Research Article

A New Hybrid Algorithm for Variational Inclusions, Generalized Equilibrium Problems, and a Finite Family of Quasi-Nonexpansive Mappings

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We proposed in this paper a new iterative scheme for finding common elements of the set of fixed points of a finite family of quasi-nonexpansive mappings, the set of solutions of variational inclusion, and the set of solutions of generalized equilibrium problems. Some strong convergence results were derived by using the concept of *W*-mappings for a finite family of quasi-nonexpansive mappings. Strong convergence results are derived under suitable conditions in Hilbert spaces.

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1. Introduction

Let *H* be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and inducted norm $|| \cdot ||$, and let *C* be a nonempty closed and convex subset of *H*. Then, a mapping $T : C \to C$ is said to be

- (1) *nonexpansive* if $||Tx Ty|| \le ||x y||$, for all $x, y \in C$;
- (2) *quasi-nonexpansive* if $||Tx p|| \le ||x p||$, for all $x \in C$ and $p \in F(T)$;
- (3) *L*-*Lipschitzian* if there exists a constant L > 0 such that $||Tx Ty|| \le L||x y||$, for all $x, y \in C$. We denoted by F(T) the set of fixed points of T.

In 1953, Mann [1] introduced the following iterative procedure to approximate a fixed point of a nonexpansive mapping *T* in a Hilbert space *H*:

$$x_{n+1} = \alpha_n x_n + (1 - \alpha_n) T x_n, \quad \forall n \in \mathbf{N},$$
(1.1)

where the initial point x_0 is taken in *C* arbitrarily and $\{\alpha_n\}$ is a sequence in [0, 1].

However, we note that Mann's iteration process (1.1) has only weak convergence, in general; for instance, see [2, 3].

Many authors attempt to modify the process (1.1) so that strong convergence is guaranteed that has recently been made. Nakajo and Takahashi [4] proposed the following modification which is the so-called CQ method and proved the following strong convergence theorem for a nonexpansive mapping *T* in a Hilbert space *H*.

Theorem 1.1 (see [4]). Let *C* be a nonempty closed convex subset of a Hilbert space *H* and let *T* be a nonexpansive mapping of *C* into itself such that $F(T) \neq \emptyset$. Suppose that $x_1 = x \in C$ and $\{x_n\}$ is given by

. .

$$y_{n} = \alpha_{n} x_{n} + (1 - \alpha_{n}) T x_{n},$$

$$C_{n} = \{ z \in C : ||y_{n} - z|| \le ||x_{n} - z|| \},$$

$$Q_{n} = \{ z \in C : \langle x_{n} - z, x - x_{n} \rangle \ge 0 \},$$

$$x_{n+1} = P_{C_{n} \cap O_{n}} x, \quad \forall n \in \mathbf{N},$$
(1.2)

where $0 \le \alpha_n \le a < 1$. Then, $\{x_n\}$ converges strongly to $z_0 = P_{F(T)}x$.

Let $\varphi : H \to R \cup \{\infty\}$ be a function and let *F* be a bifunction from $C \times C$ to *R* such that $C \cap \operatorname{dom} \varphi \neq \emptyset$, where *R* is the set of real numbers and dom $\varphi = \{x \in H : \varphi(x) < \infty\}$. The generalized equilibrium problem is to find $\hat{x} \in C$ such that

$$F(\hat{x}, y) + \varphi(y) - \varphi(\hat{x}) \ge 0, \quad \forall y \in C.$$
(1.3)

The set of solutions of (1.3) is denoted by $\text{GEP}(F, \varphi)$; see also [5–7].

If $\varphi : H \to R \cup \{\infty\}$ is replaced by a real-valued function $\phi : C \to R$, problem (1.3) reduces to the following mixed equilibrium problem introduced by Ceng and Yao [8]: find $\hat{x} \in C$ such that

$$F(\hat{x}, y) + \phi(y) - \phi(\hat{x}) \ge 0, \quad \forall y \in C.$$
(1.4)

Let $\varphi(x) = \delta_C(x)$, for all $x \in H$. Here δ_C denotes the indicator function of the set *C*; that is, $\delta_C(x) = 0$ if $x \in C$ and $\delta_C(x) = \infty$ otherwise. Then problem (1.3) reduces to the following equilibrium problem: find $\hat{x} \in C$ such that

$$F(\hat{x}, y) \ge 0, \quad \forall y \in C.$$
 (1.5)

The set of solutions (1.5) is denoted by EP(F). Problem (1.5) includes, as special cases, the optimization problem, the variational inequality problem, the fixed point problem, the nonlinear complementarity problem, the Nash equilibrium problem in noncooperative games, and the vector optimization problem; see [9–12] and the reference cited therein.

Recently, Tada and Takahashi [13] proposed a new iteration for finding a common element of the set of solutions of an equilibrium problem and the set of fixed points of a nonexpansive mapping T in a Hilbert space H and then obtain the following theorem.

Theorem 1.2 (see [13]). Let *H* be a real Hilbert space, let *C* be a closed convex subset of *H*, let $F : C \times C \rightarrow R$ be a bifunction, and let $T : C \rightarrow C$ be a nonexpansive mapping such that $F(T) \cap EP(F) \neq \emptyset$. For an initial point $x_1 = x \in C$, let a sequence $\{x_n\}$ be generated by

$$F(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge 0 \quad \forall y \in C,$$

$$y_n = \alpha_n x_n + (1 - \alpha_n) T u_n,$$

$$C_n = \{ z \in C : ||y_n - z|| \le ||x_n - z|| \},$$

$$Q_n = \{ z \in C : \langle x_n - z, x_n - x \rangle \le 0 \},$$

$$x_{n+1} = P_{C_n \cap Q_n} x, \quad \forall n \in \mathbf{N},$$

(1.6)

where $0 \le \alpha_n \le a < 1$ and $\liminf_{n \to \infty} r_n > 0$. Then, $\{x_n\}$ converges strongly to $P_{F(T) \cap EP(F)} x$.

Let $A : H \to H$ be a single-valued nonlinear mapping and let $M : H \to 2^H$ be a set-valued mapping. The variational inclusion is to find $\hat{x} \in H$ such that

$$\theta \in A(\hat{x}) + M(\hat{x}), \tag{1.7}$$

where θ is the zero vector in H. The set of solutions of problem (1.7) is denoted by I(A, M). Recall that a mapping $A : H \to H$ is called *a*-*inverse strongly monotone* if there exists a constant $\alpha > 0$ such that

$$\langle Ax - Ay, x - y \rangle \ge \alpha ||Ax - Ay||^2, \quad \forall x, y \in H.$$
 (1.8)

A set-valued mapping $M : H \to 2^H$ is called *monotone* if for all $x, y \in H$, $f \in M(x)$, and $g \in M(y)$ imply $\langle x - y, f - g \rangle \ge 0$. A monotone mapping M is *maximal* if its graph $G(M) := \{(f, x) \in H \times H : f \in M(x)\}$ of M is not properly contained in the graph of any other monotone mapping. It is known that a monotone mapping M is maximal if and only if for $(x, f) \in H \times H$, $\langle x - y, f - g \rangle \ge 0$ for all $(y, g) \in G(M)$ imply $f \in M(x)$. We define the resolvent operator $J_{M,\lambda}$ associated with M and λ as follows:

$$J_{M,\lambda}(x) = (I + \lambda M)^{-1}(x), \quad x \in H, \ \lambda > 0.$$
(1.9)

It is known that the resolvent operator $J_{M,\lambda}$ is single-valued, nonexpansive, and 1inverse strongly monotone; see [14], and that a solution of problem (1.7) is a fixed point of the operator $J_{M,\lambda}(I - \lambda A)$ for all $\lambda > 0$; see also [15]. If $0 < \lambda < 2\alpha$, it is easy to see that $J_{M,\lambda}(I - \lambda A)$ is a nonexpansive mapping; consequently, I(A, M) is closed and convex.

The equilibrium problems, generalized equilibrium problems, variational inequality problems, and variational inclusions have been intensively studied by many authors; for instance, see [8, 16–43].

Motivated by Tada and Takahashi [13] and Peng et al. [7], we introduce a new approximation scheme for finding a common element of the set of fixed points of a finite family of quasi-nonexpansive and Lipschitz mappings, the set of solutions of a generalized

equilibrium problem, and the set of solutions of a variational inclusion with set-valued maximal monotone and inverse strongly monotone mappings in the framework of Hilbert spaces.

2. Preliminaries and Lemmas

Let *C* be a closed convex subset of a real Hilbert space *H* with norm $\|\cdot\|$ and inner product $\langle \cdot, \cdot \rangle$. For each $x \in H$, there exists a unique nearest point in *C*, denoted by $P_C x$, such that $\|x - P_C x\| = \min_{y \in C} \|x - y\|$. P_C is called the *metric projection* of *H* on to *C*. It is also known that for $x \in H$ and $z \in C$, $z = P_C x$ is equivalent to $\langle x - z, y - z \rangle \leq 0$ for all $y \in C$. Furthermore

$$\|y - P_C x\|^2 + \|x - P_C x\|^2 \le \|x - y\|^2$$
(2.1)

for all $x \in H$, $y \in C$; see also [4, 44]. In a real Hilbert space, we also know that

$$\|\lambda x + (1 - \lambda)y\|^{2} = \lambda \|x\|^{2} + (1 - \lambda)\|y\|^{2} - \lambda(1 - \lambda)\|x - y\|^{2}$$
(2.2)

for all $x, y \in H$ and $\lambda \in [0, 1]$.

Lemma 2.1 (see [45]). Let *C* be a nonempty closed convex subset of a Hilbert space *H*. Then for points $w, x, y \in H$ and a real number $a \in R$, the set

$$D := \left\{ z \in C : \|y - z\|^2 \le \|x - z\|^2 + \langle w, z \rangle + a \right\} \text{ is closed and convex.}$$
(2.3)

For solving the generalized equilibrium problem, let us give the following assumptions for *F*, φ , and the set *C*:

- (A1) F(x, x) = 0 for all $x \in C$;
- (A2) *F* is monotone, that is, $F(x, y) + F(y, x) \le 0$ for all $x, y \in C$;
- (A3) for each $y \in C, x \mapsto F(x, y)$ is weakly upper semicontinuous;
- (A4) for each $x \in C$, $y \mapsto F(x, y)$ is convex;
- (A5) for each $x \in C$, $y \mapsto F(x, y)$ is lower semicontinuous;
- (B1) for each $x \in H$ and r > 0, there exists a bounded subset $D_x \subseteq C$ and $y_x \in C \cap \operatorname{dom} \varphi$ such that for any $z \in C \setminus D_x$,

$$F(z, y_x) + \varphi(y_x) + \frac{1}{r} \langle y_x - z, z - x \rangle < \varphi(z); \qquad (2.4)$$

(B2) *C* is a bounded set.

Lemma 2.2 (see [7]). Let C be a nonempty closed convex subset of a real Hilbert H. Let F be a bifunction from $C \times C$ to R satisfying (A1)–(A5) and let $\varphi : H \rightarrow R \cup \{\infty\}$ be a proper lower

semicontinuous and convex function such that $C \cap \operatorname{dom} \varphi \neq \emptyset$. For r > 0 and $x \in H$, define a mapping $S_r : H \to C$ as follows:

$$S_r(x) = \left\{ z \in C : F(z, y) + \varphi(y) + \frac{1}{r} \langle y - z, z - x \rangle \ge \varphi(z), \ \forall y \in C \right\}.$$
(2.5)

Assume that either (B1) or (B2) holds. Then, the following conclusions hold:

- (1) for each $x \in H$, $S_r(x) \neq \emptyset$;
- (2) S_r is single-valued;
- (3) S_r is firmly nonexpansive, that is, for any $x, y \in H$,

$$\|S_r(x) - S_r(y)\|^2 \le \langle S_r(x) - S_r(y), x - y \rangle;$$
 (2.6)

- (4) $F(S_r) = GEP(F, \varphi);$
- (5) $GEP(F, \varphi)$ is closed and convex.

Lemma 2.3 (see [14]). Let $M : H \to 2^H$ be a maximal monotone mapping and let $A : H \to H$ be a Lipshitz continuous mapping. Then the mapping $S = M + A : H \to 2^H$ is a maximal monotone mapping.

Lemma 2.4. Let C be a nonempty closed convex subset of a real Hilbert space H. Let T be a quasinonexpansive and L-Lipschitz mapping of C into itself. Then, F(T) is closed and convex.

Proof. Since *T* is *L*-Lipschitz, it is easy to show that F(T) is closed. Let $x, y \in F(T)$ and z = tx + (1 - t)y where $t \in (0, 1)$. From (2.2), we have

$$||z - Tz||^{2} = t||x - Tz||^{2} + (1 - t)||y - Tz||^{2} - t(1 - t)||x - y||^{2}$$

$$\leq t||x - z||^{2} + (1 - t)||y - z||^{2} - t(1 - t)||x - y||^{2}$$

$$= t(1 - t)^{2}||x - y||^{2} + (1 - t)t^{2}||x - y||^{2} - t(1 - t)||x - y||^{2} = 0,$$
(2.7)

which implies $z \in F(T)$; consequently, F(T) is convex. This completes the proof.

Lemma 2.5 (see [46]). In a strictly convex Banach space X, if

$$\|x\| = \|y\| = \|\lambda x + (1 - \lambda)y\|$$
(2.8)

for all $x, y \in X$ and $\lambda \in (0, 1)$, then x = y.

In 1999, Atsushiba and Takahashi [47] introduced the concept of the *W*-mapping as follows:

$$U_{1} = \beta_{1}T_{1} + (1 - \beta_{1})I,$$

$$U_{2} = \beta_{2}T_{2}U_{1} + (1 - \beta_{2})I,$$

$$\vdots$$

$$U_{N-1} = \beta_{N-1}T_{N-1}U_{N-2} + (1 - \beta_{N-1})I,$$

$$W = U_{N} = \beta_{N}T_{N}U_{N-1} + (1 - \beta_{N})I,$$
(2.9)

where $\{T_i\}_{i=1}^N$ is a finite mapping of *C* into itself and $\beta_i \in [0,1]$ for all i = 1, 2, ..., N with $\sum_{i=1}^N \beta_i = 1$.

Such a mapping *W* is called the *W*-mapping generated by $T_1, T_2, ..., T_N$ and $\beta_1, \beta_2, ..., \beta_N$; see also [48–50]. Throughout this paper, we denote $F := \bigcap_{i=1}^N F(T_i)$.

Next, we prove some useful lemmas concerning the *W*-mapping.

Lemma 2.6. Let *C* be a nonempty closed convex subset of a strictly convex Banach space X. Let $\{T_i\}_{i=1}^N$ be a finite family of quasi-nonexpansive and L_i -Lipschitz mappings of *C* into itself such that $F := \bigcap_{i=1}^N F(T_i) \neq \emptyset$ and let $\beta_1, \beta_2, \ldots, \beta_N$ be real numbers such that $0 < \beta_i < 1$ for all $i = 1, 2, \ldots, N-1, 0 < \beta_N \leq 1$, and $\sum_{i=1}^N \beta_i = 1$. Let *W* be the *W*-mapping generated by T_1, T_2, \ldots, T_N and $\beta_1, \beta_2, \ldots, \beta_N$. Then, the followings hold:

- (i) W is quasi-nonexpansive and Lipschitz;
- (ii) $F(W) = \bigcap_{i=1}^{N} F(T_i)$.

Proof. (i) For each $x \in C$ and $z \in F$, we observe that

$$||T_1 x - z|| \le ||x - z||. \tag{2.10}$$

Let $k \in \{2, 3, ..., N\}$, then

$$\|U_{k}x - z\| = \|\beta_{k}T_{k}U_{k-1}x + (1 - \beta_{k})x - z\|$$

$$\leq \beta_{k}\|U_{k-1}x - z\| + (1 - \beta_{k})\|x - z\|.$$
(2.11)

Hence,

$$\begin{split} \|Wx - z\| &= \|U_N x - z\| \\ &\leq \beta_N \|U_{N-1} x - z\| + (1 - \beta_N) \|x - z\| \\ &\leq \beta_N (\beta_{N-1} \|U_{N-2} x - z\| + (1 - \beta_{N-1}) \|x - z\|) + (1 - \beta_N) \|x - z\| \end{split}$$

$$\leq \beta_{N} (\beta_{N-1} (\beta_{N-2} \| U_{N-3}x - z \| + (1 - \beta_{N-2}) \| x - z \|) + (1 - \beta_{N-1}) \| x - z \|) + (1 - \beta_{N}) \| x - z \| \\\vdots \leq \beta_{N} (\beta_{N-1} (\beta_{N-2} \cdots (\beta_{2} (\beta_{1} \| T_{1}x - z \| + (1 - \beta_{1}) \| x - z \|) + (1 - \beta_{2}) \| x - z \|) + \cdots + (1 - \beta_{N-2}) \| x - z \|) + (1 - \beta_{N-1}) \| x - z \|) + (1 - \beta_{N}) \| x - z \| \leq \beta_{N} (\beta_{N-1} (\beta_{N-2} \cdots (\beta_{2} (\beta_{1} \| x - z \| + (1 - \beta_{1}) \| x - z \|) + (1 - \beta_{2}) \| x - z \|) + \cdots + (1 - \beta_{N-2}) \| x - z \|) + (1 - \beta_{N-1}) \| x - z \|) + (1 - \beta_{N}) \| x - z \| = \beta_{N} (\beta_{N-1} (\beta_{N-2} \cdots (\beta_{3} (\beta_{2} \| x - z \| + (1 - \beta_{2}) \| x - z \|) + (1 - \beta_{3}) \| x - z \|) + \cdots + (1 - \beta_{N-2}) \| x - z \|) + (1 - \beta_{N-1}) \| x - z \|) + (1 - \beta_{N}) \| x - z \| = \| x - z \|.$$

$$(2.12)$$

This shows that *W* is a quasi-nonexpansive mapping.

Next, we claim that *W* is a Lipschitz mapping. Note that T_i is L_i -Lipschitz for all i = 1, 2, ..., N. For each $x, y \in C$, we observe

$$\|U_{1}x - U_{1}y\| = \|\beta_{1}T_{1}x + (1 - \beta_{1})x - \beta_{1}T_{1}y - (1 - \beta_{1})y\|$$

$$\leq \beta_{1}\|T_{1}x - T_{1}y\| + (1 - \beta_{1})\|x - y\|$$

$$\leq (\beta_{1}L_{1} + (1 - \beta_{1}))\|x - y\|.$$
(2.13)

Let $k \in \{2, 3, ..., N\}$, then

$$\|U_{k}x - U_{k}y\| = \|\beta_{k}T_{k}U_{k-1}x + (1 - \beta_{k})x - \beta_{k}T_{k}U_{k-1}y - (1 - \beta_{k})y\|$$

$$\leq \beta_{k}L_{k}\|U_{k-1}x - U_{k-1}y\| + (1 - \beta_{k})\|x - y\|.$$
(2.14)

Hence,

$$\begin{aligned} \|Wx - Wy\| &\leq \beta_N L_N \|U_{N-1}x - U_{N-1}y\| + (1 - \beta_N) \|x - y\| \\ &\leq \beta_N L_N \beta_{N-1} L_{N-1} \|U_{N-2}x - U_{N-2}y\| \\ &+ (\beta_N L_N (1 - \beta_{N-1}) + (1 - \beta_N)) \|x - y\| \\ &\vdots \end{aligned}$$

$$\leq \beta_{N}L_{N}\beta_{N-1}L_{N-1}\cdots\beta_{2}L_{2}||U_{1}x - U_{1}y|| \\ + (\beta_{N}L_{N}\beta_{N-1}L_{N-1}\cdots\beta_{3}L_{3}(1 - \beta_{2}) \\ + \beta_{N}L_{N}\beta_{N-1}L_{N-1}\cdots\beta_{4}L_{4}(1 - \beta_{3}) \\ + \cdots + \beta_{N}L_{N}(1 - \beta_{N-1}) + (1 - \beta_{N}))||x - y|| \\ \leq \beta_{N}L_{N}\beta_{N-1}L_{N-1}\cdots\beta_{2}L_{2}(\beta_{1}L_{1} + (1 - \beta_{1})||x - y||) \\ + (\beta_{N}L_{N}\beta_{N-1}L_{N-1}\cdots\beta_{3}L_{3}(1 - \beta_{2}) \\ + \beta_{N}L_{N}\beta_{N-1}L_{N-1}\cdots\beta_{4}L_{4}(1 - \beta_{3}) \\ + \cdots + \beta_{N}L_{N}(1 - \beta_{N-1}) + (1 - \beta_{N}))||x - y|| \\ = (\beta_{N}L_{N}\beta_{N-1}L_{N-1}\cdots\beta_{2}L_{2}(1 - \beta_{1}) \\ + \beta_{N}L_{N}\beta_{N-1}L_{N-1}\cdots\beta_{3}L_{3}(1 - \beta_{2}) \\ + \beta_{N}L_{N}\beta_{N-1}L_{N-1}\cdots\beta_{4}L_{4}(1 - \beta_{3}) \\ + \cdots + \beta_{N}L_{N}(1 - \beta_{N-1}) + (1 - \beta_{N}))||x - y||. \\ \leq (L_{N}L_{N-1}\cdots L_{1} + L_{N}L_{N-1}\cdots L_{2} + L_{N}L_{N-1}\cdots L_{3} \\ + L_{N}L_{N-1}\cdots L_{4} + \cdots + L_{N}L_{N-1} + L_{N} + 1)||x - y||.$$

$$(2.15)$$

Since $L_i > 0$ for all i = 1, 2, ..., N, we get that W is a Lipschitz mapping. (ii) Since $F \in F(W)$ is trivial, it suffices to show that $F(W) \in F$. To end this, let $p \in F(W)$ and $x^* \in F$. Then, we have

$$\|p - x^*\| = \|Wp - x^*\| = \|\beta_N(T_N U_{N-1}p - x^*) + (1 - \beta_N)(p - x^*)\|$$

$$\leq \beta_N \|U_{N-1}p - x^*\| + (1 - \beta_N)\|p - x^*\|$$

$$\leq \rho_{N} \| \mathcal{U}_{N-1} p^{-x} \| + (1 - \rho_{N}) \| p^{-x} \|$$

$$= \beta_{N} \| \beta_{N-1} (T_{N-1} \mathcal{U}_{N-2} p - x^{*}) + (1 - \beta_{N-1}) (p - x^{*}) \| + (1 - \beta_{N}) \| p - x^{*} \|$$

$$\leq \beta_{N} \beta_{N-1} \| \mathcal{U}_{N-2} p - x^{*} \| + (1 - \beta_{N} \beta_{N-1}) \| p - x^{*} \|$$

$$= \beta_{N} \beta_{N-1} \| \beta_{N-2} (T_{N-2} \mathcal{U}_{N-3} p - x^{*}) + (1 - \beta_{N-2}) (p - x^{*}) \| + (1 - \beta_{N} \beta_{N-1}) \| p - x^{*} \|$$

$$\leq \beta_{N} \beta_{N-1} \beta_{N-2} \| \mathcal{U}_{N-3} p - x^{*} \| + (1 - \beta_{N} \beta_{N-1} \beta_{N-2}) \| p - x^{*} \|$$

$$\vdots$$

$$= \beta_{N} \beta_{N-1} \cdots \beta_{3} \| \beta_{2} (T_{2} \mathcal{U}_{1} p - x^{*}) + (1 - \beta_{2}) (p - x^{*}) \| + (1 - \beta_{N} \beta_{N-1} \cdots \beta_{3}) \| p - x^{*} \|$$

$$\leq \beta_{N}\beta_{N-1}\cdots\beta_{2} \|T_{2}U_{1}p - x^{*}\| + (1 - \beta_{N}\beta_{N-1}\cdots\beta_{2}) \|p - x^{*}\|$$

$$\leq \beta_{N}\beta_{N-1}\cdots\beta_{2} \|U_{1}p - x^{*}\| + (1 - \beta_{N}\beta_{N-1}\cdots\beta_{2}) \|p - x^{*}\|$$

$$= \beta_{N}\beta_{N-1}\cdots\beta_{2} \|\beta_{1}(T_{1}p - x^{*}) + (1 - \beta_{1})(p - x^{*})\| + (1 - \beta_{N}\beta_{N-1}\cdots\beta_{2}) \|p - x^{*}\|$$

$$\leq \beta_{N}\beta_{N-1}\cdots\beta_{2}\beta_{1} \|T_{1}p - x^{*}\| + (1 - \beta_{N}\beta_{N-1}\cdots\beta_{2}\beta_{1}) \|p - x^{*}\|$$

$$\leq \beta_{N}\beta_{N-1}\cdots\beta_{2}\beta_{1} \|p - x^{*}\| + (1 - \beta_{N}\beta_{N-1}\cdots\beta_{2}\beta_{1}) \|p - x^{*}\| = \|p - x^{*}\|.$$
(2.16)

This shows that

$$\|p - x^*\| = \beta_N \beta_{N-1} \cdots \beta_2 \|\beta_1 (T_1 p - x^*) + (1 - \beta_1) (p - x^*)\| + (1 - \beta_N \beta_{N-1} \cdots \beta_2) \|p - x^*\|,$$
(2.17)

and hence

$$\|p - x^*\| = \|\beta_1(T_1p - x^*) + (1 - \beta_1)(p - x^*)\|.$$
(2.18)

Again by (2.16), we see that $||p - x^*|| = ||T_1p - x^*||$. Hence

$$\|p - x^*\| = \|T_1p - x^*\| = \|\beta_1(T_1p - x^*) + (1 - \beta_1)(p - x^*)\|.$$
(2.19)

Applying Lemma 2.5 to (2.19), we get that $T_1p = p$ and hence $U_1p = p$. Again by (2.16), we have

$$\|p - x^*\| = \beta_N \beta_{N-1} \cdots \beta_3 \|\beta_2 (T_2 U_1 p - x^*) + (1 - \beta_2) (p - x^*)\| + (1 - \beta_N \beta_{N-1} \cdots \beta_3) \|p - x^*\|,$$
(2.20)

and hence

$$\|p - x^*\| = \|\beta_2(T_2U_1p - x^*) + (1 - \beta_2)(p - x^*)\|.$$
(2.21)

From (2.16), we know that $||U_1p - x^*|| = ||T_2U_1p - x^*||$. Since $U_1p = p$, we have

$$\|p - x^*\| = \|T_2p - x^*\| = \|\beta_2(T_2p - x^*) + (1 - \beta_2)(p - x^*)\|.$$
(2.22)

Applying Lemma 2.5 to (2.22), we get that $T_2p = p$ and hence $U_2p = p$.

By proving in the same manner, we can conclude that $T_i p = p$ and $U_i p = p$ for all i = 1, 2, ..., N - 1. Finally, we also have

$$\|p - T_N p\| \le \|p - Wp\| + \|Wp - T_N p\| = \|p - Wp\| + (1 - \beta_N) \|p - T_N p\|,$$
(2.23)

which yields that $p = T_N p$ since $p \in F(W)$. Hence $p \in F := \bigcap_{i=1}^N F(T_i)$.

Lemma 2.7. Let C be a nonempty closed convex subset of a Banach space X. Let $\{T_i\}_{i=1}^N$ be a finite family of quasi-nonexpansive and L_i -Lipschitz mappings of C into itself and $\{\beta_{n,i}\}_{i=1}^N$ sequences in [0,1] such that $\beta_{n,i} \rightarrow \beta_i$ as $n \rightarrow \infty$. Moreover, for every $n \in \mathbb{N}$, let W and W_n be the W-mappings generated by T_1, T_2, \ldots, T_N and $\beta_1, \beta_2, \ldots, \beta_N$ and T_1, T_2, \ldots, T_N and $\beta_{n,1}, \beta_{n,2}, \ldots, \beta_{n,N}$, respectively. Then

$$\lim_{n \to \infty} \|W_n x - W x\| = 0, \quad \forall x \in C.$$
(2.24)

Proof. Let $x \in C$ and U_k and $U_{n,k}$ be generated by T_1, T_2, \ldots, T_k and $\beta_1, \beta_2, \ldots, \beta_k$ and T_1, T_2, \ldots, T_k and $\beta_{n,1}, \beta_{n,2}, \ldots, \beta_{n,k}$, respectively. Then

$$\|U_{n,1}x - U_1x\| = \|(\beta_{n,1} - \beta_1)(T_1x - x)\| \le |\beta_{n,1} - \beta_1| \|T_1x - x\|.$$
(2.25)

Let $k \in \{2, 3, ..., N\}$ and $M = \max\{\|T_k U_{k-1}x\| + \|x\| : k = 2, 3, ..., N\}$. Then

$$\begin{aligned} \|U_{n,k}x - U_{k}x\| &= \left\|\beta_{n,k}T_{k}U_{n,k-1}x + (1 - \beta_{n,k})x - \beta_{k}T_{k}U_{k-1} - (1 - \beta_{k})x\right\| \\ &= \left\|\beta_{n,k}T_{k}U_{n,k-1}x - \beta_{n,k}x - \beta_{k}T_{k}U_{k-1} + \beta_{k}x\right\| \\ &\leq \beta_{n,k}\|T_{k}U_{n,k-1}x - T_{k}U_{k-1}x\| + \left|\beta_{n,k} - \beta_{k}\right|\|T_{k}U_{k-1}x\| + \left|\beta_{n,k} - \beta_{k}\right|\|x\| \\ &\leq L_{k}\|U_{n,k-1}x - U_{k-1}x\| + \left|\beta_{n,k} - \beta_{k}\right|M. \end{aligned}$$

$$(2.26)$$

It follows that

$$\begin{split} \|W_{n}x - Wx\| &= \|U_{n,N}x - U_{N}x\| \\ &\leq L_{N}\|U_{n,N-1}x - U_{N-1}x\| + |\beta_{n,N} - \beta_{N}|M \\ &\leq L_{N}(L_{N-1}\|U_{n,N-2}x - U_{N-2}x\| + |\beta_{n,N-1} - \beta_{N-1}|M) + |\beta_{n,N} - \beta_{N}|M \\ &= L_{N}L_{N-1}\|U_{n,N-2}x - U_{N-2}x\| + L_{N}|\beta_{n,N-1} - \beta_{N-1}|M + |\beta_{n,N} - \beta_{N}|M \\ &\vdots \\ &\leq L_{N}L_{N-1}\cdots L_{3}(L_{2}\|U_{n,1}x - U_{1}x\| + |\beta_{n,2} - \beta_{2}|M) \\ &+ L_{N}L_{N-1}\cdots L_{4}|\beta_{n,3} - \beta_{3}|M + \cdots + L_{N}|\beta_{n,N-1} - \beta_{N-1}|M + |\beta_{n,N} - \beta_{N}|M \\ &\leq L_{N}L_{N-1}\cdots L_{2}|\beta_{n,1} - \beta_{1}|\|T_{1}x - x\| + L_{N}L_{N-1}\cdots L_{3}|\beta_{n,2} - \beta_{2}|M \\ &+ L_{N}L_{N-1}\cdots L_{4}|\beta_{n,3} - \beta_{3}|M + \cdots + L_{N}|\beta_{n,N-1} - \beta_{N-1}|M + |\beta_{n,N} - \beta_{N}|M . \end{split}$$

$$(2.27)$$

Since $\beta_{n,i} \rightarrow \beta_i$ as $n \rightarrow \infty$ (*i* = 1, 2, ..., *N*), we obtain the result.

3. Strong Convergence Theorems

In this section, we prove a strong convergence theorem which solves the problem of finding a common element of the set of solutions of a generalized equilibrium problem and the set of solutions of a variational inclusion and the set of common fixed points of a finite family of quasi-nonexpansive and Lipschitz mappings.

Theorem 3.1. Let C be a nonempty closed convex subset of a real Hilbert space H, let $F : C \times C \to R$ be a bifunction satisfying (A1)–(A5), let $\varphi : C \to R \cup \{\infty\}$ be a proper lower semicontinuous and convex function, let $A : H \to H$ be an α -inverse strongly monotone mapping, let $M : H \to 2^H$ be a maximal monotone mapping, and let $\{T_i\}_{i=1}^N$ be a finite family of quasi-nonexpansive and L_i -Lipschitz mappings of C into itself. Assume that $\Omega := \bigcap_{i=1}^N F(T_i) \cap GEP(F, \varphi) \cap I(A, M) \neq \emptyset$ and either (B1) or (B2) holds. Let W_n be the W-mapping generated by T_1, T_2, \ldots, T_N and $\beta_{n,1}, \beta_{n,2}, \ldots, \beta_{n,N}$. For an initial point $x_0 \in H$ with $C_1 = C$ and $x_1 = P_{C_1}x_0$, let $\{x_n\}, \{y_n\}, \{z_n\}, and \{u_n\}$ be sequences generated by

$$F(u_{n}, y) + \varphi(y) - \varphi(u_{n}) + \frac{1}{r_{n}} \langle y - u_{n}, u_{n} - x_{n} \rangle \ge 0, \quad \forall y \in C,$$

$$y_{n} = \alpha_{n} x_{n} + (1 - \alpha_{n}) W_{n} u_{n},$$

$$z_{n} = J_{M,\lambda_{n}} (y_{n} - \lambda_{n} A y_{n}),$$

$$C_{n+1} = \{ z \in C_{n} : ||z_{n} - z|| \le ||y_{n} - z|| \le ||x_{n} - z|| \},$$

$$x_{n+1} = P_{C_{n+1}} x_{0}, \quad \forall n \in \mathbf{N},$$

(3.1)

where $\{\alpha_n\} \subset [0, a]$ for some $a \in [0, 1)$, $\{r_n\} \subset [b, \infty)$ for some $b \in (0, \infty)$ and $\{\lambda_n\} \subset [c, d]$ for some $c, d \in (0, 2\alpha)$.

Then, $\{x_n\}$, $\{y_n\}$, $\{z_n\}$, and $\{u_n\}$ converge strongly to $z_0 = P_\Omega x_0$.

Proof. Since $0 < c \le \lambda_n \le d < 2\alpha$ for all $n \in \mathbb{N}$, we get that $J_{M,\lambda_n}(I - \lambda_n A)$ is nonexpansive for all $n \in \mathbb{N}$. Hence, $\bigcap_{n=1}^{\infty} F(J_{M,\lambda_n}(I - \lambda_n A)) = I(A, M)$ is closed and convex. By Lemma 2.2(5), we know that $GEP(F, \varphi)$ is closed and convex. By Lemma 2.4, we also know that $F := \bigcap_{i=1}^{N} F(T_i)$ is closed and convex. Hence, $\Omega := \bigcap_{i=1}^{N} F(T_i) \cap GEP(F, \varphi) \cap I(A, M)$ is a nonempty closed convex set; consequently, $P_{\Omega}x_0$ is well defined for every $x_0 \in H$.

Next, we divide the proof into seven steps.

Step 1. Show that $\Omega \subset C_n$ for all $n \in \mathbb{N}$.

By Lemma 2.1, we see that C_n is closed and convex for all $n \in \mathbb{N}$. Hence $P_{C_{n+1}}x_0$ is well defined for every $x_0 \in H$, $n \in \mathbb{N}$. Let $p \in \Omega$. From $u_n = S_{r_n}x_n$ and $p = J_{M,\lambda_n}(p - \lambda_n Ap)$ for all $n \in \mathbb{N}$, we have

$$\begin{aligned} \|z_{n} - p\| &= \|J_{M,\lambda_{n}}(y_{n} - \lambda_{n}Ay_{n}) - J_{M,\lambda_{n}}(p - \lambda_{n}Ap)\| \\ &\leq \|y_{n} - p\| \\ &\leq \alpha_{n} \|x_{n} - p\| + (1 - \alpha_{n}) \|W_{n}u_{n} - p\| \\ &\leq \alpha_{n} \|x_{n} - p\| + (1 - \alpha_{n}) \|u_{n} - p\| \\ &= \alpha_{n} \|x_{n} - p\| + (1 - \alpha_{n}) \|S_{r_{n}}x_{n} - S_{r_{n}}p\| \\ &\leq \|x_{n} - p\|. \end{aligned}$$
(3.2)

It follows that $p \in C_{n+1}$, and hence $\Omega \subset C_n$ for all $n \in \mathbb{N}$.

Step 2. Show that $\lim_{n\to\infty} ||x_n - x_0||$ exists.

Since Ω is a nonempty closed convex subset of *C*, there exists a unique element $z_0 = P_{\Omega}x_0 \in \Omega \subset C_n$. From $x_n = P_{C_n}x_0$, we obtain

$$\|x_n - x_0\| \le \|z_0 - x_0\|. \tag{3.3}$$

Hence { $||x_n - x_0||$ } is bounded; so are { y_n }, { z_n }, and { u_n }. Since $x_{n+1} = P_{C_{n+1}}x_0 \in C_{n+1} \subset C_n$, we also have

$$\|x_n - x_0\| \le \|x_{n+1} - x_0\|. \tag{3.4}$$

From (3.3) and (3.4), we get that $\lim_{n\to\infty} ||x_n - x_0||$ exists.

Step 3. Show that $\{x_n\}$ is a Cauchy sequence.

By the construction of the set C_n , we know that $x_m = P_{C_m} x_0 \in C_m \subset C_n$ for m > n. From (2.1), it follows that

$$\|x_m - x_n\|^2 \le \|x_m - x_0\|^2 - \|x_n - x_0\|^2 \longrightarrow 0,$$
(3.5)

as $m, n \to \infty$. Hence $\{x_n\}$ is a Cauchy sequence. By the completeness of H and the closeness of C, we can assume that $x_n \to q \in C$.

Step 4. Show that $q \in F$.

From (3.5), we get

$$\|x_{n+1} - x_n\| \longrightarrow 0, \tag{3.6}$$

as $n \to \infty$. Since $x_{n+1} \in C_{n+1} \subset C_n$, we have

$$||z_n - x_n|| \le ||z_n - x_{n+1}|| + ||x_{n+1} - x_n|| \le 2||x_{n+1} - x_n|| \longrightarrow 0,$$
(3.7)

as $n \to \infty$. Hence, $z_n \to q$ as $n \to \infty$. By the nonexpansiveness of J_{M,λ_n} and the inverse strongly monotonicity of A, we obtain that

$$||z_{n} - p||^{2} \leq ||y_{n} - \lambda_{n}Ay_{n} - (p - \lambda_{n}Ap)||^{2}$$

$$\leq ||y_{n} - p||^{2} + \lambda_{n}(\lambda_{n} - 2\alpha)||Ay_{n} - Ap||^{2}$$

$$\leq ||x_{n} - p||^{2} + c(d - 2\alpha)||Ay_{n} - Ap||^{2}.$$
(3.8)

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This implies that

$$c(2\alpha - d) ||Ay_n - Ap||^2 \le ||x_n - p||^2 - ||z_n - p||^2$$

$$\le ||x_n - z_n|| (||x_n - p|| + ||z_n - p||).$$
(3.9)

It follows from (3.7) that

$$\lim_{n \to \infty} \left\| Ay_n - Ap \right\| = 0. \tag{3.10}$$

Since J_{M,λ_n} is 1-inverse strongly monotone, we have

$$\begin{aligned} \|z_{n} - p\|^{2} &= \|J_{M,\lambda_{n}}(y_{n} - \lambda_{n}Ay_{n}) - J_{M,\lambda_{n}}(p - \lambda_{n}Ap)\|^{2} \\ &\leq \langle (y_{n} - \lambda_{n}Ay_{n}) - (p - \lambda_{n}Ap), z_{n} - p \rangle \\ &= \frac{1}{2} \Big(\|(y_{n} - \lambda_{n}Ay_{n}) - (p - \lambda_{n}Ap)\|^{2} + \|z_{n} - p\|^{2} \\ &- \|(y_{n} - \lambda_{n}Ay_{n}) - (p - \lambda_{n}Ap) - (z_{n} - p)\|^{2} \Big) \\ &\leq \frac{1}{2} \Big(\|y_{n} - p\|^{2} + \|z_{n} - p\|^{2} - \|(y_{n} - z_{n}) - \lambda_{n}(Ay_{n} - Ap)\|^{2} \Big) \\ &\leq \frac{1}{2} \Big(\|x_{n} - p\|^{2} + \|z_{n} - p\|^{2} - \|y_{n} - z_{n}\|^{2} + 2\lambda_{n}\langle y_{n} - z_{n}, Ay_{n} - Ap \rangle \Big) \\ &\leq \frac{1}{2} \Big(\|x_{n} - p\|^{2} + \|z_{n} - p\|^{2} - \|y_{n} - z_{n}\|^{2} + 2\lambda_{n}\|y_{n} - z_{n}\|\|Ay_{n} - Ap\| \Big). \end{aligned}$$

This implies that

$$||z_n - p||^2 \le ||x_n - p||^2 - ||y_n - z_n||^2 + 2\lambda_n ||y_n - z_n|| ||Ay_n - Ap||.$$
(3.12)

It follows that

$$||y_n - z_n||^2 \le ||x_n - z_n|| (||x_n - p|| + ||z_n - p||) + 2d||y_n - z_n|| ||Ay_n - Ap||.$$
(3.13)

From (3.7) and (3.10) we get

$$\lim_{n \to \infty} \|y_n - z_n\| = 0.$$
(3.14)

It follows from (3.7) and (3.14) that

$$\|W_n u_n - x_n\| = \frac{1}{1 - \alpha_n} \|y_n - x_n\| \longrightarrow 0,$$
(3.15)

as $n \to \infty$. Since S_{r_n} is firmly nonexpansive and $u_n = S_{r_n} x_n$, we have

$$\|u_{n} - p\|^{2} = \|S_{r_{n}}x_{n} - S_{r_{n}}p\|^{2}$$

$$\leq \langle S_{r_{n}}x_{n} - S_{r_{n}}p, x_{n} - p \rangle$$

$$= \langle u_{n} - p, x_{n} - p \rangle$$

$$= \frac{1}{2} (\|u_{n} - p\|^{2} + \|x_{n} - p\|^{2} - \|x_{n} - u_{n}\|^{2}),$$
(3.16)

which implies that

$$\|u_n - p\|^2 \le \|x_n - p\|^2 - \|x_n - u_n\|^2.$$
(3.17)

It follows from (3.17) that

$$\|y_{n} - p\|^{2} \leq \alpha_{n} \|x_{n} - p\|^{2} + (1 - \alpha_{n}) \|W_{n}u_{n} - p\|^{2}$$

$$\leq \alpha_{n} \|x_{n} - p\|^{2} + (1 - \alpha_{n}) \|u_{n} - p\|^{2}$$

$$\leq \alpha_{n} \|x_{n} - p\|^{2} + (1 - \alpha_{n}) \left(\|x_{n} - p\|^{2} - \|x_{n} - u_{n}\|^{2} \right)$$

$$= \|x_{n} - p\|^{2} - (1 - \alpha_{n}) \|x_{n} - u_{n}\|^{2},$$
(3.18)

which yields that

$$(1-a)\|x_n-u_n\|^2 \le \|x_n-p\|^2 - \|y_n-p\|^2.$$
(3.19)

Hence, from (3.7) and (3.14), we also have

$$\lim_{n \to \infty} \|x_n - u_n\| = 0.$$
(3.20)

It follows from (3.15) and (3.20) that

$$\lim_{n \to \infty} \|u_n - W_n u_n\| = 0.$$
(3.21)

By Lemma 2.7, we also get that $\lim_{n\to\infty} ||u_n - Wu_n|| = 0$. From Lemma 2.6(i), we know that W is Lipschitz. Since $u_n \to q$ as $n \to \infty$, it is easy to verify that $q \in F(W)$. Moreover, by Lemma 2.6(ii), we can conclude that $q \in F := \bigcap_{i=1}^N F(T_i)$.

Step 5. Show that $q \in \text{GEP}(F, \varphi)$.

Since $u_n = S_{r_n} x_n$, we have

$$F(u_n, y) + \varphi(y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge \varphi(u_n), \quad \forall y \in C.$$
(3.22)

From (A2), we have

$$\varphi(y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge F(y, u_n) + \varphi(u_n), \quad \forall y \in C.$$
(3.23)

It follows from (A5) and the weakly lower semicontinuity of φ , $||x_n - u_n|| / r_n \to 0$, and $u_n \to q$ that

$$F(y,q) + \varphi(q) \le \varphi(y), \quad \forall y \in C.$$
(3.24)

Put $y_t = ty + (1-t)q$ for all $t \in (0,1]$ and $y \in C \cap \text{dom } \varphi$. Since $y \in C \cap \text{dom } \varphi$ and $q \in C \cap \text{dom } \varphi$, we obtain $y_t \in C \cap \text{dom } \varphi$, and hence $F(y_t, q) + \varphi(q) \leq \varphi(y_t)$. So by (A1), (A4), and the convexity of φ , we have

$$0 = F(y_t, y_t) + \varphi(y_t) - \varphi(y_t)$$

$$\leq tF(y_t, y) + (1 - t)F(y_t, q) + t\varphi(y) + (1 - t)\varphi(q) - \varphi(y_t)$$
(3.25)

$$\leq t[F(y_t, y) + \varphi(y) - \varphi(y_t)].$$

Hence,

$$F(y_t, y) + \varphi(y) - \varphi(y_t) \ge 0. \tag{3.26}$$

Letting $t \to 0$, it follows from (A3) and the weakly semicontinuity of φ that

$$F(q, y) + \varphi(y) \ge \varphi(q) \tag{3.27}$$

for all $y \in C \cap \text{dom } \varphi$. Observe that if $y \in C \setminus \text{dom } \varphi$, then $F(q, y) + \varphi(y) \ge \varphi(q)$ holds. Hence $q \in \text{GEP}(F, \varphi)$.

Step 6. Show that $q \in I(A, M)$.

First observe that *A* is an $(1/\alpha)$ -Lipschitz monotone mapping and D(A) = H. From Lemma 2.3, we know that M + A is maximal monotone. Let $(v, g) \in G(M + A)$, that is, $g - Av \in M(v)$. Since $z_n = J_{M,\lambda_n}(y_n - \lambda_n Ay_n)$, we get $y_n - \lambda_n Ay_n \in (I + \lambda_n M)(z_n)$, that is,

$$\frac{1}{\lambda_n}(y_n - z_n - \lambda_n A y_n) \in M(z_n).$$
(3.28)

By the maximal monotonicity of M + A, we have

$$\left\langle v - z_n, g - Av - \frac{1}{\lambda_n} (y_n - z_n - \lambda_n A y_n) \right\rangle \ge 0,$$
 (3.29)

and so

$$\langle v - z_n, g \rangle \geq \left\langle v - z_n, Av + \frac{1}{\lambda_n} (y_n - z_n - \lambda_n Ay_n) \right\rangle$$

$$= \left\langle v - z_n, Av - Az_n + Az_n - Ay_n + \frac{1}{\lambda_n} (y_n - z_n) \right\rangle$$

$$\geq 0 + \left\langle v - z_n, Az_n - Ay_n \right\rangle + \left\langle v - z_n, \frac{1}{\lambda_n} (y_n - z_n) \right\rangle.$$

$$(3.30)$$

It follows from $||y_n - z_n|| \to 0$, $||Ay_n - Az_n|| \to 0$ and $z_n \to q$ that

$$\lim_{n \to \infty} \langle v - z_n, g \rangle = \langle v - q, g \rangle \ge 0.$$
(3.31)

By the maximal monotonicity of M + A, we have $\theta \in (M + A)(q)$; consequently, $q \in I(A, M)$.

Step 7. Show that $q = z_0 = P_{\Omega} x_0$.

Since $x_n = P_{C_n} x_0$ and $\Omega \subset C_n$, we obtain

$$\langle x_0 - x_n, x_n - p \rangle \ge 0 \quad \forall p \in \Omega.$$
 (3.32)

By taking the limit in (3.32), we obtain

$$\langle x_0 - q, q - p \rangle \ge 0 \quad \forall p \in \Omega.$$
 (3.33)

This shows that $q = P_{\Omega}x_0 = z_0$.

From Steps 1–7, we can conclude that $\{x_n\}$, $\{y_n\}$, $\{z_n\}$, and $\{u_n\}$ converge strongly to $z_0 = P_{\Omega}x_0$. This completes the proof.

4. Applications

As a direct consequence of Theorem 3.1, we obtain some new and interesting results in a Hilbert space as the following theorems. Recall that VI(A, C) is the solution set of the classical variational inequality

$$\langle A\hat{x}, y - \hat{x} \rangle \ge 0, \quad \forall y \in C.$$
 (4.1)

Theorem 4.1. Let *C* be a nonempty closed convex subset of a real Hilbert space *H*, let $F : C \times C \to R$ be a bifunction satisfying (A1)–(A5), let $\varphi : C \to R \cup \{\infty\}$ be a proper lower semicontinuous and convex function, let $A : C \to H$ be an α -inverse strongly monotone mapping, and let $\{T_i\}_{i=1}^N$ be a finite family of quasi-nonexpansive and L_i -Lipschitz mappings of *C* into itself. Assume that $\Omega :=$ $\bigcap_{i=1}^N F(T_i) \cap GEP(F,\varphi) \cap VI(A,C) \neq \emptyset$ and either (B1) or (B2) holds. Let W_n be the *W*-mapping generated by T_1, T_2, \ldots, T_N and $\beta_{n,1}, \beta_{n,2}, \ldots, \beta_{n,N}$. For an initial point $x_0 \in H$ with $C_1 = C$ and $x_1 = P_{C_1}x_0$, let $\{x_n\}, \{y_n\}, \{z_n\}$, and $\{u_n\}$ be sequences generated by

$$F(u_{n}, y) + \varphi(y) - \varphi(u_{n}) + \frac{1}{r_{n}} \langle y - u_{n}, u_{n} - x_{n} \rangle \ge 0, \quad \forall y \in C,$$

$$y_{n} = \alpha_{n} x_{n} + (1 - \alpha_{n}) W_{n} u_{n},$$

$$z_{n} = P_{C}(y_{n} - \lambda_{n} A y_{n}),$$

$$C_{n+1} = \{ z \in C_{n} : ||z_{n} - z|| \le ||y_{n} - z|| \le ||x_{n} - z|| \},$$

$$x_{n+1} = P_{C_{n+1}} x_{0}, \quad \forall n \in \mathbf{N},$$

(4.2)

where $\{\alpha_n\} \subset [0, a]$ for some $a \in [0, 1)$, $\{r_n\} \subset [b, \infty)$ for some $b \in (0, \infty)$, and $\{\lambda_n\} \subset [c, d]$ for some $c, d \in (0, 2\alpha)$.

Then, $\{x_n\}$, $\{y_n\}$, $\{z_n\}$, and $\{u_n\}$ converge strongly to $z_0 = P_{\Omega}x_0$.

Proof. In Theorem 3.1, take $M = \partial \delta_C : H \to 2^H$, where $\delta_C : H \to [0, \infty]$ is the indicator function of *C*. It is well known that the subdifferential $\partial \delta_C$ is a maximal monotone operator. Then, problem (1.7) is equivalent to problem (4.1) and the resolvent operator $J_{M,\lambda_n} = P_C$ for all $n \in \mathbb{N}$. This completes the proof.

Next, we give a strong convergence theorem for finding a common element of the set of solutions of an equilibrium problem, the set of solutions of a variational inclusion and the set of common fixed points of a finite family of quasi-nonexpansive and Lipschitz mappings. In order to do this, let us assume that

(B3) for each $x \in H$ and r > 0, there exists a bounded subset $D_x \subseteq C$ and $y_x \in C$ such that for any $z \in C \setminus D_x$,

$$F(z, y_x) + \frac{1}{r} \langle y_x - z, z - x \rangle < 0.$$
(4.3)

Theorem 4.2. Let *C* be a nonempty closed convex subset of a real Hilbert space *H*, let $F : C \times C \to R$ be a bifunction satisfying (A1)–(A5), let $A : H \to H$ be an α -inverse strongly monotone mapping, let $M : H \to 2^H$ be a maximal monotone mapping, and let $\{T_i\}_{i=1}^N$ be a finite family of quasinonexpansive and L_i -Lipschitz mappings of *C* into itself. Assume that $\Omega := \bigcap_{i=1}^N F(T_i) \cap EP(F) \cap$ $I(A, M) \neq \emptyset$ and either (B1) or (B3) holds. Let W_n be the W-mapping generated by T_1, T_2, \ldots, T_N and $\beta_{n,1}, \beta_{n,2}, \dots, \beta_{n,N}$. For an initial point $x_0 \in H$ with $C_1 = C$ and $x_1 = P_{C_1}x_0$, let $\{x_n\}, \{y_n\}, \{z_n\}$, and $\{u_n\}$ be sequences generated by

$$F(u_{n}, y) + \frac{1}{r_{n}} \langle y - u_{n}, u_{n} - x_{n} \rangle \geq 0, \quad \forall y \in C,$$

$$y_{n} = \alpha_{n} x_{n} + (1 - \alpha_{n}) W_{n} u_{n},$$

$$z_{n} = J_{M,\lambda_{n}} (y_{n} - \lambda_{n} A y_{n}),$$

$$C_{n+1} = \{ z \in C_{n} : ||z_{n} - z|| \leq ||y_{n} - z|| \leq ||x_{n} - z|| \},$$

$$x_{n+1} = P_{C_{n+1}} x_{0}, \quad \forall n \in \mathbf{N},$$

(4.4)

where $\{\alpha_n\} \subset [0, a]$ for some $a \in [0, 1)$, $\{r_n\} \subset [b, \infty)$ for some $b \in (0, \infty)$, and $\{\lambda_n\} \subset [c, d]$ for some $c, d \in (0, 2\alpha)$.

Then, $\{x_n\}$, $\{y_n\}$, $\{z_n\}$, and $\{u_n\}$ converge strongly to $z_0 = P_{\Omega}x_0$.

Proof. In Theorem 3.1, take $\varphi(x) = \delta_C(x)$, for all $x \in H$. Then problem (1.3) reduces to the equilibrium problem (1.5).

Remark 4.3. Theorem 3.1 improves and extends the main results in [4, 13] and the corresponding results.

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