PARAMETRIC PROBLEM OF COMPLETELY GENERALIZED QUASI-VARIATIONAL INEQUALITIES

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This paper is devoted to the study of behaviour and sensitivity analysis of the solution for a class of parametric problem of completely generalized quasi-variational inequalities.

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1. Introduction

Sensitivity analysis of solutions for variational inequalities with single-valued mappings has been studied by many authors with different techniques in finite dimensional spaces and Hilbert spaces [3, 4, 7, 11, 14]. Robinson [10] has dealt with the sensitivity analysis of solutions for the classical variational inequalities over polyhedral convex sets in finite dimensional spaces.

In this paper, we study the behaviour and sensitivity analysis of solutions for a class of parametric problem of completely generalized quasi-variational inequalities with setvalued mappings without the differentiability assumptions.

2. Preliminaries

Let *H* be a real Hilbert space with $||x||^2 = \langle x, x \rangle$, 2^H the family of all nonempty bounded subsets of *H* and *C*(*H*) the family of all nonempty compact subsets of *H*. Let $\delta : 2^H \to [0, \infty)$ be defined by

$$\delta(A,B) = \sup\{\|a - b\| : a \in A, b \in B\}, \quad \forall A, B \in 2^{H},$$
(2.1)

and let \widetilde{H} : $C(H) \rightarrow [0, \infty)$ be defined by

$$\widetilde{H}(A,B) = \max\left\{\sup_{x\in A} d(x,B), \sup_{y\in B} d(A,y)\right\}, \quad \forall A,B \in C(H),$$
(2.2)

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where

$$d(x,B) = \inf_{y \in B} ||x - y||.$$
(2.3)

Then, $(2^H, \delta)$ and $(C(H), \tilde{H})$ are complete metric spaces, \tilde{H} is the Hausdorff metric on C(H).

We now consider the parametric problem of completely generalized quasi-variational inequalities. Let Ω be a nonempty open subset of H in which the parameter λ takes values and $K : H \times \Omega \to 2^H$ set-valued mapping with nonempty closed convex valued. Let $A, R, T : H \times \Omega \to 2^H$ be the set-valued mappings and $p, f, g, G : H \times \Omega \to H$ the singlevalued mappings. For each fixed $\lambda \in \Omega$, we write $G_{\lambda}(x) = G(x,\lambda)$, $u_{\lambda}(x) = u(x,\lambda)$ unless otherwise specified. The parametric problem of completely generalized quasi-variational inequality (PPCGQVI) consists in finding $x \in H$, $u_{\lambda}(x) \in A_{\lambda}(x)$, $w_{\lambda}(x) \in R_{\lambda}(x)$, $z_{\lambda}(x) \in$ $T_{\lambda}(x)$ such that $G_{\lambda}(x) \in K_{\lambda}(x)$ and

$$\langle p_{\lambda}(u_{\lambda}(x)) - (f_{\lambda}(w_{\lambda}(x)) - g_{\lambda}(z_{\lambda}(x))), y - G_{\lambda}(x) \rangle \ge 0, \quad \forall y \in K_{\lambda}(x).$$
 (2.4)

In many important applications, $K_{\lambda}(x)$ has the form

$$K_{\lambda}(x) = m(x) + K_{\lambda}, \quad \forall (x, \lambda) \in H \times \Omega,$$
 (2.5)

where $m: H \to H$ and $\{K_{\lambda} : \lambda \in \Omega\}$ is a family of nonempty closed and convex subsets of *H*, see, for example, [13] and the references therein.

For each $\lambda \in \Omega$, let $S(\lambda)$ denote the set of solutions to the problem (2.4). For some $\overline{\lambda} \in \Omega$, we fix those conditions under which for each λ in a neighborhood (say $N(\overline{\lambda})$) of $\overline{\lambda}$, problem (2.4) has a nonempty solution set, that is, $S(\lambda) \neq \emptyset$ near $S(\overline{\lambda})$ and the set-valued mappings $S(\lambda)$ is continuous or Lipschitz continuous under the metric δ or \widetilde{H} .

We need the following concepts and results.

LEMMA 2.1 [5]. For each $x, v \in H$,

$$x = P_K(v) \tag{2.6}$$

if and only if

$$\langle x - v, y - v \rangle \ge 0, \quad \forall y \in K,$$
 (2.7)

where $P_K(v)$ is the projection of $v \in H$ onto K.

LEMMA 2.2 [9]. Let $m: H \to H$ be a single-valued mapping and

$$K(x) = m(x) + K, \quad \forall x \in H.$$
(2.8)

Then

$$P_{K(x)}(y) = m(x) + P_K(y - m(x)), \quad \forall x, y \in H.$$
(2.9)

Definition 2.3 [12]. A single-valued mapping $G: H \times \Omega \rightarrow H$ is called:

(i) α -strongly monotone if there exists a constant $\alpha > 0$ such that

$$\langle G_{\lambda}(x) - G_{\lambda}(y), x - y \rangle \ge \alpha ||x - y||^2, \quad \forall (x, y, \lambda) \in H \times H \times \Omega;$$
 (2.10)

(ii) β - *Lipschitz continuous* if there exists a constant β > 0 such that

$$\left|\left|G_{\lambda}(x) - G_{\lambda}(y)\right|\right| \le \beta \|x - y\|, \quad \forall (x, y, \lambda) \in H \times H \times \Omega.$$
(2.11)

- *Definition 2.4* [1]. A set-valued mapping $R: H \times \Omega \rightarrow 2^H$ is said to be
 - (i) *relaxed Lipschitz with respect to a mapping* $f : H \times \Omega \rightarrow H$ if there exists a constant $r \ge 0$ such that

$$\langle f_{\lambda}(w_{\lambda}(x)) - f_{\lambda}(w_{\lambda}(y)), x - y \rangle \leq -r ||x - y||^{2},$$

$$\forall (x, y, \lambda) \in H \times H \times \Omega, \quad w_{\lambda}(x) \in R_{\lambda}(x), \quad w_{\lambda}(y) \in R_{\lambda}(y);$$

$$(2.12)$$

(ii) relaxed monotone with respect to a mapping $g : H \times \Omega \rightarrow H$ if there exists a constant s > 0 such that

$$\langle g_{\lambda}(w_{\lambda}(x)) - g_{\lambda}(w_{\lambda}(y)), x - y \rangle \geq -s ||x - y||^{2}, \forall (x, y, \lambda) \in H \times H \times \Omega, \quad w_{\lambda}(x) \in R_{\lambda}(x), \, w_{\lambda}(y) \in R_{\lambda}(y).$$

$$(2.13)$$

Definition 2.5 [2]. A set-valued mapping $A: H \times \Omega \to 2^H [A: H \times \Omega \to C(H)]$ is said to be η - δ -Lipschitz [η - \tilde{H} -Lipschitz] continuous if there exists a constant $\eta \ge 0$ such that

$$\delta(A_{\lambda}(x), A_{\lambda}(y)) \leq \eta ||x - y||, \quad \forall (x, y, \lambda) \in H \times H \times \Omega, \widetilde{H}(A_{\lambda}(x), A_{\lambda}(y)) \leq \eta ||x - y||, \quad \forall (x, y, \lambda) \in H \times H \times \Omega.$$
(2.14)

LEMMA 2.6. Let $K_{\lambda}(x)$ be defined as (2.5). Then for each fixed $\overline{\lambda} \in \Omega$, problem (2.4) has a solution $(x(\overline{\lambda}), u_{\overline{\lambda}}(x(\overline{\lambda})), w_{\overline{\lambda}}(x(\overline{\lambda})), z_{\lambda}(x(\overline{\lambda})))$ if and only if $\overline{x} = x(\overline{\lambda})$ is a fixed point of the set-valued mapping $\phi : H \times \Omega \to 2^{H}$ defined by

$$\phi_{\lambda}(x) = \bigcup_{\substack{u_{\lambda}(x) \in A_{\lambda}(x), w_{\lambda}(x) \in R_{\lambda}(x), z_{\lambda}(x) \in T_{\lambda}(x) \\ \left[x - G_{\lambda}(x) + m(x) + P_{K_{\lambda}} \left\{G_{\lambda}(x) - \rho(p_{\lambda}(u_{\lambda}(x)) - (f_{\lambda}(w_{\lambda}(x)) - g_{\lambda}(z_{\lambda}(x)))) - m(x)\right\}\right],$$

$$(2.15)$$

for each $x \in H$, where $\lambda = \overline{\lambda}$, $\rho > 0$ is some constant and $P_{K_{\lambda}}(v)$ is the projection of $v \in H$ onto $K_{\overline{\lambda}}$.

Proof. For any fixed $\overline{\lambda} \in \Omega$, let $(\overline{x}, u_{\overline{\lambda}}(\overline{x}), w_{\overline{\lambda}}(\overline{x}), z_{\overline{\lambda}}(\overline{x}))$ be a solution of problem (2.4). Then $\overline{x} \in H$, $u_{\overline{\lambda}}(\overline{x}) \in A_{\overline{\lambda}}(\overline{x})$, $w_{\overline{\lambda}}(\overline{x}) \in R_{\overline{\lambda}}(\overline{x})$ and $z_{\overline{\lambda}}(\overline{x}) \in T_{\overline{\lambda}}(\overline{x})$ such that $G_{\overline{\lambda}}(\overline{x}) \in K_{\overline{\lambda}}(\overline{x})$ and

$$\left\langle p_{\overline{\lambda}}(u_{\overline{\lambda}}(\overline{x})) - \left(f_{\overline{\lambda}}(w_{\overline{\lambda}}(\overline{x})) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(\overline{x}))\right), y - G_{\overline{\lambda}}(\overline{x})\right\rangle \ge 0, \quad \forall y \in K_{\overline{\lambda}}(\overline{x}).$$
(2.16)

Hence for any $\rho > 0$,

$$\left\langle G_{\overline{\lambda}}(\overline{x}) - \left[G_{\overline{\lambda}}(\overline{x}) - \rho \left(p_{\overline{\lambda}}(u_{\overline{\lambda}}(\overline{x})) - \left(f_{\overline{\lambda}}(w_{\overline{\lambda}}(\overline{x}) \right) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(\overline{x})) \right) \right], y - G_{\overline{\lambda}}(\overline{x}) \right\rangle \ge 0, \quad \forall y \in K_{\overline{\lambda}}(\overline{x}).$$

$$(2.17)$$

From Lemmas 2.1 and 2.2, we have

$$G_{\overline{\lambda}}(\overline{x}) = P_{K_{\overline{\lambda}}(\overline{x})} \Big[G_{\overline{\lambda}}(\overline{x}) - \rho \big(p_{\overline{\lambda}} \big(u_{\overline{\lambda}}(\overline{x}) \big) - \big(f_{\overline{\lambda}} \big(w_{\overline{\lambda}}(\overline{x}) \big) - g_{\overline{\lambda}} \big(z_{\overline{\lambda}}(\overline{x}) \big) \big) \big) \Big]$$

$$= m(\overline{x}) + P_{K_{\overline{\lambda}}} \Big[G_{\overline{\lambda}}(\overline{x}) - \rho \big(p_{\overline{\lambda}} \big(u_{\overline{\lambda}}(\overline{x}) \big) - \big(f_{\overline{\lambda}} \big(w_{\overline{\lambda}}(\overline{x}) \big) - g_{\overline{\lambda}} \big(z_{\overline{\lambda}}(\overline{x}) \big) \big) \big) - m(\overline{x}) \Big].$$
(2.18)

We can also write

$$\begin{aligned} \overline{x} &= \overline{x} - G_{\overline{\lambda}}(\overline{x}) + m(\overline{x}) \\ &+ P_{K_{\overline{\lambda}}} \Big[G_{\overline{\lambda}}(\overline{x}) - \rho \left(p_{\overline{\lambda}} \left(u_{\overline{\lambda}}(\overline{x}) \right) - \left(f_{\overline{\lambda}} \left(w_{\overline{\lambda}}(\overline{x}) \right) - g_{\overline{\lambda}} \left(z_{\overline{\lambda}}(\overline{x}) \right) \right) \right) - m(\overline{x}) \Big] \\ &\in \bigcup_{u_{\overline{\lambda}}(\overline{x}) \in A_{\overline{\lambda}}(\overline{x}), w_{\overline{\lambda}}(\overline{x}) \in R_{\overline{\lambda}}(\overline{x}), z_{\overline{\lambda}}(\overline{x}) \in T_{\overline{\lambda}}(\overline{x})} \\ &\left[\overline{x} - G_{\overline{\lambda}}(\overline{x}) + m(\overline{x}) \right. \\ &\left. + P_{K_{\overline{\lambda}}} \Big\{ G_{\overline{\lambda}}(\overline{x}) - \rho \left(p_{\overline{\lambda}} \left(u_{\overline{\lambda}}(\overline{x}) \right) - \left(f_{\overline{\lambda}} \left(w_{\overline{\lambda}}(\overline{x}) \right) - g_{\overline{\lambda}} \left(z_{\overline{\lambda}}(\overline{x}) \right) \right) \right) - m(\overline{x}) \Big\} \Big] = \phi_{\overline{\lambda}}(\overline{x}), \end{aligned}$$

$$(2.19)$$

that is, $\overline{x} = x(\overline{\lambda})$ is a fixed point of $\phi_{\overline{\lambda}}(\overline{x})$.

Now, for any fixed $\overline{\lambda} \in \Omega$, let $x(\overline{\lambda})$ be a fixed point of $\phi_{\overline{\lambda}}(\overline{x})$. By Lemma 2.1 there exist $u_{\overline{\lambda}}(\overline{x}) \in A_{\overline{\lambda}}(\overline{x})$, $w_{\overline{\lambda}}(\overline{x}) \in R_{\overline{\lambda}}(\overline{x})$ and $z_{\overline{\lambda}}(\overline{x}) \in T_{\overline{\lambda}}(\overline{x})$ such that

$$G_{\overline{\lambda}}(\overline{x}) = m(\overline{x}) + P_{K_{\overline{\lambda}}} \Big[G_{\overline{\lambda}}(\overline{x}) - \rho \big(p_{\overline{\lambda}} \big(u_{\overline{\lambda}}(\overline{x}) \big) - \big(f_{\overline{\lambda}} \big(w_{\overline{\lambda}} \quad (\overline{x}) \big) - g_{\overline{\lambda}} \big(z_{\overline{\lambda}}(\overline{x}) \big) \big) - m(\overline{x}) \Big]$$

$$= P_{K_{\overline{\lambda}}(\overline{x})} \Big[G_{\overline{\lambda}}(\overline{x}) - \rho \big(p_{\overline{\lambda}} \big(u_{\overline{\lambda}}(\overline{x}) \big) - \big(f_{\overline{\lambda}} \big(w_{\overline{\lambda}}(\overline{x}) \big) - g_{\overline{\lambda}} \big(z_{\overline{\lambda}}(\overline{x}) \big) \big) \Big].$$
(2.20)

Hence, we have $G_{\overline{\lambda}}(\overline{x}) \in K_{\overline{\lambda}}(\overline{x})$ and

$$\left\langle G_{\overline{\lambda}}(\overline{x}) - \left[G_{\overline{\lambda}}(\overline{x}) - \rho \left(p_{\overline{\lambda}}(u_{\overline{\lambda}}(\overline{x})) - \left(f_{\overline{\lambda}}(w_{\overline{\lambda}}(\overline{x})) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(\overline{x})) \right) \right], y - G_{\overline{\lambda}}(\overline{x}) \right\rangle \ge 0, \quad (2.21)$$

for all $y \in K_{\overline{\lambda}}(\overline{x})$.

Noting that $\rho > 0$, we have

$$\left\langle p_{\overline{\lambda}}(u_{\overline{\lambda}}(\overline{x})) - \left(f_{\overline{\lambda}}(w_{\overline{\lambda}}(\overline{x})) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(\overline{x}))\right), y - G_{\overline{\lambda}}(\overline{x})\right\rangle \ge 0, \quad \forall y \in K_{\overline{\lambda}}(\overline{x}),$$
(2.22)

 \square

that is, $(\overline{x}, u_{\overline{\lambda}}(\overline{x}), w_{\overline{\lambda}}(\overline{x}), z_{\overline{\lambda}}(\overline{x}))$ is a solution of the problem (2.4).

LEMMA 2.7. Let $K_{\lambda}(x)$ be defined as (2.5), $A, R, T : H \times \Omega \to 2^{H}$ the δ -Lipschitz continuous with respect to constants η, γ, ν , respectively, and $p, f, g, G : H \times \Omega \to H$ the Lipschitz continuous with respect to the constants ξ, χ, σ and β , respectively. Let G be strongly monotone with constant $\alpha > 0$, R relaxed Lipschitz continuous with respect to f with constant $r \ge 0$, T

relaxed monotone with respect to g with constant s > 0, and $m : H \to H$ is μ -Lipschitz continuous. If there exists a constant $\rho > 0$ such that

$$\left| \rho - \frac{(r-s) + \xi \eta (q-1)}{(\gamma \chi + \sigma \nu)^2 - (\xi \eta)^2} \right| < \frac{\sqrt{((r-s) + \xi \eta (q-1))^2 - q(q-1)((\gamma \chi + \sigma \nu)^2 - (\xi \eta)^2)}}{(\gamma \chi + \sigma \nu)^2 - (\xi \eta)^2} (r-s) > (1-q)\xi \eta + \sqrt{q(q-1)((\gamma \chi + \sigma \nu)^2 - (\xi \eta)^2)} \rho \xi \eta < \gamma \chi + \sigma \nu, q = 2(\mu + \sqrt{1 - 2\alpha + \beta^2}) < 1,$$
(2.23)

then the set-valued mapping $\phi : H \times \Omega \to 2^H$ defined by (2.15) is a uniform θ - δ -set-valued contraction with respect to $\lambda \in \Omega$, where

$$\theta = q + t(\rho) + \rho \xi \eta < 1,$$

$$t(\rho) = \sqrt{1 - 2\rho(r - s) + \rho^2(\gamma \chi + \sigma \nu)^2}.$$
(2.24)

Proof. By the definition of ϕ , for any $x, y \in H$, $\lambda \in \Omega$, $a \in \phi_{\lambda}(x)$ and $b \in \phi_{\lambda}(y)$, there exist $u_{\lambda}(x) \in A_{\lambda}(x)$, $u_{\lambda}(y) \in A_{\lambda}(y)$, $w_{\lambda}(x) \in R_{\lambda}(x)$, $w_{\lambda}(y) \in R_{\lambda}(y)$, $z_{\lambda}(x) \in T_{\lambda}(x)$ and $z_{\lambda}(y) \in T_{\lambda}(y)$ such that

$$a = x - G_{\lambda}(x) + m(x) + P_{K_{\lambda}}[G_{\lambda}(x) - \rho(p_{\lambda}(u_{\lambda}(x)) - (f_{\lambda}(w_{\lambda}(x)) - g_{\lambda}(z_{\lambda}(x)))) - m(x)],$$

$$b = y - G_{\lambda}(y) + m(y) + P_{K_{\lambda}}[G_{\lambda}(y) - \rho(p_{\lambda}(u_{\lambda}(y)) - (f_{\lambda}(w_{\lambda}(y)) - g_{\lambda}(z_{\lambda}(y)))) - m(y)].$$
(2.25)

Since projection operator is nonexpansive, we have

$$\begin{aligned} \|a - b\| &\leq 2||x - y - (G_{\lambda}(x) - G_{\lambda}(y))|| + 2||m(x) - m(y)|| \\ &+ ||x - y + \rho(f_{\lambda}(w_{\lambda}(y)) - f_{\lambda}(w_{\lambda}(y))) - \rho(g_{\lambda}(z_{\lambda}(x)) - g_{\lambda}(z_{\lambda}(y)))|| \\ &+ \rho||p_{\lambda}(u_{\lambda}(x)) - p_{\lambda}(u_{\lambda}(y))||. \end{aligned}$$
(2.26)

Since G is strongly monotone and Lipschitz continuous, we have

$$||x - y - (G_{\lambda}(x) - G_{\lambda}(y))||^{2} \leq (1 - 2\alpha + \beta^{2}) ||x - y||^{2},$$

$$||m(x) - m(y)|| \leq \mu ||x - y||,$$

$$||p_{\lambda}(\mu_{\lambda}(x)) - p_{\lambda}(u_{\lambda}(y))|| \leq \xi ||u_{\lambda}(x) - u_{\lambda}(y)|| \leq \xi \delta(A_{\lambda}(x), A_{\lambda}(y)) \leq \xi \eta ||x - y||.$$
(2.27)

Again

$$\begin{aligned} \left\| \left\| x - y + \rho \left(f_{\lambda} \left(w_{\lambda}(x) \right) - f_{\lambda} \left(w_{\lambda}(y) \right) \right) - \rho \left(g_{\lambda} \left(z_{\lambda}(x) \right) - g_{\lambda} \left(z_{\lambda}(y) \right) \right) \right\|^{2} \\ &= \left\| x - y \right\|^{2} + 2\rho \left\langle f_{\lambda} \left(w_{\lambda}(x) \right) - f_{\lambda} \left(w_{\lambda}(y) \right), x - y \right\rangle - 2\rho \left\langle g_{\lambda} \left(z_{\lambda}(x) \right) - g_{\lambda} \left(z_{\lambda}(y) \right), x - y \right\rangle \\ &+ \rho^{2} \left\| f_{\lambda} \left(w_{\lambda}(x) \right) - f_{\lambda} \left(w_{\lambda}(y) \right) - \left(g_{\lambda} \left(z_{\lambda}(x) \right) - g_{\lambda} \left(z_{\lambda}(y) \right) \right) \right\|^{2} \\ &\leq \left[1 - 2\rho (r - s) + \rho^{2} (\gamma \chi + \sigma \gamma)^{2} \right] \left\| x - y \right\|^{2}. \end{aligned}$$

$$(2.28)$$

From (2.26)–(2.28), we have

$$||a - b|| \le [q + t(\rho) + \rho \xi \eta] ||x - y|| \le \theta ||x - y||,$$
(2.29)

where

$$\theta = q + t(\rho) + \rho \xi \eta,$$

$$t(\rho) = \sqrt{1 - 2\rho(r - s) + \rho^2(\gamma \chi + \rho \nu)^2},$$

$$q = 2\left(\mu + \sqrt{1 - 2\alpha + \beta^2}\right).$$
(2.30)

By the arbitrariness of *a* and *b*, we have

$$\delta(\phi_{\lambda}(x),\phi_{\lambda}(y)) \le \theta d(x,y). \tag{2.31}$$

By conditions (2.23) and (2.24), we have $\theta < 1$. This proves that θ is a uniform θ - δ -set-valued contraction with respect to $\lambda \in \Omega$.

LEMMA 2.8 [6]. Let X be a complete metric space and $T_1, T_2 : X \to C(X)$ be $\theta - \tilde{H}$ -contraction mapping. Then

$$\widetilde{H}(F(T_1), F(T_2)) \le \left[\frac{1}{1-\theta}\right] \sup_{x \in X} \widetilde{H}(T_1(x), T_2(x)),$$
(2.32)

where $F(T_1)$ and $F(T_2)$ are the sets of fixed points of T_1 and T_2 , respectively.

3. Sensitivity analysis

THEOREM 3.1. Assume that $A_{\lambda}(\overline{x})$, $R_{\lambda}(\overline{x})$ and $T_{\lambda}(\overline{x})$ are δ -Lipschitz continuous at $\overline{\lambda}$. Let $R_{\lambda}(\overline{x})$ be the relaxed Lipschitz continuous with $f_{\lambda}(\cdot)$ at $\overline{\lambda}$, and $T_{\lambda}(\overline{x})$ the relaxed monotone with $g_{\lambda}(\cdot)$ at $\overline{\lambda}$. Suppose that $G_{\lambda}(\overline{x})$, $p_{\lambda}(\cdot)$, $f_{\lambda}(\cdot)$, $g_{\lambda}(\cdot)$ and $P_{K_{\lambda}}(v)$ are Lipschitz continuous at $\overline{\lambda}$, where $\overline{x} = \overline{x}(\overline{\lambda}) \in S(\overline{\lambda})$, $\overline{u}_{\overline{\lambda}}(\overline{x}) \in A_{\overline{\lambda}}(\overline{x})$, $\overline{w}_{\overline{\lambda}}(\overline{x}) \in R_{\overline{\lambda}}(\overline{x})$, $\overline{z}_{\overline{\lambda}}(\overline{x}) \in T_{\overline{\lambda}}(\overline{x})$ and

$$v = G_{\overline{\lambda}}(\overline{x}) - \rho \left(p_{\overline{\lambda}}(\overline{u}_{\overline{\lambda}}(\overline{x})) - \left(f_{\overline{\lambda}}(\overline{w}_{\overline{\lambda}}(\overline{x})) - g_{\overline{\lambda}}(\overline{z}_{\overline{\lambda}}(\overline{x})) \right) \right) - m(\overline{x}).$$
(3.1)

Then for all $\lambda \in \Omega$, the solution set $S(\lambda)$ of the problem (2.4) is nonempty and $S(\lambda)$ is δ -Lipschitz continuous at $\overline{\lambda}$.

Proof. For each fixed $\lambda \in \Omega$, $\phi_{\lambda}(x)$ has a fixed point, that is, there exists a $x(\overline{\lambda}) \in H$ such that $x(\lambda) \in \phi_{\lambda}(x(\lambda))$. From Lemma 2.6, we have $x(\lambda) \in S(\lambda)$, hence $S(\lambda) \neq \emptyset$ and $S(\lambda)$ coincides with the set of fixed point of $\phi_{\lambda}(x)$. In particular, $S(\overline{\lambda})$ coincides with the set of

fixed point of $\phi_{\overline{\lambda}}(x)$. Now we show that $S(\lambda)$ is δ -Lipschitz continuous at $\overline{\lambda}$. For all $x(\lambda) \in S(\lambda)$ and $\overline{x}(\overline{\lambda}) \in S(\overline{\lambda})$ there exist $u_{\lambda}(x(\lambda)) \in A_{\lambda}(x(\lambda)), w_{\lambda}(x(\lambda)) \in R_{\lambda}(x(\lambda)), z_{\lambda}(x(\lambda)) \in T_{\overline{\lambda}}(\overline{x}(\overline{\lambda})) \in A_{\overline{\lambda}}(\overline{x}(\overline{\lambda})) \in R_{\overline{\lambda}}(\overline{x}(\overline{\lambda})) = R_{\overline{\lambda}}(\overline{x}(\overline{\lambda})) = R_{\overline{\lambda}}(\overline{x}(\overline{\lambda})) \in T_{\overline{\lambda}}(\overline{x}(\overline{\lambda})) = T_{\overline{\lambda}}(\overline{x}(\overline{\lambda}))$ such that $x(\lambda) = x(\lambda) - G_{\lambda}(x(\lambda)) + m(x(\lambda)) + m(x(\lambda)) + P_{K_{\lambda}}[G_{\lambda}(x(\lambda)) - \rho(p_{\lambda}(u_{\lambda}(x(\lambda))) - (f_{\lambda}(w_{\lambda}(x(\lambda))) - g_{\lambda}(z_{\lambda}(x(\lambda))))) - m(x(\lambda))],$ $\overline{x}(\overline{\lambda}) = \overline{x}(\overline{\lambda}) - G_{\overline{\lambda}}(\overline{x}(\overline{\lambda})) + m(\overline{x}(\overline{\lambda})) + P_{K_{\overline{\lambda}}}[G_{\overline{\lambda}}(\overline{x}(\overline{\lambda})) - \rho(p_{\overline{\lambda}}(\overline{u}_{\overline{\lambda}}(\overline{x}(\overline{\lambda}))) - (f_{\overline{\lambda}}(\overline{w}_{\overline{\lambda}}(\overline{x}(\overline{\lambda}))) - g_{\overline{\lambda}}(\overline{z}_{\overline{\lambda}}(\overline{x}(\overline{\lambda}))))) - m(\overline{x}(\overline{\lambda}))].$ (3.2)

Write $x = x(\lambda)$ and $\overline{x} = \overline{x}(\overline{\lambda})$. Taking any $u_{\lambda}(\overline{x}) \in A_{\lambda}(\overline{x})$, $w_{\lambda}(\overline{x}) \in R_{\lambda}(\overline{x})$ and $z_{\lambda}(\overline{x}) \in T_{\lambda}(\overline{x})$, we have

$$\begin{split} \|x - \overline{x}\| &\leq \left\| |x - G_{\lambda}(x) + m(x) \right\| \\ &+ P_{K_{\lambda}} \left[G_{\lambda}(x) - \rho\left(p_{\lambda}\left(u_{\lambda}(x)\right) - \left(f_{\lambda}\left(w_{\lambda}(x)\right) - g_{\lambda}\left(z_{\lambda}(x)\right) \right) \right) - m(x) \right] \\ &- \left[\overline{x} - G_{\lambda}(\overline{x}) + m(\overline{x}) \right] \\ &+ P_{K_{\lambda}} \left\{ G_{\lambda}(\overline{x}) - \rho\left(p_{\lambda}\left(u_{\lambda}(\overline{x})\right) - \left(f_{\lambda}\left(w_{\lambda}(\overline{x})\right) - g_{\lambda}\left(z_{\lambda}(\overline{x})\right) \right) \right) - m(\overline{x}) \right\} \right] \\ &+ \left\| |\overline{x} - G_{\lambda}(\overline{x}) + m(\overline{x}) \right\| \\ &+ P_{K_{\lambda}} \left[G_{\lambda}(\overline{x}) - \rho\left(p_{\lambda}(u_{\lambda}(\overline{x})) - \left(f_{\lambda}\left(w_{\lambda}(\overline{x})\right) - g_{\lambda}\left(z_{\lambda}(\overline{x})\right) \right) \right) - m(\overline{x}) \right] \\ &- \left[\overline{x} - G_{\overline{\lambda}}(\overline{x}) + m(\overline{x}) \right] \\ &+ P_{K_{\overline{\lambda}}} \left\{ G_{\overline{\lambda}}(\overline{x}) - \rho\left(p_{\overline{\lambda}}\left(\overline{u}_{\overline{\lambda}}(\overline{x})\right) - \left(f_{\overline{\lambda}}\left(\overline{w}_{\overline{\lambda}}(\overline{x})\right) - g_{\overline{\lambda}}\left(\overline{z}_{\overline{\lambda}}(\overline{x})\right) \right) \right) - m(\overline{x}) \right\} \right] \\ &\leq \theta \| x - \overline{x}\| + \left\| G_{\lambda}(\overline{x}) - G_{\overline{\lambda}}(\overline{x}) \right\| \\ &+ \left\| P_{K_{\lambda}} \left[G_{\lambda}(\overline{x}) - \rho\left(p_{\lambda}(u_{\lambda}(\overline{x})) - \left(f_{\lambda}\left(w_{\lambda}(\overline{x})\right) - g_{\lambda}(z_{\lambda}(\overline{x})) \right) \right) - m(\overline{x}) \right] \\ &- P_{K_{\overline{\lambda}}} \left[G_{\overline{\lambda}}(\overline{x}) - \rho\left(p_{\overline{\lambda}}(\overline{u}_{\overline{\lambda}}(\overline{x}) \right) - \left(f_{\overline{\lambda}}\left(\overline{w}_{\overline{\lambda}}(\overline{x})\right) - g_{\overline{\lambda}}(\overline{z}_{\overline{\lambda}}(\overline{x})) \right) \right) - m(\overline{x}) \right] \\ &+ \left\| P_{K_{\lambda}} \left[G_{\overline{\lambda}}(\overline{x}) - \rho\left(p_{\overline{\lambda}}(\overline{u}_{\overline{\lambda}}(\overline{x}) \right) - \left(f_{\overline{\lambda}}(\overline{w}_{\overline{\lambda}}(\overline{x}) \right) - g_{\overline{\lambda}}(\overline{z}_{\overline{\lambda}}(\overline{x})) \right) - m(\overline{x}) \right] \\ & \leq \theta \| x - \overline{x}\| + 2 \left\| G_{\lambda}(\overline{x}) - \rho\left(p_{\overline{\lambda}}(\overline{u}_{\overline{\lambda}}(\overline{x}) \right) - \left(f_{\overline{\lambda}}(\overline{w}_{\overline{\lambda}}(\overline{x}) \right) - g_{\overline{\lambda}}(\overline{z}_{\overline{\lambda}}(\overline{x})) \right\| \\ &+ \rho \left\| f_{\lambda}\left(w_{\lambda}(\overline{x})\right) - f_{\overline{\lambda}}(\overline{w}_{\overline{\lambda}}(\overline{x})) \right\| \\ &+ \rho \left\| g_{\lambda}\left(z_{\lambda}(\overline{x})\right) - g_{\overline{\lambda}}(\overline{z}_{\overline{\lambda}}(\overline{x}) \right) \right\| + \left\| P_{K_{\lambda}}(\nu) - P_{K_{\overline{\lambda}}}(\nu) \right\|$$

where, $v = G_{\overline{\lambda}}(\overline{x}) - \rho(p_{\overline{\lambda}}(\overline{u}_{\overline{\lambda}}(\overline{x})) - (f_{\overline{\lambda}}(\overline{w}_{\overline{\lambda}}(\overline{x})) - g_{\overline{\lambda}}(\overline{z}_{\overline{\lambda}}(\overline{x})))) - m(\overline{x})$. Since, $x = x(\lambda) \in S(\lambda)$ and $\overline{x} = \overline{x}(\overline{\lambda}) \in S(\overline{\lambda})$ are arbitrary, it follows that

$$\delta(S(\lambda), S(\overline{\lambda})) \leq \left[\frac{1}{1-\theta}\right] \left[2||G_{\lambda}(\overline{x}) - G_{\overline{\lambda}}(\overline{x})|| + \rho||p_{\lambda}(u_{\lambda}(\overline{x})) - p_{\overline{\lambda}}(\overline{u}_{\overline{\lambda}}(\overline{x}))|| + \rho||f_{\lambda}(w_{\lambda}(\overline{x})) - f_{\overline{\lambda}}(\overline{w}_{\overline{\lambda}}(\overline{x}))|| + \rho||g_{\lambda}(z_{\lambda}(\overline{x})) - g_{\overline{\lambda}}(\overline{z}_{\overline{\lambda}}(\overline{x}))|| + ||P_{K_{\lambda}}(v) - P_{K_{\overline{\lambda}}}(v)||\right].$$

$$(3.4)$$

From the δ -Lipschitz continuity of A, R, T at $\overline{\lambda}$; Lipschitz continuity of G and $P_{K_{\lambda}}(\nu)$ at $\overline{\lambda}$, it follows that $S(\lambda)$ is δ -Lipschitz continuous.

THEOREM 3.2. If we assume the hypothesis of Lemma 2.7, then

- (i) $\phi: H \times \Omega \rightarrow C(H)$ defined by (2.15) is a compact valued uniform θ - \tilde{H} -contraction mapping with respect to $\lambda \in \Omega$;
- (ii) for each $\lambda \in \Omega$, (2.4) has nonempty solution set $S(\lambda)$, closed in H.

Proof. (i) For each $(x,\lambda) \in H \times \Omega$; $A_{\lambda}(x)$, $R_{\lambda}(x)$, $T_{\lambda}(x) \in C(H)$ and $P_{K_{\lambda}}$ are continuous, follows from (2.15) of $\phi_{\lambda}(x) \in C(H)$. Now, we show that $\phi_{\lambda}(x)$ is a uniform θ - \tilde{H} -contraction mapping with respect to $\lambda \in \Omega$. For any $a \in \phi_{\lambda}(x)$, there exist $u_{\lambda}(x) \in A_{\lambda}(x) \in C(H)$, $w_{\lambda}(x) \in R_{\lambda}(x) \in C(H)$ and $z_{\lambda}(x) \in T_{\lambda}(x) \in C(H)$ such that

$$a = x - G_{\lambda}(x) + m(x) + P_{K_{\lambda}} [G_{\lambda}(x) - \rho(p_{\lambda}(u_{\lambda}(x)) - (f_{\lambda}(w_{\lambda}(x)) - g_{\lambda}(z_{\lambda}(x)))) - m(x)].$$
(3.5)

Note that $(y,\lambda) \in H \times \Omega$; $A_{\lambda}(y)$, $R_{\lambda}(y)$, $T_{\lambda}(y) \in C(H)$, then there exist $u_{\lambda}(y) \in A_{\lambda}(y)$, $w_{\lambda}(y) \in R_{\lambda}(y)$ and $z_{\lambda}(y) \in T_{\lambda}(y)$ such that

$$\begin{split} ||p_{\lambda}(u_{\lambda}(x)) - p_{\lambda}(u_{\lambda}(y))|| &\leq \xi ||u_{\lambda}(x) - u_{\lambda}(y)|| \leq \xi \widetilde{H}(A_{\lambda}(x), A_{\lambda}(y)), \\ ||f_{\lambda}(w_{\lambda}(x)) - f_{\lambda}(w_{\lambda}(y))|| &\leq \chi ||w_{\lambda}(x) - w_{\lambda}(y)|| \leq \chi \widetilde{H}(R_{\lambda}(x), R_{\lambda}(y)), \\ ||g_{\lambda}(z_{\lambda}(x)) - g_{\lambda}(z_{\lambda}(y))|| &\leq \sigma ||z_{\lambda}(x) - z_{\lambda}(y)|| \leq \sigma \widetilde{H}(T_{\lambda}(x), T_{\lambda}(y)). \end{split}$$
(3.6)

Let

$$b = y - G_{\lambda}(y) + m(y) + P_{K_{\lambda}}[G_{\lambda}(y) - \rho(p_{\lambda}(u_{\lambda}(y)) - (f_{\lambda}(w_{\lambda}(y)) - g_{\lambda}(z_{\lambda}(y)))) - m(y)],$$
(3.7)

then

$$b \in \phi_{\lambda}(y).$$
 (3.8)

By using the similar argument as in the proof of Lemma 2.7, we can obtain

$$\begin{aligned} \|a - b\| &\leq \left[2(\mu + \sqrt{1 - 2\alpha + \beta^2}) + \sqrt{1 - 2\rho(r - s) + \rho^2(\gamma \chi + \sigma \nu)^2} + \rho \xi \eta \right] \|x - y\| \\ &\leq \left[q + t(\rho) + \rho \xi \eta \right] \|x - y\| \leq \theta \|x - y\|, \end{aligned}$$
(3.9)

where

$$\theta = q + t(\rho) + \rho \xi \eta,$$

$$t(\rho) = \sqrt{1 - 2\rho(r - s) + \rho^2(\gamma \chi + \sigma \nu)^2},$$

$$q = 2\left(\mu + \sqrt{1 - 2\alpha + \beta^2}\right).$$
(3.10)

 \Box

By conditions (2.23) and (2.24), $\theta < 1$, and hence we have

$$\sup_{a \in \phi_{\lambda}(x)} d(a, \phi_{\lambda}(y)) \le \theta \|x - y\|.$$
(3.11)

By the similar arguments, we have

$$\sup_{b \in \phi_{\lambda}(y)} d(\phi_{\lambda}(x), b) \le \theta ||x - y||.$$
(3.12)

Hence, by the Hausdorff metric \tilde{H} , we obtain

$$\widetilde{H}(\phi_{\lambda}(x),\phi_{\lambda}(y)) \le \theta \|x - y\|.$$
(3.13)

Therefore $\phi_{\lambda}(x)$ is a uniform θ - \tilde{H} -contraction mapping with respect to $\lambda \in \Omega$.

(ii) Since $\phi_{\lambda}(x)$ is a uniform θ - \tilde{H} -contraction with respect to $\lambda \in \Omega$, hence by Nadler theorem [8], $\phi_{\lambda}(x)$ has a fixed point $x(\lambda)$. Since $S(\lambda) \neq \emptyset$, then let $\{x_n\} \subset S(\lambda)$ and $x_n \to x_0$ as $n \to \infty$. Therefore,

$$x_n \in \phi_\lambda(x_n), \quad n = 1, 2, \dots \tag{3.14}$$

From (i), we have

$$\widetilde{H}(\phi_{\lambda}(x_n),\phi_{\lambda}(x_0)) \le \theta \|x_n - x_0\|.$$
(3.15)

If follows that

$$d(x_0,\phi_{\lambda}(x_0)) \le ||x_0 - x_n|| + d(x_n,\phi_{\lambda}(x_n)) + \tilde{H}(\phi_{\lambda}(x_n),\phi_{\lambda}(x_0))$$

$$\le (1+\theta)||x_n - x_0|| \longrightarrow 0, \quad \text{as } n \longrightarrow \infty,$$
(3.16)

hence $x_0 \in \phi_{\lambda}(x_0)$ and $x_0 \in S(\lambda)$. Therefore $S(\lambda)$ is closed in H.

THEOREM 3.3. Assume the hypothesis as in Theorem 3.1. Then for all $\lambda \in \Omega$, the solution set $S(\lambda)$ of (2.4) is nonempty and $S(\lambda)$ is \tilde{H} -Lipschitz continuous at $\overline{\lambda}$.

Proof. From Theorem 3.2(ii), the solution set $S(\lambda)$ of (2.4) is a nonempty closed set in H. Now, we show that $S(\lambda)$ is \tilde{H} -Lipschitz continuous at $\bar{\lambda}$. By Theorem 3.2(i), $\phi_{\lambda}(x)$ and $\phi_{\bar{\lambda}}(x)$ are both θ - \tilde{H} -contraction mappings. From Lemma 2.8, we have

$$\widetilde{H}(S(\lambda), S(\overline{\lambda})) \leq \left[\frac{1}{1-\theta}\right] \sup_{x \in H} \widetilde{H}(\phi_{\lambda}(x), \phi_{\overline{\lambda}}(x)).$$
(3.17)

Taking any $a \in \phi_{\lambda}(x)$, $\exists u_{\lambda}(x) \in A_{\lambda}(x)$, $w_{\lambda}(x) \in R_{\lambda}(x)$ and $z_{\lambda}(x) \in T_{\lambda}(x)$ such that

$$a = x - G_{\lambda}(x) + m(x) + P_{K_{\lambda}}[G_{\lambda}(x) - \rho(p_{\lambda}(u_{\lambda}(x)) - (f_{\lambda}(w_{\lambda}(x)) - g_{\lambda}(z_{\lambda}(x)))) - m(x)].$$
(3.18)

For $u_{\lambda}(x) \in A_{\lambda}(x) \in C(H)$, $w_{\lambda}(x) \in R_{\lambda}(x) \in C(H)$, $z_{\lambda}(x) \in T_{\lambda}(x) \in C(H)$, there exist $u_{\overline{\lambda}}(x) \in A_{\overline{\lambda}}(x)$, $w_{\overline{\lambda}}(x) \in R_{\overline{\lambda}}(x)$ and $z_{\overline{\lambda}}(x) \in T_{\overline{\lambda}}(x)$ such that

$$\begin{aligned} \left| \left| u_{\lambda}(x) - u_{\overline{\lambda}}(x) \right| \right| &\leq \widetilde{H}\left(A_{\lambda}(x), A_{\overline{\lambda}}(x)\right), \\ \left| \left| w_{\lambda}(x) - w_{\overline{\lambda}}(x) \right| \right| &\leq \widetilde{H}\left(R_{\lambda}(x), R_{\overline{\lambda}}(x)\right), \\ \left| \left| z_{\lambda}(x) - z_{\overline{\lambda}}(x) \right| \right| &\leq \widetilde{H}\left(T_{\lambda}(x), T_{\overline{\lambda}}(x)\right). \end{aligned}$$
(3.19)

Let

$$b = x - G_{\overline{\lambda}}(x) + m(x) + P_{K_{\overline{\lambda}}} [G_{\overline{\lambda}}(x) - \rho(p_{\overline{\lambda}}(u_{\overline{\lambda}}(x)) - (f_{\overline{\lambda}}(w_{\overline{\lambda}}(x)) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(x)))) - m(x)],$$
(3.20)

then

$$b \in \phi_{\overline{\lambda}}(x). \tag{3.21}$$

It follows that

$$\begin{split} \|a - b\| &\leq \left\| |G_{\lambda}(x) - G_{\overline{\lambda}}(x)| \right\| \\ &+ \left\| P_{K_{\lambda}} \{G_{\lambda}(x) - \rho(p_{\lambda}(u_{\lambda}(x)) - (f_{\lambda}(w_{\lambda}(x)) - g_{\lambda}(z_{\lambda}(x)))) - m(x) \} \right\| \\ &- P_{K_{\lambda}} \{G_{\overline{\lambda}}(x) - \rho(p_{\overline{\lambda}}(u_{\overline{\lambda}}(x)) - (f_{\overline{\lambda}}(w_{\overline{\lambda}}(x)) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(x)))) - m(x) \} \| \\ &+ \left\| P_{K_{\lambda}} \{G_{\overline{\lambda}}(x) - \rho(p_{\overline{\lambda}}(u_{\overline{\lambda}}(x)) - (f_{\overline{\lambda}}(w_{\overline{\lambda}}(x)) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(x)))) - m(x) \} \right\| \\ &- P_{K_{\overline{\lambda}}} \{G_{\overline{\lambda}}(x) - \rho(p_{\overline{\lambda}}(u_{\overline{\lambda}}(x)) - (f_{\overline{\lambda}}(w_{\overline{\lambda}}(x)) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(x)))) - m(x) \} \| \\ &\leq 2 \| [G_{\lambda}(x) - G_{\overline{\lambda}}(x)] \| + \rho \| p_{\lambda}(u_{\lambda}(x)) - p_{\overline{\lambda}}(u_{\overline{\lambda}}(x)) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(x))) \| \\ &+ \rho \| f_{\lambda}(w_{\lambda}(x)) - f_{\overline{\lambda}}(w_{\overline{\lambda}}(x)) \| + \rho \| g_{\lambda}(z_{\lambda}(x)) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(x)) \| \\ &+ \rho \| p_{\lambda}(u_{\lambda}(x)) - p_{\overline{\lambda}}(u_{\lambda}(x)) \| + \rho \| p_{\overline{\lambda}}(u_{\lambda}(x)) - p_{\overline{\lambda}}(u_{\overline{\lambda}}(x)) \| \\ &+ \rho \| g_{\lambda}(z_{\lambda}(x)) - g_{\overline{\lambda}}(z_{\lambda}(x)) \| + \rho \| g_{\overline{\lambda}}(z_{\lambda}(x)) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(x)) \| \\ &+ \rho \| g_{\lambda}(z_{\lambda}(x)) - g_{\overline{\lambda}}(z_{\lambda}(x)) \| + \rho \| g_{\overline{\lambda}}(z_{\lambda}(x)) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(x)) \| \\ &+ \rho \| g_{\lambda}(z_{\lambda}(x)) - g_{\overline{\lambda}}(z_{\lambda}(x)) \| + \rho \| g_{\overline{\lambda}}(z_{\lambda}(x)) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(x)) \| \\ &+ \| P_{K_{\lambda}}(v) - P_{K_{\overline{\lambda}}}(v) \| , \end{split}$$

where $v = G_{\overline{\lambda}}(x) - \rho(p_{\overline{\lambda}}(u_{\overline{\lambda}}(x)) - (f_{\overline{\lambda}}(w_{\overline{\lambda}}(x)) - g_{\overline{\lambda}}(z_{\overline{\lambda}}(x)))) - m(x)$. Write

$$M = 2||G_{\lambda}(x) - G_{\overline{\lambda}}(x)|| + \rho||p_{\lambda}(u_{\lambda}(x)) - p_{\overline{\lambda}}(u_{\lambda}(x))|| + \rho||f_{\lambda}(w_{\lambda}(x)) - f_{\overline{\lambda}}(w_{\lambda}(x))|| + \rho||g_{\lambda}(z_{\lambda}(x)) - g_{\overline{\lambda}}(z_{\lambda}(x))|| + \rho\xi\widetilde{H}(A_{\lambda}(x), A_{\overline{\lambda}}(x)) + \rho\chi\widetilde{H}(R_{\lambda}(x), R_{\overline{\lambda}}(x)) + \rho\sigma\widetilde{H}(T_{\lambda}(x), T_{\overline{\lambda}}(x)) + ||P_{K_{\lambda}}(v) - P_{K_{\overline{\lambda}}}(v)||.$$

$$(3.23)$$

Then we have

$$\sup_{a \in \phi_{\lambda}(x)} d(a, \phi_{\overline{\lambda}}(x)) \le M.$$
(3.24)

By the similar arguments, we obtain

$$\sup_{b\in\phi_{\bar{\lambda}}(x)}d(\phi_{\lambda}(x),b)\leq M.$$
(3.25)

It follows that

$$\widetilde{H}(\phi_{\lambda}(x), \phi_{\overline{\lambda}}(x)) \le M.$$
(3.26)

If $A_{\lambda}(x)$, $R_{\lambda}(x)$ and $T_{\lambda}(x)$ are uniformly \tilde{H} -Lipschitz continuous at $\bar{\lambda}$ with respect to $x \in H$, and $G_{\lambda}(x)$, $P_{K_{\lambda}}(v)$ are uniformly Lipschitz continuous at $\bar{\lambda}$ with respect to $x \in H$, then it follows that: for any $\epsilon > 0$, there exists a $\delta > 0$ such that for all $\lambda \in \Omega$ with $||\lambda - \bar{\lambda}|| < \delta$,

$$\widetilde{H}(\phi_{\lambda}(x), \phi_{\overline{\lambda}}(x)) \le M < \epsilon, \quad \forall x \in H.$$
(3.27)

From (3.17), we obtain

$$H(S(\lambda), S(\overline{\lambda})) < \frac{\epsilon}{1-\theta}, \tag{3.28}$$

hence $S(\lambda)$ is \tilde{H} -continuous at $\bar{\lambda}$. If $A_{\lambda}(x)$, $R_{\lambda}(x)$ and $T_{\lambda}(x)$ are uniformly \tilde{H} -Lipschitz continuous at $\bar{\lambda}$ with respect to $x \in H$, and $G_{\lambda}(x)$, $P_{K_{\lambda}}(v)$ are also uniformly Lipschitz continuous at $\bar{\lambda}$ with respect to $x \in H$, then by the above arguments, we can prove that $S(\lambda)$ is \tilde{H} -Lipschitz continuous.

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