bar{\Omega}} D(x), \\
\gamma_{1}=\max _{x \in \bar{\Omega}} \gamma(x), \quad \gamma_{2}=\min _{x \in \bar{\Omega}} \gamma(x), \quad \eta_{1}=\max _{x \in \bar{\Omega}} \eta(x), \quad \eta_{2}=\min _{x \in \bar{\Omega}} \eta(x), \\
\alpha(x, y)=\frac{(p+x)(e-p+1)-(p+y) b}{(a-p+1)(e-p+1)-b c}, \quad \beta(x, y)=\frac{(p+y)(a-p+1)-(p+x) c}{(a-p+1)(e-p+1)-b c}, \\
E(x, y)=\left(\frac{\left((p-1) \alpha^{p-1}(\alpha+1)\right)^{e-p+1} x^{b}}{\left((p-1) \beta^{p-1}(\beta+1)\right)^{b} y^{e-p+1}}\right)^{1 /((a-p+1)(e-p+1)-b c)}, \\
F(x, y)=\left(\frac{\left((p-1) \beta^{p-1}(\beta+1)\right)^{a-p+1} y^{c}}{\left((p-1) \alpha^{p-1}(\alpha+1)\right)^{c} x^{a-p+1}}\right)^{1 /((a-p+1)(e-p+1)-b c)} \tag{1.7}
\end{gather*}
$$

$n_{x_{0}}$ stands for the outward unit normal at $x_{0} \in \partial \Omega$.
The paper is organized as follows. In Section 2 we consider some preliminaries which will be used in proof of Theorem 1.1. In Section 3 we will give the proof of the main theorem.

By modifications of the arguments in the proof of Theorem 1.1 in [12], we obtain the following main results.

Theorem 1.1. Assume that $\Omega$ is a bounded $C^{2}$ domain of $\mathbf{R}^{\mathbf{N}}, a(x), b(x) \in C^{\theta}(\Omega)$ for some $\theta \in$ $(0,1), a(x), b(x)>0$ in $\Omega$ and verify (1.2), $(a-p+1)(e-p+1)>b c, a, e>p-1, b, c>$ $0, \gamma(x), \eta(x) \in C\left(\bar{\Omega}, R^{+}\right)$and satisfy

$$
\begin{equation*}
\frac{b}{e-p+1}<\frac{p+\gamma\left(x_{0}\right)}{p+\eta\left(x_{0}\right)}<\frac{a-p+1}{c} \text { for } x_{0} \in \partial \Omega . \tag{1.8}
\end{equation*}
$$

Then problem (1.1) has a solution $(u, v)$ if and only if

$$
\begin{equation*}
\frac{b}{e-p+1}<\frac{p+\gamma_{1}}{p+\eta_{2}}, \quad \frac{p+\gamma_{2}}{p+\eta_{1}}<\frac{a-p+1}{c} \tag{1.9}
\end{equation*}
$$

And one has

$$
\begin{align*}
& \lim _{x \rightarrow x_{0}} \frac{u(x)}{d(x)^{-\alpha\left(\gamma\left(x_{0}\right), \eta\left(x_{0}\right)\right)} E\left(D\left(x_{0}\right), C\left(x_{0}\right)\right)}=1  \tag{1.10}\\
& \lim _{x \rightarrow x_{0}} \frac{v(x)}{d(x)^{-\beta\left(\gamma\left(x_{0}\right), \eta\left(x_{0}\right)\right)} F\left(D\left(x_{0}\right), C\left(x_{0}\right)\right)}=1 \tag{1.11}
\end{align*}
$$

## 2. Preliminaries

In this section, we will introduce some propositions.
Definition 2.1. $(\underline{u}, \underline{v})$ is a subsolution of

$$
\left\{\begin{array} { l l } 
{ \Delta _ { p } u = a ( x ) u ^ { a } v ^ { b } } & { \text { in } \Omega , }  \tag{2.1}\\
{ \Delta _ { p } v = b ( x ) u ^ { c } v ^ { e } } & { \text { in } \Omega , }
\end{array} \quad \text { provided } \left\{\begin{array}{ll}
\Delta_{p} \underline{u} \geq a(x) \underline{u}^{a} \underline{v}^{b} & \text { in } \Omega \\
\Delta_{p} \underline{v} \leq b(x) \underline{u}^{c} \underline{v}^{e} & \text { in } \Omega
\end{array}\right.\right.
$$

A supersolution $(\bar{u}, \bar{v})$ is defined by reversing the inequalities.
Proposition 2.2. Assume that $(\underline{u}, \underline{v})$ is a subsolution and $(\bar{u}, \bar{v})$ is a supersolution of problem (1.1), with $\underline{u}=\underline{v}=\bar{u}=\bar{v}=+\infty$ on $\partial \Omega$. Then problem (1.1) has at least a solution $(u, v)$ with $\underline{u} \leq u \leq$ $\bar{u}, \underline{v} \geq v \geq \bar{v}$ in $\Omega$. In particular $u=v=+\infty$ on $\partial \Omega$.

Proposition 2.3 (see [43]). Assume that $a(x), b(x)$ satisfy (1.4), then problem (1.1) admits a positive solution $(u, v)$ with $u=v=+\infty$ on $\partial \Omega$ if and only if $k_{1}, k_{2}>-p$ and

$$
\begin{equation*}
\frac{b}{e-p+1}<\frac{p+k_{1}}{p+k_{2}}<\frac{a-p+1}{c} \tag{2.2}
\end{equation*}
$$

This solution is unique and satisfies

$$
\begin{equation*}
\lim _{x \rightarrow x_{0}} \frac{u(x)}{d(x)^{-\alpha\left(k_{1}, k_{2}\right)} E\left(C_{2}, C_{1}\right)}=1, \quad \lim _{x \rightarrow x_{0}} \frac{v(x)}{d(x)^{-\beta\left(k_{1}, k_{2}\right)} F\left(C_{2}, C_{1}\right)}=1 \tag{2.3}
\end{equation*}
$$

for each $x_{0} \in \partial \Omega$.
Next, we are ready to study two auxiliary problems in a ball and an annuli. To this aim, for given $0<R_{1}<R$ and $x_{0} \in \mathbf{R}^{\mathbf{N}}, N \geq 1$, set

$$
\begin{equation*}
B_{R}\left(x_{0}\right)=\left\{x \in \mathbf{R}^{\mathbf{N}}:\left|x-x_{0}\right|<R\right\}, \quad A_{R_{1}, R}\left(x_{0}\right)=\left\{x \in \mathbf{R}^{\mathbf{N}}: R_{1}<\left|x-x_{0}\right|<R\right\} . \tag{2.4}
\end{equation*}
$$

Proposition 2.4. Assume $\Omega=B_{R}\left(x_{0}\right),(a-p+1)(e-p+1)>b c, a, e>p-1, b, c>0, C(r), D(r) \in$ $C\left([0, R], R^{+}\right)$and $\gamma, \eta>0$ satisfy

$$
\begin{equation*}
\frac{b}{e-p+1}<\frac{p+\gamma}{p+\eta}<\frac{a-p+1}{c} \tag{2.5}
\end{equation*}
$$

Then the following systems

$$
\begin{gather*}
\Delta_{p} \Phi=C(r)(R-r)^{r} \Phi^{a} \Psi^{b} \quad \text { in } B_{R}\left(x_{0}\right) \\
\Delta_{p} \Psi=D(r)(R-r)^{\eta} \Phi^{c} \Psi^{e} \quad \text { in } B_{R}\left(x_{0}\right)  \tag{2.6}\\
\Phi=\Psi=+\infty \quad \text { on } \partial B_{R}\left(x_{0}\right)
\end{gather*}
$$

possess a unique radially symmetric positive solution $(\Phi(r), \Psi(r))$ satisfying

$$
\begin{align*}
& \lim _{x \rightarrow x_{0}} \frac{\Phi(r)}{E(D(R), C(R))(R-r)^{-\alpha(\gamma, \eta)}}=1  \tag{2.7}\\
& \lim _{x \rightarrow x_{0}} \frac{\Psi(r)}{F(D(R), C(R))(R-r)^{-\beta(r, \eta)}}=1
\end{align*}
$$

where $r=\left|x-x_{0}\right|$.
Proof. At first, we consider the following systems

$$
\begin{gather*}
\left(\left|\Phi^{\prime}\right|^{p-2} \Phi^{\prime}\right)^{\prime}+\frac{N-1}{r}\left(\left|\Phi^{\prime}\right|^{p-2} \Phi^{\prime}\right)=C(r)(R-r)^{r} \Phi^{a} \Psi^{b} \quad \text { in }(0, R) \\
\left(\left|\Psi^{\prime}\right|^{p-2} \Psi^{\prime}\right)^{\prime}+\frac{N-1}{r}\left(\left|\Psi^{\prime}\right|^{p-2} \Psi^{\prime}\right)=D(r)(R-r)^{\eta} \Phi^{c} \Psi^{e} \quad \text { in }(0, R)  \tag{2.8}\\
\Phi(R)=\Psi(R)=+\infty, \quad \Phi^{\prime}(0)=\Psi^{\prime}(0)=0
\end{gather*}
$$

We will show that problem (2.8) has a solution $(\Phi(r), \Psi(r))$, which provide a positive radially symmetric solution to problem (2.6). Indeed, any positive solution $(\Phi(r), \Psi(r))$ of the integral equation system

$$
\begin{align*}
& \Phi(r)=l+\int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1} C(s)(R-s)^{r} \Phi^{a} \Psi^{b} d s\right]^{1 /(p-1)} d t, \quad 0<r<R \\
& \Psi(r)=m+\int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1} D(s)(R-s)^{\eta} \Phi^{c} \Psi^{e} d s\right]^{1 /(p-1)} d t, \quad 0<r<R \tag{2.9}
\end{align*}
$$

provides a solution of (2.8), where $\Phi(0)=l, \Psi(0)=m, \Phi(R)=+\infty, \Psi(R)=+\infty$.

Define $\Phi_{0}(r)=l, \Psi_{0}(r)=m$ for all $0<r<R$, let $\left\{\Phi_{k}\right\},\left\{\Psi_{k}\right\}$ be the function sequences given by

$$
\begin{align*}
& \Phi_{k}(r)=l+\int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1} C(s)(R-s)^{r} \Phi_{k-1}^{a} \Psi_{k-1}^{b} d s\right]^{1 /(p-1)} d t, \quad 0<r<R  \tag{2.10}\\
& \Psi_{k}(r)=m+\int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1} D(s)(R-s)^{\eta} \Phi_{k-1}^{c} \Psi_{k-1}^{e} d s\right]^{1 /(p-1)} d t, \quad 0<r<R
\end{align*}
$$

subject to $\Phi_{k}(0)=l, \Psi_{k}(0)=m, \Phi_{k}(R)=\Psi_{k}(R)=k$.
We remark that $\left\{\Phi_{k}\right\},\left\{\Psi_{k}\right\}$ are nondecreasing sequences. In fact,

$$
\begin{align*}
\Phi_{1}(r) & =l+\left(l^{a} m^{b}\right)^{1 /(p-1)} \int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1} C(s)(R-s)^{r} d s\right]^{1 /(p-1)} d t \\
& =l+\left(l^{a} m^{b}\right)^{1 /(p-1)} A(r) \geq l=\Phi_{0}(r)  \tag{2.11}\\
\Psi_{1}(r) & =m+\left(l^{c} m^{e}\right)^{1 /(p-1)} \int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1} D(s)(R-s)^{\eta} d s\right]^{1 /(p-1)} d t \\
& =m+\left(l^{c} m^{e}\right)^{1 /(p-1)} B(r) \geq m=\Psi_{0}(r),
\end{align*}
$$

where

$$
\begin{align*}
& A(r)=\int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1} C(s)(R-s)^{r} d s\right]^{1 /(p-1)} d t  \tag{2.12}\\
& B(r)=\int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1} D(s)(R-s)^{\eta} d s\right]^{1 /(p-1)} d t
\end{align*}
$$

Proceeding by the same manner, we conclude that

$$
\begin{equation*}
l \leq \Phi_{k} \leq \Phi_{k+1}, \quad m \leq \Psi_{k} \leq \Psi_{k+1} \tag{2.13}
\end{equation*}
$$

We now prove that $\left\{\Phi_{k}\right\},\left\{\Psi_{k}\right\}$ are bounded in $(0, R)$. To prove this, we consider

$$
\begin{equation*}
\Delta_{p} \Upsilon=\left(C(r)(R-r)^{r}+D(r)(R-r)^{\eta}\right)\left(\Upsilon^{a+b}+\Upsilon^{c+e}\right) \tag{2.14}
\end{equation*}
$$

problem (2.14) has a large radially symmetric solution $\Upsilon(r)$, and

$$
\begin{equation*}
\Upsilon(r)=\Upsilon(0)+\int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1}\left(C(s)(R-s)^{\gamma}+D(s)(R-s)^{\eta}\right)\left(\Upsilon^{a+b}+\Upsilon^{c+e}\right) d s\right]^{1 /(p-1)} d t \tag{2.15}
\end{equation*}
$$

where $\Upsilon(0)=l+m$. It follows that

$$
\begin{align*}
\Phi_{1}(r) & =l+\left(l^{a} m^{b}\right)^{1 /(p-1)} \int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1} C(s)(R-s)^{\gamma} d s\right]^{1 /(p-1)} d t \\
& \leq \Upsilon(0)+\int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1}\left(C(s)(R-s)^{\gamma}+D(s)(R-s)^{\eta}\right)\left(\Upsilon^{a+b}+\Upsilon^{c+e}\right) d s\right]^{1 /(p-1)} d t \\
& =\Upsilon(r) \tag{2.16}
\end{align*}
$$

Similarly, we have $\Psi_{1} \leq \Upsilon(r)$.
Arguing as before, we obtain $\Phi_{k} \leq \Upsilon(r), \Psi_{k} \leq \Upsilon(r)$. Therefore, we show that $\left\{\Phi_{k}\right\},\left\{\Psi_{k}\right\}$ are nondecreasing and bounded sequences in $(0, R)$, which implies that the following limit holds

$$
\begin{equation*}
(\Phi, \Psi)=\lim _{k \rightarrow \infty}\left(\Phi_{k}, \Psi_{k}\right) \tag{2.17}
\end{equation*}
$$

we deduce that $(\Phi, \Psi)$ is a positive solution of (2.8). Then $(\Phi(x), \Psi(x))=(\Phi(r), \Psi(r))$ is a positive radially symmetric solution to problem (2.6) and

$$
\begin{equation*}
\Phi(R)=\lim _{r \rightarrow R} \Phi(r)=\infty, \quad \Psi(R)=\lim _{r \rightarrow R} \Psi(r)=\infty \tag{2.18}
\end{equation*}
$$

Secondly, it is clear that

$$
\begin{equation*}
C_{1}(R-r)^{\gamma} \leq C(r)(R-r)^{\gamma} \leq C_{2}(R-r)^{r}, \quad D_{1}(R-r)^{\eta} \leq D(r)(R-r)^{\eta} \leq D_{2}(R-r)^{\eta} . \tag{2.19}
\end{equation*}
$$

By (2.5) and Proposition 2.3, we have

$$
\begin{align*}
& E\left(D_{1}, C_{2}\right) \leq \lim _{r \rightarrow R} \frac{\Phi(r)}{(R-r)^{-\alpha(r, \eta)}} \leq E\left(D_{2}, C_{1}\right)  \tag{2.20}\\
& F\left(D_{2}, C_{1}\right) \leq \lim _{r \rightarrow R} \frac{\Psi(r)}{(R-r)^{-\beta(r, \eta)}} \leq F\left(D_{1}, C_{2}\right)
\end{align*}
$$

Denote by

$$
\begin{equation*}
l=\lim _{r \rightarrow R} \frac{\Phi(r)}{(R-r)^{-\alpha(r, \eta)}}, \quad k=\lim _{r \rightarrow R} \frac{\Psi(r)}{(R-r)^{-\beta(r, \eta)}} \tag{2.21}
\end{equation*}
$$

By using $\gamma+p=(a-p+1) \alpha(\gamma, \eta)+b \beta(\gamma, \eta), \eta+p=(e-p+1) \beta(\gamma, \eta)+c \alpha(\gamma, \eta)$ and L'Hôpital rule, we obtain

$$
\begin{align*}
l & =\lim _{r \rightarrow R} \frac{\Phi(0)+\int_{0}^{r}\left[t^{1-N} \int_{0}^{t} s^{N-1} C(s)(R-s)^{r} \Phi^{a} \Psi^{b} d s\right]^{1 /(p-1)} d t}{(R-r)^{-\alpha}} \\
& =\lim _{r \rightarrow R} \frac{\left[r^{1-N} \int_{0}^{r} t^{N-1} C(t)(R-t)^{r} \Phi^{a} \Psi^{b} d t\right]^{1 /(p-1)}}{\alpha(R-r)^{-\alpha-1}} \\
& =\left[\lim _{r \rightarrow R} \frac{r^{1-N} \int_{0}^{r} t^{N-1} C(t)(R-t)^{r} \Phi^{a} \Psi^{b} d t}{\alpha(R-r)^{-(\alpha+1)(p-1)}}\right]^{1 /(p-1)} \\
& =\left[\lim _{r \rightarrow R} \frac{(1-N) r^{-N} \int_{0}^{r} t^{N-1} C(t)(R-t)^{r} \Phi^{a} \Psi^{b} d t+C(r)(R-r)^{r} \Phi^{a} \Psi^{b}}{\alpha(\alpha+1)(p-1)(R-r)^{-\alpha p+\alpha-p}}\right]^{1 /(p-1)} \\
& =\left[\frac{C(R)}{\alpha(\alpha+1)(p-1)} \lim _{r \rightarrow R}(R-r)^{a \alpha+b \beta} \Phi^{a} \Psi^{b}\right. \\
& =\left[\frac{1-N}{\alpha(\alpha+1)(p-1)} \lim _{r \rightarrow R} \frac{r^{-N} \int_{0}^{r} t^{N-1} C(t)(R-t)^{r} \Phi^{a} \Psi^{b} d t}{(R-r)^{-\alpha p+\alpha-p}}\right]^{1 /(p-1)} \\
& C(R)  \tag{2.22}\\
\alpha(\alpha+1)(p-1) & \left.l^{a} k^{b}+\frac{1-N}{\alpha(\alpha+1)(p-1)} \lim _{r \rightarrow R} \frac{r^{-N} \int_{0}^{r} t^{N-1} C(t)(R-t)^{r} \Phi^{a} \Psi^{b} d t}{(R-r)^{-\alpha p+\alpha-p}}\right]^{1 /(p-1)} .
\end{align*}
$$

We note that

$$
\begin{align*}
0 & \leq \lim _{r \rightarrow R} \frac{r^{-N} \int_{0}^{r} t^{N-1} C(t)(R-t)^{r} \Phi^{a} \Psi^{b} d t}{(R-r)^{-\alpha p+\alpha-p}} \\
& \leq \lim _{r \rightarrow R} \frac{r^{-1} \int_{0}^{r} C(t)(R-t)^{r} \Phi^{a} \Psi^{b} d t}{(R-r)^{-\alpha p+\alpha-p}} \\
& =\lim _{r \rightarrow R} \frac{C(r)(R-r)^{r} \Phi^{a} \Psi^{b} d t}{R(-\alpha p+\alpha-p)(R-r)^{-\alpha p+\alpha-p+1}}  \tag{2.23}\\
& =\frac{C(R)}{R(-\alpha p+\alpha-p)} \lim _{r \rightarrow R}(R-r)^{\gamma+\alpha p-\alpha+p+1} \Phi^{a} \Psi^{b} \\
& =\frac{C(R)}{R(-\alpha p+\alpha-p)} l^{a} k^{b} \lim _{r \rightarrow R}(R-r)=0 .
\end{align*}
$$

This implies that

$$
\begin{equation*}
l^{p-1}=\frac{C(R)}{\alpha(\alpha+1)(p-1)} l^{a} k^{b} \tag{2.24}
\end{equation*}
$$

Similarly, we obtain

$$
\begin{equation*}
k^{p-1}=\frac{D(R)}{\beta(\beta+1)(p-1)} l^{c} k^{e} . \tag{2.25}
\end{equation*}
$$

Since

$$
\begin{align*}
& \frac{\alpha^{p-1}(\alpha+1)(p-1)}{C(R)}=E(D(R), C(R))^{a-p+1} F(D(R), C(R))^{b}  \tag{2.26}\\
& \frac{\beta^{p-1}(\beta+1)(p-1)}{D(R)}=E(D(R), C(R))^{c} F(D(R), C(R))^{e-p+1}
\end{align*}
$$

If $0<\alpha<1,1<p \leq 2$, then

$$
\begin{equation*}
E^{a-p+1} F^{b}=\frac{\alpha^{p-1}(\alpha+1)(p-1)}{C(R)} \geq \frac{\alpha(\alpha+1)(p-1)}{C(R)}=l^{a-p+1} k^{b} \tag{2.27}
\end{equation*}
$$

therefore, we get $E \geq l, F \geq k$. If $0<\alpha<1, p>2$, we get $E \leq l, F \leq k$. So, when $0<\alpha<1$, we get $E=l, F=k$.

Similarly, when $\alpha \geq 1$, we also get $E=l, F=k$.
By (2.24) and (2.25), we conclude that $l=E(D(R), C(R)), k=F(D(R), C(R))$, this completes the proof.

Proposition 2.5. Assume $(a-p+1)(e-p+1)>b c, a, e>p-1, b, c>0, \gamma>0, \eta>0$, and

$$
\begin{equation*}
\frac{b}{e-p+1}<\frac{p+\gamma}{p+\eta}<\frac{a-p+1}{c} \tag{2.28}
\end{equation*}
$$

$\underline{D}(r), \underline{C}(r) \in C\left(\left[R_{1}, R\right], R^{+}\right)$are the reflection around $R_{0}=\left(R_{1}+R\right) / 2$ of some functions $\bar{C}(r), \bar{D}(r) \in C\left(\left[R_{0}, R\right], R^{+}\right)$. Then the following system

$$
\begin{align*}
\Delta_{p} \Phi & =C(r) d(x)^{\gamma} \Phi^{a} \Psi^{b} \quad \text { in } A_{R_{1}, R}\left(x_{0}\right) \\
\Delta_{p} \Psi & =D(r) d(x)^{\eta} \Phi^{c} \Psi^{e} \quad \text { in } A_{R_{1}, R}\left(x_{0}\right)  \tag{2.29}\\
\Phi & =\Psi=+\infty \quad \text { on } \partial A_{R_{1}, R}\left(x_{0}\right)
\end{align*}
$$

has a unique radially symmetric positive solution $(\Phi(r), \Psi(r))$ such that

$$
\begin{align*}
& \lim _{d(x) \rightarrow 0} \frac{\Phi(r)}{E(D(R), C(R)) d(x)^{-\alpha(r, \eta)}}=1  \tag{2.30}\\
& \lim _{d(x) \rightarrow 0} \frac{\Psi(r)}{F(D(R), C(R)) d(x)^{-\beta(r, \eta)}}=1
\end{align*}
$$

where

$$
d(x)=d\left(x, \partial A_{R_{1}, R}\left(x_{0}\right)\right)= \begin{cases}R-\left|x-x_{0}\right|, & \text { if } R_{0} \leq\left|x-x_{0}\right| \leq R  \tag{2.31}\\ \left|x-x_{0}\right|-R_{1}, & \text { if } R_{1} \leq\left|x-x_{0}\right| \leq R_{0}\end{cases}
$$

Proof. The proof is similarl to the proof of Proposition 2.4, so we omit it here.

## 3. Proof of Theorem 1.1

We are now ready to prove Theorem 1.1, whose proof will be split into the following several lemmas.

Lemma 3.1. Assume $(a-p+1)(e-p+1)>b c, a, e>p-1, b, c>0, C(x), D(x) \in$ $C(\bar{\Omega}), a(x), b(x)>0$ in $\Omega$ and (1.2) holds, $\gamma(x), \eta(x)>0$ and satisfy

$$
\begin{equation*}
\frac{b}{e-p+1}<\frac{p+\gamma\left(x_{0}\right)}{p+\eta\left(x_{0}\right)}<\frac{a-p+1}{c} \tag{3.1}
\end{equation*}
$$

for each $x_{0} \in \partial \Omega$, then problem (1.1) has a solution $(u, v)$ if

$$
\begin{equation*}
\frac{b}{e-p+1}<\frac{p+\gamma_{1}}{p+\eta_{2}}, \quad \frac{p+\gamma_{2}}{p+\eta_{1}}<\frac{a-p+1}{c} \tag{3.2}
\end{equation*}
$$

Proof. By (3.2) and Proposition 2.3, the following system

$$
\begin{gather*}
\Delta_{p} \Phi=C_{1} d(x)^{\gamma_{1}} \Phi^{a} \Psi^{b} \quad \text { in } \Omega \\
\Delta_{p} \Psi=D_{2} d(x)^{\eta_{2}} \Phi^{c} \Psi^{e} \quad \text { in } \Omega  \tag{3.3}\\
\Phi=\Psi=+\infty \quad \text { on } \partial \Omega
\end{gather*}
$$

possesses a positive solution $\left(u_{1}, v_{1}\right)$.
Next we will show that

$$
\begin{equation*}
(\bar{u}, \bar{v})=\left(\left(\frac{m+n}{(m-n)^{b /(a-p+1)}}\right)^{1 /(p-1)} u_{1},\left(\frac{m-n}{(m+n)^{c /(e-p+1)}}\right)^{1 /(p-1)} v_{1}\right) \tag{3.4}
\end{equation*}
$$

is a supersolution of (1.1), if $m$ is sufficiently large and $0<m-n<1$, where $m, n \in R^{+}$and $m>n$. In fact, by

$$
\begin{equation*}
r_{1}+p=(a-p+1) \alpha\left(\gamma_{1}, \eta_{2}\right)+b \beta\left(\gamma_{1}, \eta_{2}\right), \quad \eta_{2}+p=(e-p+1) \beta\left(\gamma_{1}, \eta_{2}\right)+c \alpha\left(\gamma_{1}, \eta_{2}\right) \tag{3.5}
\end{equation*}
$$

We have $(\bar{u}, \bar{v})$ is a supersolution of (1.1) provided

$$
\begin{align*}
& C_{1} d(x)^{r_{1}} \leq a(x)(m+n)^{((e-p+1)(a-p+1)-b c) /(e-p+1)(p-1)} \\
& D_{2} d(x) \geq b(x)(m-n)^{((a-p+1)(e-p+1)-b c) /(a-p+1)(p-1)} \tag{3.6}
\end{align*}
$$

Since $a(x), b(x) \in C(\bar{\Omega})$, choosing $m$ is large enough, and $m-n>0$ is sufficiently small, we can prove that

$$
\begin{equation*}
(\underline{u}, \underline{v})=\left(\left(\frac{m-n}{(m+n)^{b /(a-p+1)}}\right)^{1 /(p-1)} u_{2},\left(\frac{m+n}{(m-n)^{c /(e-p+1)}}\right)^{1 /(p-1)} v_{2}\right) \tag{3.7}
\end{equation*}
$$

is a subsolution of $(1.1)$, where $\left(u_{2}, v_{2}\right)$ is a solution of the following problem:

$$
\begin{gather*}
\Delta_{p} \Phi=C_{2} d(x)^{\gamma_{2}} \Phi^{a} \Psi^{b} \quad \text { in } \Omega \\
\Delta_{p} \Psi=D_{1} d(x)^{\eta_{1}} \Phi^{c} \Psi^{e} \quad \text { in } \Omega  \tag{3.8}\\
\Phi=\Psi=+\infty \quad \text { on } \partial \Omega
\end{gather*}
$$

Then by Proposition 2.2, problem (1.1) has a solution.
Lemma 3.2. Assume that problem (1.1) has a solution (u,v), then (1.9) holds.
Proof. In fact, if (1.9) does not hold, it will lead to a contradiction. From Lemma 3.1, we find that if $m$ is large enough and $m-n>0$ is sufficiently small, we have

$$
\begin{equation*}
u \leq \bar{u}=\left(\frac{m+n}{(m-n)^{b /(a-p+1)}}\right)^{1 /(p-1)} u_{1}, \quad v \leq \underline{v}=\left(\frac{m+n}{(m-n)^{c /(e-p+1)}}\right)^{1 /(p-1)} v_{2} \tag{3.9}
\end{equation*}
$$

On the other hand, by (2.3), there exists $\varepsilon>0$ such that for $x \in \Omega_{\varepsilon}=\{x \in \Omega: d(x, \partial \Omega) \leq \varepsilon\}$, we get

$$
\begin{equation*}
u \leq\left(\frac{m+n}{(m-n)^{b /(a-p+1)}}\right)^{1 /(p-1)} u_{1} \leq\left(\frac{m+n}{(m-n)^{b /(a-p+1)}}\right)^{1 /(p-1)} E\left(D_{2}, C_{1}\right) d(x)^{-\alpha\left(\gamma_{1}, \eta_{2}\right)} \tag{3.10}
\end{equation*}
$$

Thus, if

$$
\begin{equation*}
\frac{b}{e-p+1} \geq \frac{p+\gamma_{1}}{p+\eta_{2}} \tag{3.11}
\end{equation*}
$$

by the definition of $\alpha\left(\gamma_{1}, \eta_{2}\right)$, we obtain $\alpha\left(\gamma_{1}, \eta_{2}\right) \leq 0$. By (3.10), it implies that $u$ is bounded for $x \in \Omega_{\varepsilon}$, which is impossible since $u(x)=+\infty$ as $d(x)=\operatorname{dist}(x, \partial \Omega) \rightarrow 0^{+}$. If

$$
\begin{equation*}
\frac{p+\gamma_{2}}{p+\eta_{2}} \geq \frac{a-p+1}{c} \tag{3.12}
\end{equation*}
$$

it is similarly proved that $v$ is bounded near $\partial \Omega$, which is also a contradiction. The proof of Lemma 3.2 is complete.

Lemma 3.3. Let $(u, v)$ be a positive solution of (1.1), then (1.10) and (1.11) hold.
Proof. Fix $\tau \in(0,1)$, by (1.2), there exits $\sigma \in(0,1)$ such that, if $d\left(x, x_{0}\right)<\sigma$,

$$
\begin{equation*}
a(x) \geq(1-\tau) C\left(x_{0}\right) d(x)^{r\left(x_{0}\right)}, \quad b(x) \leq(1+\tau) D\left(x_{0}\right) d(x)^{\eta\left(x_{0}\right)} \tag{3.13}
\end{equation*}
$$

where $x_{0} \in \partial \Omega$. For a fixed $x_{0} \in \partial \Omega$, set

$$
\begin{equation*}
\Sigma=\bar{B}_{\sigma / 2} \bigcap \partial \Omega \tag{3.14}
\end{equation*}
$$

and choose $R>0$ small enough such that

$$
\begin{equation*}
K=\bigcup_{y \in \Sigma} \bar{B}_{R}\left(y-R n_{y}\right) \subset B_{\sigma}\left(x_{0}\right) \bigcap \Omega, \tag{3.15}
\end{equation*}
$$

where $n_{y}$ stands for the outward unit normal at $y \in \partial \Omega$.
For $x \in B_{\sigma}\left(x_{0}\right) \cap \Omega$, we get

$$
\begin{equation*}
a(x) \geq(1-\tau) C\left(x_{0}\right) d(x)^{\gamma\left(x_{0}\right)}, \quad b(x) \leq(1+\tau) D\left(x_{0}\right) d(x)^{\eta\left(x_{0}\right)} \tag{3.16}
\end{equation*}
$$

Since $\Omega$ is of $C^{2}$ bounded domain, there exit $R>0$ and $\sigma_{0}>0$ such that

$$
\begin{equation*}
B_{R}\left(x_{0}-(R+\sigma) n_{x_{0}}\right) \subset \Omega, \quad B_{R}\left(x_{0}-R n_{x_{0}}\right) \bigcap \partial \Omega=\left\{x_{0}\right\} \tag{3.17}
\end{equation*}
$$

for each $\sigma \in\left(0, \sigma_{0}\right)$.
Let $\left(u_{B, \sigma}, v_{B, \sigma}\right)$ be any positive radially symmetric solution to the following system:

$$
\begin{gather*}
\Delta_{p} u=(1-\tau) C\left(x_{0}\right)\left(R-\left|x-x_{0}\right|\right)^{\gamma\left(x_{0}\right)} u^{a} v^{b} \quad \text { in } B_{R}\left(x_{0}-(R+\sigma) n_{x_{0}}\right), \\
\Delta_{p} v=(1+\tau) D\left(x_{0}\right)\left(R-\left|x-x_{0}\right|\right)^{\eta\left(x_{0}\right)} u^{c} v^{e} \quad \text { in } B_{R}\left(x_{0}-(R+\sigma) n_{x_{0}}\right),  \tag{3.18}\\
u=v=+\infty \quad \text { on } \partial B_{R}\left(x_{0}-(R+\sigma) n_{x_{0}}\right) .
\end{gather*}
$$

It is easy to see that $\left(\underline{u}_{\sigma}, \underline{v}_{\sigma}\right)=\left.(u, v)\right|_{B_{R}\left(x_{0}-(R+\sigma) n_{x_{0}}\right)}$ is a positive smooth subsolution of (3.18), where $(u, v)$ is a positive solution of (1.1).

Then we get

$$
\begin{equation*}
\underline{u}_{\sigma}=\left.u\right|_{B_{R}\left(x_{0}-(R+\sigma) n_{x_{0}}\right)} \leq u_{B, \sigma}, \quad \underline{v}_{\sigma}=\left.v\right|_{B_{R}\left(x_{0}-(R+\sigma) n_{x_{0}}\right)} \geq v_{B, \sigma} \tag{3.19}
\end{equation*}
$$

Let $\left(u_{B}, v_{B}\right)$ be any positive solution to the following system:

$$
\begin{gather*}
\Delta_{p} u=(1-\tau) C\left(x_{0}\right)\left(R-\left|x-x_{0}\right|\right)^{r\left(x_{0}\right)} u^{a} v^{b} \quad \text { in } B_{R}\left(x_{0}-R n_{x_{0}}\right), \\
\Delta_{p} v=(1+\tau) D\left(x_{0}\right)\left(R-\left|x-x_{0}\right|\right)^{\eta\left(x_{0}\right)} u^{c} v^{e} \quad \text { in } B_{R}\left(x_{0}-R n_{x_{0}}\right),  \tag{3.20}\\
u=v=+\infty \quad \text { on } \partial B_{R}\left(x_{0}-R n_{x_{0}}\right) .
\end{gather*}
$$

By Proposition 2.3, $\left(u_{B}, v_{B}\right)$ satisfies

$$
\begin{align*}
& \lim _{r \rightarrow R} \frac{u_{B}}{E\left((1+\tau) D\left(x_{0}\right),(1-\tau) C\left(x_{0}\right)\right)(R-r)^{-\alpha\left(r\left(x_{0}\right), \eta\left(x_{0}\right)\right)}}=1  \tag{3.21}\\
& \lim _{r \rightarrow R} \frac{v_{B}}{F\left((1+\tau) D\left(x_{0}\right),(1-\tau) C\left(x_{0}\right)\right)(R-r)^{-\beta\left(r\left(x_{0}\right), \eta\left(x_{0}\right)\right)}}=1 \tag{3.22}
\end{align*}
$$

where $r=\left|x-x_{0}\right|$.
Taking into account that, for $x \in B_{R}\left(x_{0}-(R+\sigma) n_{x_{0}}\right)$,

$$
\begin{equation*}
u_{B, \sigma}(x)=u_{B}\left(x+\sigma n_{x_{0}}\right), \quad v_{B, \sigma}(x)=v_{B}\left(x+\sigma n_{x_{0}}\right) \tag{3.23}
\end{equation*}
$$

by (3.19), for each $x \in B_{R}\left(x_{0}-(R+\sigma) n_{x_{0}}\right)$ and $\sigma \in\left(0, \sigma_{0}\right)$, we have

$$
\begin{equation*}
u(x) \leq u_{B}\left(x+\sigma n_{x_{0}}\right), \quad v(x) \geq v_{B}\left(x+\sigma n_{x_{0}}\right) \tag{3.24}
\end{equation*}
$$

Let $\sigma \rightarrow 0$, we have

$$
\begin{equation*}
u(x) \leq u_{B}(x), \quad v(x) \geq v_{B}(x) \tag{3.25}
\end{equation*}
$$

It follows immediately from (3.21), (3.22) that

$$
\begin{align*}
& \lim _{r \rightarrow R} \frac{u}{E(R-r)^{-\alpha}} \leq \lim _{r \rightarrow R} \frac{u_{B}}{E(R-r)^{-\alpha}}=1  \tag{3.26}\\
& \lim _{r \rightarrow R} \frac{v}{F(R-r)^{-\beta}} \geq \lim _{r \rightarrow R} \frac{v_{B}}{F(R-r)^{-\beta}}=1 \tag{3.27}
\end{align*}
$$

where $E=E((1+\tau) D(R),(1-\tau) C(R)), F=F((1+\tau) D(R),(1-\tau) C(R))$.
We next have to prove the inverse inequalities. Similarly, there exits $R>R_{1}>0$ and $\sigma_{0}>0$ such that $\Omega \subset \bigcap_{0<\sigma<\sigma_{0}} A_{R_{1}, R}\left(x_{0}+(R+\sigma) n_{x_{0}}\right)$ and $A_{R_{0}, R}\left(x_{0}+R_{1} n_{x_{0}}\right) \cap \partial \Omega=\left\{x_{0}\right\}$.

Fix a sufficiently small $\tau$, there exit radially symmetric functions $\bar{a}: A_{R_{1}, R}\left(x_{0}+R_{1} n_{x_{0}}\right) \rightarrow R^{+}$ and $\underline{b}: A_{R_{1}, R}\left(x_{0}+R_{1} n_{x_{0}}\right) \rightarrow R^{+}$such that $\bar{a} \geq a, \underline{b} \leq b$ in $\Omega$, and

$$
\begin{equation*}
\max _{\bar{A}_{R_{1}, R\left(x_{0}+R_{1} n x_{0}\right)}} \bar{a} \leq \max _{\Omega} a+1, \quad \max _{\Omega} b+1 \leq \max _{\bar{A}_{R_{1}, R\left(x_{0}+R_{1} n x_{0}\right)}} \underline{b}, \tag{3.28}
\end{equation*}
$$

and for each $x \in A_{R_{1}, R}\left(x_{0}+R_{1} n x_{0}\right)$

$$
\begin{align*}
& \bar{a}(x)=a_{1}\left(\left|x-x_{0}-R_{1} n_{x_{0}}\right|\right)\left[d\left(x, \partial A_{R_{1}, R\left(x_{0}+R_{1} n_{x_{0}}\right)}\right)\right]^{\gamma\left(x_{0}\right)}  \tag{3.29}\\
& \underline{b}(x)=b_{1}\left(\left|x-x_{0}-R_{1} n_{x_{0}}\right|\right)\left[d\left(x, \partial A_{R_{1}, R\left(x_{0}+R_{1} n_{x_{0}}\right)}\right)\right]^{\eta\left(x_{0}\right)}
\end{align*}
$$

where $a_{1}, b_{1} \in C\left(\left[R_{1}, R\right], R^{+}\right)$, satisfing

$$
\begin{equation*}
a_{1}\left(R_{1}\right)=C\left(x_{0}\right)+\tau, \quad b_{1}\left(R_{1}\right)=D\left(x_{0}\right)-\tau \tag{3.30}
\end{equation*}
$$

We now consider the system

$$
\begin{gather*}
\Delta_{p} u=\bar{a}(x) u^{a} v^{b} \quad \text { in } A_{R_{1}, R}\left(x_{0}+R_{1} n_{x_{0}}\right) \\
\Delta_{p} v=\underline{b}(x) u^{c} v^{e} \quad \text { in } A_{R_{1}, R}\left(x_{0}+R_{1} n_{x_{0}}\right),  \tag{3.31}\\
u=v=+\infty \quad \text { on } \partial A_{R_{1}, R}\left(x_{0}+R_{1} n_{x_{0}}\right) .
\end{gather*}
$$

By Proposition 2.5, problem (3.31) possesses a solution $\left(u_{A}, v_{A}\right)$.
But for the system

$$
\begin{gather*}
\Delta_{p} u=\bar{a}(x) u^{a} v^{b} \quad \text { in } A_{R_{1}, R}\left(x_{0}+\left(R_{1}+\sigma\right) n_{x_{0}}\right) \\
\Delta_{p} v=\underline{b}(x) u^{c} v^{e} \quad \text { in } A_{R_{1}, R}\left(x_{0}+\left(R_{1}+\sigma\right) n_{x_{0}}\right)  \tag{3.32}\\
u=v=+\infty \quad \text { on } \partial A_{R_{1}, R}\left(x_{0}+\left(R_{1}+\sigma\right) n_{x_{0}}\right)
\end{gather*}
$$

it has a solution $\left(u_{A, \sigma}, v_{A, \sigma}\right)$, and for each $x \in A_{R_{1}, R}\left(x_{0}+\left(R_{1}+\sigma\right) n_{x_{0}}\right)$, we have

$$
\begin{equation*}
\left(u_{A, \sigma}(x), v_{A, \sigma}(x)\right)=\left(u_{A}\left(x-\sigma n_{x_{0}}\right), v_{A}\left(x-\sigma n_{x_{0}}\right)\right) \tag{3.33}
\end{equation*}
$$

It is also clear that $\left(\underline{u}_{A}(x), \underline{v}_{A}(x)\right)=\left.\left(u_{A, \sigma}(x), v_{A, \sigma}(x)\right)\right|_{\Omega}$ is a subsolution of problem (1.1). Thus for each $x \in A_{R_{1}, R}\left(x_{0}+\left(R_{1}+\sigma\right) n_{x_{0}}\right)$, we get $u_{A}\left(x-\sigma n_{x_{0}}\right) \leq u(x), v_{A}\left(x-\sigma n_{x_{0}}\right) \geq v(x)$. Let $\sigma \rightarrow 0$, we have $\underline{u}_{A}(x) \leq u(x), \underline{v}_{A}(x) \geq v(x)$. Thus for $x \in K$, we get

$$
\begin{align*}
1 & =\lim _{|x| \rightarrow R} \frac{\underline{u}_{A}(x)}{E(\bar{a}(x), \underline{b}(x))(R-|x|)^{-\alpha\left(\gamma\left(x_{0}\right), \eta\left(x_{0}\right)\right)}} \\
& \leq \lim _{d(x) \rightarrow 0} \frac{u(x)}{E(\bar{a}(x), \underline{b}(x))(R-|x|)^{-\alpha\left(\gamma\left(x_{0}\right), \eta\left(x_{0}\right)\right)}},  \tag{3.34}\\
1 & =\lim _{|x| \rightarrow R} \frac{\underline{v}_{A}(x)}{F(\bar{a}(x), \underline{b}(x))(R-|x|)^{-\beta\left(\gamma\left(x_{0}\right), \eta\left(x_{0}\right)\right)}} \\
& \geq \lim _{d(x) \rightarrow 0} \frac{v(x)}{F(\bar{a}(x), \underline{b}(x))(R-|x|)^{-\beta\left(\gamma\left(x_{0}\right), \eta\left(x_{0}\right)\right)}} \tag{3.35}
\end{align*}
$$

but we have $\lim _{\tau \rightarrow 0} K=\left\{x_{0}\right\}$. Therefore, by (3.26), (3.27), (3.34), and (3.35), we finish (1.10) and (1.11). The proof of Lemma 3.3 is complete. From Lemma 3.1 to Lemma 3.3, we finish the proof of Theorem 1.1.

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