Research Article

# On the Solution $n$-Dimensional of the Product $\otimes^{k}$ Operator and Diamond Bessel Operator 

Wanchak Satsanit and Amnuay Kananthai<br>Department of Mathematics, Chiangmai University, Chiangmai 50200, Thailand

Correspondence should be addressed to Amnuay Kananthai, malamnaka@science.cmu.ac.th
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Firstly, we studied the solution of the equation $\otimes^{k} \diamond_{B}^{k} u(x)=f(x)$ where $u(x)$ is an unknown unknown function for $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right) \in \mathbb{R}^{n}, f(x)$ is the generalized function, $k$ is a positive integer. Finally, we have studied the solution of the nonlinear equation $\otimes^{k} \diamond_{B}^{k} u(x)=$ $f\left(x, \square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)\right)$. It was found that the existence of the solution $u(x)$ of such an equation depends on the condition of $f$ and $\square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)$. Moreover such solution $u(x)$ is related to the inhomogeneous wave equation depending on the conditions of $p, q$, and $k$.

## 1. Introduction

The operator $\diamond^{k}$ has been first introduced by Kananthai (see [1]), is named as the Diamond operator iterated $k$-times, and is defined by

$$
\begin{equation*}
\diamond^{k}=\left(\left(\sum_{i=1}^{p} \frac{\partial^{2}}{\partial x_{i}^{2}}\right)^{2}-\left(\sum_{j=p+1}^{p+q} \frac{\partial^{2}}{\partial x_{j}^{2}}\right)^{2}\right)^{k}, \quad p+q=n . \tag{1.1}
\end{equation*}
$$

$n$ is the dimension of the space $\mathbb{R}^{n}$, for $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right) \in \mathbb{R}^{n}$ and $k$ is a nonnegative integer. The operator $\nabla^{k}$ can be expressed in the form $\diamond^{k}=\Delta^{k} \square^{k}=\square^{k} \Delta^{k}$, where $\Delta^{k}$ is the Laplacian operator itrerated $k$-times defined by

$$
\begin{equation*}
\Delta^{k}=\left(\frac{\partial^{2}}{\partial x_{1}^{2}}+\frac{\partial^{2}}{\partial x_{2}^{2}}+\cdots+\frac{\partial^{2}}{\partial x_{n}^{2}}\right)^{k} \tag{1.2}
\end{equation*}
$$

and $\square^{k}$ is the ultrahyperbolic operator iterated $k$-times defined by

$$
\begin{equation*}
\square^{k}=\left(\frac{\partial^{2}}{\partial x_{1}^{2}}+\frac{\partial^{2}}{\partial x_{2}^{2}}+\cdots+\frac{\partial^{2}}{\partial x_{p}^{2}}-\frac{\partial^{2}}{\partial x_{p+1}^{2}}-\frac{\partial^{2}}{\partial x_{p+2}^{2}}-\cdots-\frac{\partial^{2}}{\partial x_{p+q}^{2}}\right)^{k} \tag{1.3}
\end{equation*}
$$

Kananthai (see [1, Theorem 3.1, page 33]) has shown that the convolution $(-1)^{k} R_{2 \mathrm{k}}^{e}(x) * R_{2 k}^{H}(x)$ is an elementary solution of the operator $\diamond^{k}$, that is,

$$
\begin{equation*}
\diamond^{k}\left((-1)^{k} R_{2 k}^{e}(x) * R_{2 k}^{H}(x)\right)=\delta(x) \tag{1.4}
\end{equation*}
$$

Next, Kananthai (see [2]) has studied the linear equation

$$
\begin{equation*}
\diamond^{k} u(x)=f(x) \tag{1.5}
\end{equation*}
$$

This equation is the generalization of the ultrahyperbolic equation and it can be applied to the wave equation. We obtain $u(x)=(-1)^{k} M_{2 k, 2 k}(x) * f(x)$ as a solution of such an equation (1.5) where

$$
\begin{equation*}
M_{2 k, 2 k}=R_{2 k}^{H}(x) * R_{2 k}^{e}(x) \tag{1.6}
\end{equation*}
$$

The function $R_{2 k}^{H}(x)$ is called the ultrahyperbolic kernel defined by (2.2) and $R_{2 k}^{e}(x)$ is called the elliptic kernel defined by (2.8), with $\alpha=2 k$.

Furthermore, Yıld $\imath \mathrm{r} \imath \mathrm{m}$ et al. (see [3]) first introduced the $\diamond_{B}^{k}$ operator that is named as Diamond Bessel operator, where $\diamond_{B}^{k}$ is defined by

$$
\begin{equation*}
\diamond_{B}^{k}=\left[\left(\sum_{i=1}^{p} B_{x_{i}}\right)^{2}-\left(\sum_{j=p+1}^{p+q} B_{x_{j}}\right)^{2}\right]^{k} \tag{1.7}
\end{equation*}
$$

and $B_{x_{i}}=\partial^{2} / \partial x_{i}^{2}+\left(2 v_{i} / x_{i}\right)\left(\partial / \partial x_{i}\right), 2 v_{i}=2 \alpha_{i}+1, \alpha_{i}>-1 / 2, x_{i}>0$. The operator $\diamond_{B}^{k}$ can be expressed by $\diamond_{B}^{k}=\Delta_{B}^{k} \square_{B}^{k}=\square_{B}^{k} \Delta_{B}^{k}$, where

$$
\begin{gather*}
\Delta_{B}^{k}=\left(\sum_{i=1}^{n} B_{x_{i}}\right)^{k}  \tag{1.8}\\
\square_{B}^{k}=\left(\sum_{i=1}^{p} B_{x_{i}}-\sum_{j=p+1}^{p+q} B_{x_{j}}\right)^{k} . \tag{1.9}
\end{gather*}
$$

Next, W. Satsanit has first introduced $\otimes^{k}$ operator and $\otimes^{k}$ is defined by

$$
\begin{align*}
\otimes^{k} & =\left[\left(\sum_{i=1}^{p} \frac{\partial^{2}}{\partial x_{i}^{2}}\right)^{3}-\left(\sum_{j=p+1}^{p+q} \frac{\partial^{2}}{\partial x_{j}^{2}}\right)^{3}\right]^{k} \\
& =\left(\sum_{i=1}^{p} \frac{\partial^{2}}{\partial x_{i}^{2}}-\sum_{j=p+1}^{p+q} \frac{\partial^{2}}{\partial x_{j}^{2}}\right)^{k}\left[\left(\sum_{i=1}^{p} \frac{\partial^{2}}{\partial x_{i}^{2}}\right)^{2}+\left(\sum_{i=1}^{p} \frac{\partial^{2}}{\partial x_{i}^{2}}\right) \cdot\left(\sum_{j=p+1}^{p+q} \frac{\partial^{2}}{\partial x_{j}^{2}}\right)+\left(\sum_{j=p+1}^{p+q} \frac{\partial^{2}}{\partial x_{j}^{2}}\right)^{2}\right]^{k} \\
& =\square^{k}\left(\Delta^{2}-\frac{1}{4}(\Delta+\square)(\Delta-\square)\right)^{k} \\
& =\left(\frac{3}{4} \Delta \Delta+\frac{1}{4} \square^{3}\right)^{k}, \tag{1.10}
\end{align*}
$$

where $\diamond, \Delta$, and $\square$ are defined by (1.1), (1.2), and (1.3) with $k=1$, respectively.
Now, firstly, the purpose of this work is to study the equation

$$
\begin{equation*}
\otimes^{k} \diamond_{B}^{k} u(x)=f(x) \tag{1.11}
\end{equation*}
$$

where the operator $\otimes^{k}$ is defined by (1.10) and $\diamond_{B}^{k}$ defined by (1.7), $f(x)$ is a generalized function and $u(x)$ is an unknown function. Finally we study the equation

$$
\begin{equation*}
\otimes^{k} \diamond_{B}^{k} u(x)=f\left(x, \square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)\right) \tag{1.12}
\end{equation*}
$$

with $f$ having a continuous first derivative for all $x \in \Omega \cup \partial \Omega$, where $\Omega$ is an open subset of $R^{n}$, and $\partial \Omega$ denotes the boundary of $\Omega, f$ is bounded on $\Omega$, that is, $|f| \leq N, N$ is constant, as well as $\square^{k-1}, L^{k}, \Delta_{B}^{k}$, and $\square_{B}^{k}$ are defined by (1.3), (2.46), (1.8) and (1.9), respectively.

We can find the solution $u(x)$ of (1.12) that is unique under the boundary condition $\square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=0$ for $x \in \partial \Omega$. By [4, page 369] there exists a unique solution $W(x)$ of the equation $\square W(x)=f(x, W(x))$ for all $x \in \Omega$ with the boundary condition $W(x)=0$ for all $x \in \partial \Omega$ where $W(x)=\square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)$.

Moreover, if we put $p=k=1$ in $\square^{k} \square_{B}^{k} M(x)=W(x)$, then we found that $M(x)=$ $I_{2}^{H}(x) * I_{2}(x) * W(x)$ is a solution of the inhomogeneous equation where $I_{2}^{H}(x)$ and $I_{2}(x)$ are defined by (2.6) and (2.20) with $\alpha=2, \gamma=2$, respectively.

Before going into details, the following definitions and some important concepts are needed.

## 2. Preliminaries

Definition 2.1. Let $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ be a point of the $n$-dimensional Euclidean space $\mathbb{R}^{n}$, denoted by

$$
\begin{equation*}
v=x_{1}^{2}+x_{2}^{2}+\cdots+x_{p}^{2}-x_{p+1}^{2}-x_{p+2}^{2}-\cdots-x_{p+q}^{2} \tag{2.1}
\end{equation*}
$$

The nondegenerated quadratic form $p+q=n$ is the dimension of the space $\mathbb{R}^{n}$. Let $\Gamma_{+}=\{x \in$ $\mathbb{R}^{n}: x_{1}>0$ and $\left.u>0\right\}$ be the interior of forward cone and let $\bar{\Gamma}_{+}$denote its closure. For any complex number $\alpha$, define the function

$$
R_{\alpha}^{H}(v)= \begin{cases}\frac{v^{(\alpha-n) / 2}}{K_{n}(\alpha)}, & \text { for } x \in \Gamma_{+}  \tag{2.2}\\ 0, & \text { for } x \notin \Gamma_{+},\end{cases}
$$

where the constant $K_{n}(\alpha)$ is given by the formula

$$
\begin{equation*}
K_{n}(\alpha)=\frac{\pi^{(n-1) / 2} \Gamma((2+\alpha-n) / 2) \Gamma((1-\alpha) / 2) \Gamma(\alpha)}{\Gamma((2+\alpha-p) / 2) \Gamma((p-\alpha) / 2)} \tag{2.3}
\end{equation*}
$$

The function $R_{\alpha}^{H}(v)$ is called the ultrahyperbolic kernel of Marcel Riesz and was introduced by Nozaki (see [5]).

It is well known that $R_{\alpha}^{H}(v)$ is an ordinary function if $\operatorname{Re}(\alpha) \geq n$ and is a distribution of $\alpha$ if $\operatorname{Re}(\alpha)<n$. Let $\operatorname{supp} R_{\alpha}^{H}(v)$ denote the support of $R_{\alpha}^{H}(v)$ and suppose that supp $R_{\alpha}^{H}(v) \subset$ $\bar{\Gamma}_{+}$, that is, supp $R_{\alpha}^{H}(v)$ is compact.

From Trione (see [6, page 11]), $R_{2 k}^{H}(v)$ is an elementary solution of the operator $\square^{k}$, that is,

$$
\begin{equation*}
\square^{k} R_{2 k}^{H}(v)=\delta(x) \tag{2.4}
\end{equation*}
$$

By putting $p=1$ in $R_{2 k}^{H}(v)$ and taking into account Legendre's duplication formula for $\Gamma(z)$, that is

$$
\begin{equation*}
\Gamma(2 z)=2^{2 z-1} \pi^{-1 / 2} \Gamma(z) \Gamma\left(z+\frac{1}{2}\right) \tag{2.5}
\end{equation*}
$$

we obtain

$$
\begin{equation*}
I_{\alpha}^{H}(v)=\frac{v^{(\alpha-n) / 2}}{H_{n}(\alpha)} \tag{2.6}
\end{equation*}
$$

and $v=x_{1}^{2}-x_{2}^{2}-x_{3}^{2} \cdots-x_{n}^{2}$ where

$$
\begin{equation*}
H_{n}(\alpha)=\pi^{(n-2) / 2} 2^{\alpha-1} \Gamma\left(\frac{\alpha+2-n}{2}\right) \Gamma\left(\frac{\alpha}{2}\right) \tag{2.7}
\end{equation*}
$$

$I_{\alpha}^{H}(v)$ is the hyperbolic kernel of Marcel Riesz.
Definition 2.2. Let $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ be a point of $\mathbb{R}^{n}$ and $\omega=x_{1}^{2}+x_{2}^{2}+\cdots+x_{n}^{2}$, then the function $R_{\alpha}^{e}(\omega)$ denoted the elliptic kernel of Marcel Riesz and is defined by

$$
\begin{equation*}
R_{\alpha}^{e}(\omega)=\frac{\omega^{(\alpha-n) / 2}}{W_{n}(\alpha)} \tag{2.8}
\end{equation*}
$$

where

$$
\begin{gather*}
\omega=x_{1}^{2}+x_{2}^{2}+\cdots+x_{n}^{2}  \tag{2.9}\\
W_{n}(\alpha)=\frac{\pi^{n / 2} 2^{\alpha} \Gamma(\alpha / 2)}{\Gamma((n-\alpha) / 2)} \tag{2.10}
\end{gather*}
$$

where $\alpha$ is a complex parameter and $n$ is the dimension of $\mathbb{R}^{n}$.
It can be shown that $R_{-2 k}^{e}(x)=(-1)^{k} \Delta^{k} \delta(x)$ where $\Delta^{k}$ is defined by (1.2). It follows that $R_{0}^{e}(x)=\delta(x)$, (see [7, page 118]).

Moreover, we obtain $(-1)^{k} R_{2 k}^{e}(x)$ is an elementary solution of the operator $\Delta^{k}$ (see [8, Lemma 2.4, page 31]). That is

$$
\begin{equation*}
\Delta^{k}\left((-1)^{k} R_{2 k}^{e}(x)\right)=\delta(x) \tag{2.11}
\end{equation*}
$$

By (2.2) and (2.3) with $q=0$, then $v^{(\alpha-n) / 2}$ reduces to $\omega_{p}^{(\alpha-p) / 2}$ where $\omega_{p}=x_{1}^{2}+x_{2}^{2}+\cdots+x_{p}^{2}$ and $K_{n}(\alpha)$ reduces to $K_{p}(\alpha)=\left(\pi^{(p-1) / 2} \Gamma((1-\alpha) / 2) \Gamma(\alpha)\right) / \Gamma((p-\alpha) / 2)$. By using the formula

$$
\begin{align*}
& \Gamma(2 z)=2^{2 z-1} \pi^{-1 / 2} \Gamma(z) \Gamma\left(z+\frac{1}{2}\right) \\
& \Gamma\left(\frac{1}{2}+z\right) \Gamma\left(\frac{1}{2}-z\right)=\pi \sec (\pi z) \tag{2.12}
\end{align*}
$$

we obtain

$$
\begin{equation*}
K_{p}(\alpha)=\frac{1}{2} \sec \left(\frac{\pi \alpha}{2}\right) W_{p}(\alpha) \tag{2.13}
\end{equation*}
$$

where $W_{p}(\alpha)$ is defined by (2.10) with $n=p$. Thus, for $q=0$,

$$
\begin{equation*}
R_{\alpha}^{H}(v)=\frac{v^{(\alpha-p) / 2}}{K_{p}(\alpha)}=2 \cos \left(\frac{\pi \alpha}{2}\right) \frac{v^{(\alpha-p) / 2}}{W_{p}(\alpha)}=2 \cos \left(\frac{\pi \alpha}{2}\right) R_{\alpha}^{e}\left(\omega_{p}\right) \tag{2.14}
\end{equation*}
$$

where $\omega_{p}=x_{1}^{2}+x_{2}^{2}+\cdots+x_{p}^{2}$. Thus, if $\alpha=2 k$, then

$$
\begin{equation*}
R_{2 k}^{H}\left(\omega_{p}\right)=2(-1)^{k} R_{2 k}^{e}\left(\omega_{p}\right) \tag{2.15}
\end{equation*}
$$

for $q=0$ and $\omega_{p}=x_{1}^{2}+x_{2}^{2}+\cdots+x_{p}^{2}$.
Definition 2.3. Let $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right), v=\left(v_{1}, v_{2}, \ldots, v_{n}\right) \in \mathbb{R}_{n}^{+}$. For any complex number $\alpha$, we define the function $S_{\alpha}(x)$ by

$$
\begin{equation*}
S_{\alpha}(x)=\frac{2^{n+2|v|-2 \alpha} \Gamma((n+2|v|-\alpha) / 2)|x|^{\alpha-n-2|v|}}{\prod_{i=1}^{n} 2^{v_{i}-1 / 2} \Gamma\left(v_{i}+1 / 2\right)} \tag{2.16}
\end{equation*}
$$

Definition 2.4. Let $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right), v=\left(v_{1}, v_{2}, \ldots, v_{n}\right) \in \mathbb{R}_{n}^{+}$, and $V=x_{1}^{2}+x_{2}^{2}+\cdots+x_{p}^{2}-$ $x_{p+1}^{2}-x_{p+2}^{2}-\cdots-x_{p+q}^{2}$ the nondegenerated quadratic form. Denote the interior of the forward cone by $\Gamma_{+}=\left\{x \in \mathbb{R}_{n}^{+}: x_{1}>0, x_{2}>0, \ldots, x_{n}>0, V>0\right\}$. The function $R_{\gamma}(x)$ is defined by

$$
\begin{equation*}
R_{\gamma}(x)=\frac{V^{(\gamma-n-2|v|) / 2}}{K_{n}(\gamma)} \tag{2.17}
\end{equation*}
$$

where

$$
\begin{equation*}
K_{n}(\gamma)=\frac{\pi^{(n+2|v|-1) / 2} \Gamma((2+\gamma-n-2|v|) / 2) \Gamma((1-\gamma) / 2) \Gamma(\gamma)}{\Gamma((2+\gamma-p-2|v|) / 2) \Gamma((p-2|v|-\gamma) / 2)} \tag{2.18}
\end{equation*}
$$

and $\gamma$ is a complex number. By putting $p=1$ in $R_{\gamma}(x)$ and taking into account Legendre's duplication formula for $\Gamma(z)$, that is,

$$
\begin{equation*}
\Gamma(2 z)=2^{2 z-1} \pi^{-1 / 2} \Gamma(z) \Gamma\left(z+\frac{1}{2}\right) \tag{2.19}
\end{equation*}
$$

we obtain

$$
\begin{equation*}
I_{\gamma}(x)=\frac{V^{(\gamma-n-2|v|) / 2}}{N_{n}(\gamma)} \tag{2.20}
\end{equation*}
$$

and $V=x_{1}^{2}-x_{2}^{2}-x_{3}^{2} \cdots-x_{n}^{2}$ where

$$
\begin{equation*}
N_{n}(\gamma)=\pi^{(n+2|v|-1) / 2} 2^{2 k-1} \Gamma\left(\frac{2+\gamma-n-2|\nu|}{2}\right) \Gamma\left(\frac{\gamma}{2}\right) \tag{2.21}
\end{equation*}
$$

Lemma 2.5. Given the equation $\Delta_{B}^{k} u(x)=\delta(x)$ for $x \in \mathbb{R}_{n}^{+}$, where $\Delta_{B}^{k}$ is defined by (1.8), then

$$
\begin{equation*}
u(x)=(-1)^{k} S_{2 k}(x) \tag{2.22}
\end{equation*}
$$

where $S_{2 k}(x)$ is defined by (2.16), with $\alpha=2 k$.
Proof. (See [3, page 379] and [9]).
Lemma 2.6. Given the equation $\square_{B}^{k} u(x)=\delta(x)$ for $x \in \mathbb{R}_{n}^{+}$, where $\square_{B}^{k}$ is defined by (1.9), then

$$
\begin{equation*}
u(x)=R_{2 k}(x) \tag{2.23}
\end{equation*}
$$

where $R_{2 k}(x)$ is defined by (2.17), with $\gamma=2 k$.
Proof. (See [3, page 379] and [9]).

Lemma 2.7. Given that $P$ is a hyperfunction, then

$$
\begin{equation*}
P \delta^{k}(p)+k \delta^{(k-1)}(p)=0 \tag{2.24}
\end{equation*}
$$

where $\delta^{(k)}$ is the Dirac-delta distribution with $k$-derivatives.
Proof. (See [8, page 233]).
Lemma 2.8. Given the equation

$$
\begin{equation*}
\square^{k} u(x)=0 \tag{2.25}
\end{equation*}
$$

where $\square^{k}$ is defined by (1.3) and $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right) \in \mathbb{R}^{n}$, then $u(x)=\left(R_{2(k-1)}^{H}(v)\right)^{(m)}$ is a solution of $(2.25)$ with $m=(n-4) / 2, n \geq 4$ and $n$ is even dimension. The function $\left(R_{2(k-1)}^{H}(v)\right)^{(m)}$ is defined by (2.2) with $m$-derivatives, $\alpha=2(k-1)$, and $v$ being defined by (2.1).

Proof. We first show the generalized function $\delta^{(m)}\left(r^{2}-s^{2}\right)$ where $r^{2}=x_{1}^{2}+x_{2}^{2}+\cdots+x_{p}^{2}$ and $s^{2}=x_{p+1}^{2}+x_{p+2}^{2}+\cdots+x_{p+q}^{2}, p+q=n$, is a solution of the equation

$$
\begin{equation*}
\square u(x)=0, \tag{2.26}
\end{equation*}
$$

where $\square$ is defined by (1.3) with $k=1$ and $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right) \in \mathbb{R}^{n}$,

$$
\begin{align*}
\frac{\partial}{\partial x_{i}} \delta^{(m)}\left(r^{2}-s^{2}\right) & =2 x_{i} \delta^{(m+1)}\left(r^{2}-s^{2}\right), \\
\frac{\partial^{2}}{\partial x_{i}^{2}} \delta^{(m)}\left(r^{2}-s^{2}\right) & =2 \delta^{(m+1)}\left(r^{2}-s^{2}\right)+4 x_{i}^{2} \delta^{(m+2)}\left(r^{2}-s^{2}\right), \\
\square \delta^{(m)}\left(r^{2}-s^{2}\right) & =\sum_{i=1}^{p} \frac{\partial^{2}}{\partial x_{i}^{2}} \delta^{(m)}\left(r^{2}-s^{2}\right) \\
& =2 p \delta^{(m+1)}\left(r^{2}-s^{2}\right)+4 r^{2} \delta^{(m+2)}\left(r^{2}-s^{2}\right) \\
& =2 p \delta^{(m+1)}\left(r^{2}-s^{2}\right)+4\left(r^{2}-s^{2}\right) \delta^{(m+2)}\left(r^{2}-s^{2}\right)+4 s^{2} \delta^{(m+2)}\left(r^{2}-s^{2}\right) \\
& =2 p \delta^{(m+1)}\left(r^{2}-s^{2}\right)-4(m+2) \delta^{(m+1)}\left(r^{2}-s^{2}\right)+4 s^{2} \delta^{(m+2)}\left(r^{2}-s^{2}\right) \\
& =(2 p-4(m+2)) \delta^{(m+1)}\left(r^{2}-s^{2}\right)+4 s^{2} \delta^{(m+2)}\left(r^{2}-s^{2}\right) . \tag{2.27}
\end{align*}
$$

By Lemma 2.5 with $P=r^{2}-s^{2}$, similarly,

$$
\begin{equation*}
\sum_{j=p+1}^{p+q} \frac{\partial^{2}}{\partial x_{j}^{2}} \delta^{(m)}\left(r^{2}-s^{2}\right)=(-2 q+4(m+2)) \delta^{(m+1)}\left(r^{2}-s^{2}\right)+4 r^{2} \delta^{(m+2)}\left(r^{2}-s^{2}\right) \tag{2.28}
\end{equation*}
$$

Thus

$$
\begin{align*}
\square \delta^{(m)}\left(r^{2}-s^{2}\right) & =\sum_{i=1}^{p} \frac{\partial^{2}}{\partial x_{i}^{2}} \delta^{(m)}\left(r^{2}-s^{2}\right)-\sum_{j=p+1}^{p+q} \frac{\partial^{2}}{\partial x_{i}^{2}} \delta^{(m)}\left(r^{2}-s^{2}\right) \\
& =(2(p+q)-8(m+2)) \delta^{(m+1)}\left(r^{2}-s^{2}\right)-4\left(r^{2}-s^{2}\right) \delta^{(m+2)}\left(r^{2}-s^{2}\right)  \tag{2.29}\\
& =(2 n-8(m+2)) \delta^{(m+1)}\left(r^{2}-s^{2}\right)+4(m+2) \delta^{(m+1)}\left(r^{2}-s^{2}\right) \\
& =(2 n-4(m+2)) \delta^{(m+1)}\left(r^{2}-s^{2}\right) .
\end{align*}
$$

If $2 n-4(m+2)=0$, then we have $\square \delta^{(m)}\left(r^{2}-s^{2}\right)=0$. That is, $u(x)=\delta^{(\mathrm{m})}\left(r^{2}-s^{2}\right)$ is a solution of (2.26) with $m=(n-4) / 2, n \geq 4$ and $n$ is even dimension. We write

$$
\begin{equation*}
{ }^{k} u(x)=\square\left({ }^{k-1} u(x)\right)=0, \tag{2.30}
\end{equation*}
$$

and from the above proof we have $\square^{k-1} u(x)=\delta^{(m)}\left(r^{2}-s^{2}\right)$ with $m=(n-4) / 2, n \geq 4$ and $n$ is even dimension. Convolving the above equation by $R_{2(k-1)}^{H}(v)$, we obtain

$$
\begin{gather*}
R_{2(k-1)}^{H}(v) * \square^{k-1} u(x)=R_{2(k-1)}^{H}(v) * \delta^{(m)}\left(r^{2}-s^{2}\right) \\
\square^{k-1}\left(R_{2(k-1)}^{H}(v)\right) * u(x)=\left(R_{2(k-1)}^{H}(v)\right)^{(m)}, \quad \text { where } v=\left(r^{2}-s^{2}\right)  \tag{2.31}\\
\delta * u(x)=u(x)=\left(R_{2(k-1)}^{H}(v)\right)^{(m)}
\end{gather*}
$$

by (2.2), and $v=r^{2}-s^{2}$ is defined by Definition (2.1).
Thus $u(x)=\left(R_{2(k-1)}^{H}(v)\right)^{(m)}$ is a solution of (2.25) with $m=(n-4) / 2, n \geq 4$ and $n$ is even dimension.

Lemma 2.9. Given the equation

$$
\begin{equation*}
\otimes^{k} G(x)=\delta(x), \tag{2.32}
\end{equation*}
$$

then

$$
\begin{equation*}
G(x)=\left(R_{6 k}^{H}(x) *(-1)^{2 k} R_{4 k}^{e}(x)\right) *\left(O^{* k}(x)\right)^{*-1} \tag{2.33}
\end{equation*}
$$

is an elementary solution for the $\otimes^{k}$ operator iterated $k$-times where $\otimes^{k}$ is defined by (1.10), and

$$
\begin{equation*}
O(x)=\frac{3}{4} R_{4}^{H}(x)+\frac{1}{4}(-1)^{2} R_{4}^{e}(x) \tag{2.34}
\end{equation*}
$$

where $O^{* k}(x)$ denotes the convolution of $O(x)$ itself $k$-times and $\left(O^{* k}(x)\right)^{*-1}$ denotes the inverse of $O^{* k}(x)$ in the convolution algebra. Moreover $G(x)$ is a tempered distribution.

Proof. From (3.1), we have

$$
\begin{equation*}
\otimes^{k} G(x)=\left(\frac{3}{4} \diamond \Delta+\frac{1}{4}^{3}\right)^{k} G(x)=\delta(x) \tag{2.35}
\end{equation*}
$$

or we can write

$$
\begin{equation*}
\left(\frac{3}{4} \diamond \Delta+\frac{1}{4} \square^{3}\right)\left(\frac{3}{4} \diamond \Delta+\frac{1}{4} \square^{3}\right)^{k-1} G(x)=\delta(x) \tag{2.36}
\end{equation*}
$$

Convolving both sides of the above equation by $R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x)$,

$$
\begin{equation*}
\left(\frac{3}{4} \diamond \Delta+\frac{1}{4} \square^{3}\right) *\left(R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x)\right)\left(\frac{3}{4} \diamond \Delta+\frac{1^{3}}{4}\right)^{k-1} G(x)=\delta(x) * R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x) \tag{2.37}
\end{equation*}
$$

or

$$
\begin{align*}
& \left(\frac{3}{4} \square\left(R_{2}^{H}(x)\right) * \Delta^{2}(-1)^{2} R_{4}^{e}(x) * R_{4}^{H}(x)+\frac{1}{4} \square^{3} R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x)\right) \\
& \quad *\left(\frac{3}{4} \diamond \Delta+\frac{1}{4} \square^{3}\right)^{k-1} G(x)=\delta(x) * R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x) . \tag{2.38}
\end{align*}
$$

By (2.4) and (2.8), we obtain

$$
\begin{equation*}
\left(\frac{3}{4} \delta * \delta * R_{4}^{H}(x)+\frac{1}{4} \delta *(-1)^{2} R_{4}^{e}(x)\right) *\left(\frac{3}{4} \diamond \Delta+\frac{1}{4} \square^{3}\right)^{k-1} G(x)=\delta(x) * R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x) \tag{2.39}
\end{equation*}
$$

Thus

$$
\begin{equation*}
\left(\frac{3}{4} R_{4}^{H}(x)+\frac{1}{4}(-1)^{2} R_{4}^{e}(x)\right) *\left(\frac{3}{4} \diamond \Delta+\frac{1^{3}}{4}\right)^{k-1} G(x)=R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x) \tag{2.40}
\end{equation*}
$$

Keeping on convolving both sides of the above equation by $R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x)$ up to $k-1$ times, we obtain

$$
\begin{equation*}
O^{* k}(x) * G(x)=\left(R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x)\right)^{* k} \tag{2.41}
\end{equation*}
$$

where the symbol $* k$ denotes the convolution of itself $k$-times. By properties of $R_{\alpha}(x)$, we have

$$
\begin{equation*}
\left(R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x)\right)^{* k}=R_{6 k}^{H}(x) *(-1)^{2 k} R_{4 k}^{e}(x) \tag{2.42}
\end{equation*}
$$

Thus,

$$
\begin{equation*}
O^{* k}(x) * G(x)=R_{6 k}^{H}(x) *(-1)^{2 k} R_{4 k}^{e}(x) \tag{2.43}
\end{equation*}
$$

Now, consider the function $O^{* k}(x)$, since $R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x)$ is a tempered distribution. Thus $O(x)$ defined by (2.34) is a tempered distribution, and we obtain that $O^{* k}(x)$ is a tempered distribution and $R_{6 k}^{H}(x) *(-1)^{2 k} R_{4 k}^{e}(x) \in \mathcal{S}^{\prime}$ is the space of tempered distribution. Choose $S^{\prime} \subset \Phi_{\mathcal{R}}^{\prime}$ where $\mathscr{\Phi}_{\mathcal{R}}^{\prime}$ is the right-side distribution which is a subspace of $\mathscr{\Phi}^{\prime}$ of distribution.

Thus $R_{6 k}^{H}(x) *(-1)^{2 k} R_{4 k}^{e}(x) \in \Phi_{\mathcal{R}}^{\prime}$. It follows that $R_{6 k}^{H}(x) *(-1)^{2 k} R_{4 k}^{e}(x)$ is an element of convolution algebra, since $\Phi_{\mathcal{R}}^{\prime}$ is a convolution algebra. Hence by the method of Zemanian (see [10]), (2.33) has a unique solution

$$
\begin{equation*}
G(x)=\left(R_{6 k}^{H}(x) *(-1)^{2 k} R_{4 k}^{e}(x)\right) *\left(O^{* k}(x)\right)^{*-1} \tag{2.44}
\end{equation*}
$$

where $\left(O^{* k}(x)\right)^{*-1}$ is an inverse of $O^{* k}(x)$ in the convolution algebra and $G(x)$ is called the Green function of the $\otimes^{k}$ operator.

Lemma 2.10. Given the equation

$$
\begin{equation*}
L^{k} K(x)=\delta(x) \tag{2.45}
\end{equation*}
$$

where $L^{k}$ is the operator defined by

$$
\begin{equation*}
L^{k}=\left(\frac{3}{4} \Delta^{2}+\frac{1}{4} \square^{2}\right)^{k} \tag{2.46}
\end{equation*}
$$

and $\Delta$ and $\square$ are defined by (1.2) and (1.3) with $k=1$, respectively, one obtains that $K(x)$ is an elementary solution of the $L^{k}$ operator where

$$
\begin{gather*}
K(x)=\left(R_{4 k}^{H}(x) *(-1)^{2 k} R_{4 k}^{e}(x)\right) *\left(O^{* k}(x)\right)^{*-1} \\
O(x)=\frac{3}{4} R_{4}^{H}(x)+\frac{1}{4}(-1)^{2} R_{4}^{e}(x) \tag{2.47}
\end{gather*}
$$

where $O^{* k}(x)$ denotes the convolution of $O(x)$ itself $k$-times and $\left(O^{* k}(x)\right)^{*-1}$ denotes the inverse of $O^{* k}(x)$ in the convolution algebra. Moreover $K(x)$ is a tempered distribution.

Proof. The proof of Lemma 2.10 is similar to the proof of Lemma 2.9.
Lemma 2.11. Given the equation

$$
\begin{equation*}
\square u(x)=f(x, u(x)) \tag{2.48}
\end{equation*}
$$

where $f$ is defined and has continuous first derivatives for all $x \in \Omega \cup \partial \Omega$, where $\Omega$ is an open subset of $R^{n}$ and $\partial \Omega$ is the boundary of $\Omega$, assume that $f$ is bounded, that is, $|f(x, u(x))| \leq N$ for all $x \in \Omega$.

Then one obtains a continuous function $u(x)$ as unique solution of (2.48) with the boundary condition $u(x)=0$ for $x \in \partial \Omega$.

Proof. We can prove the existence of the solution $u(x)$ of (2.48) by the method of iterations and Schuder's estimates. The details of the proof are given by Courant and Hilbert; (see [4, pages 369-372]).

Lemma 2.12. The function $R_{-2 k}^{H}(x)$ and $S_{-2 k}(x)$ are the inverse of the convolution algebra of $R_{2 k}^{H}$ and $S_{2 k}$, respectively, that is,

$$
\begin{align*}
& R_{-2 k}^{H}(x) * R_{2 k}^{H}(x)=R_{-2 k+2 k}^{H}(x)=R_{0}^{H}(x)=\delta \\
& S_{-2 k}(x) * S_{2 k}(x)=S_{-2 k+2 k}(x)=S_{0}(x)=\delta \tag{2.49}
\end{align*}
$$

Proof. (See [7, page 158] and [11]).

## 3. Main Results

Theorem 3.1. Given the equation

$$
\begin{equation*}
\otimes^{k} \diamond_{B}^{k} u(x)=0 \tag{3.1}
\end{equation*}
$$

where $\otimes^{k}$ is the Otimes operator iterated $k$-times and $\diamond_{B}^{k}$ is Diamond Bessel operator iterated $k$-times defined by (1.10) and (1.7), respectively, and $u(x)$ is an unknown function, one obtains that $u(x)$ is a solution of (3.1) where

$$
\begin{equation*}
u(x)=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *(-1)^{k-1}\left(R_{2(k-1)}^{H}(v)\right)^{(m)} \tag{3.2}
\end{equation*}
$$

where $K(x)$ is defined by (2.47), as well as $S_{2 k}(x), R_{2 k}(x)$, and $\left(R_{2(k-1)}^{H}(v)\right)^{m}$ are defined by (2.16),(2.17), and (2.2) with $\alpha=2 k, \gamma=2 k$ and $\alpha=2(k-1)$, respectively.

Proof. Since

$$
\begin{equation*}
\otimes^{k}=\left(\frac{3}{4} \diamond \Delta+\frac{1}{4} \square^{3}\right)^{k}, \quad \diamond_{B}^{k}=\Delta_{B}^{k} \square_{B}^{k} . \tag{3.3}
\end{equation*}
$$

Consider the homogeneous equation

$$
\begin{equation*}
\otimes^{k} \diamond_{B}^{k} u(x)=0 \tag{3.4}
\end{equation*}
$$

The above equation can be written as

$$
\begin{equation*}
\left(\frac{3}{4} \diamond \Delta+\frac{1}{4} \square^{3}\right)^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=0 \tag{3.5}
\end{equation*}
$$

or

$$
\begin{equation*}
\square^{k}\left(\frac{3}{4} \Delta^{2}+\frac{1}{4} \square^{2}\right)^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=0 \tag{3.6}
\end{equation*}
$$

That is,

$$
\begin{equation*}
\square^{k} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=0 \tag{3.7}
\end{equation*}
$$

where $\square^{k}, L^{k}, \Delta_{B}^{k}$, and $\square_{B}^{k}$ are defined by (1.3), (2.46), (1.8), and (1.9), respectively. By Lemma 2.8, we obtain

$$
\begin{equation*}
L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=\left(R_{2(k-1)}^{H}(v)\right)^{(m)} \tag{3.8}
\end{equation*}
$$

Since $(-1)^{k} S_{2 k}(x), R_{2 k}(x)$ are the elementary solution of the operators $\Delta_{B}^{k}$ and $\square_{B^{\prime}}^{k}$ respectively, and by Lemma 2.10, we have that $K(x)$ is an elementary of the operator $L^{k}$ defined by (2.46), that is,

$$
\begin{gather*}
\Delta_{B}^{k}(-1)^{k} S_{2 k}(x)=\delta(x), \quad \square_{B}^{k} R_{2 k}(x)=\delta(x) \\
L^{k} K(x)=\delta(x) \tag{3.9}
\end{gather*}
$$

Convolving both sides of (3.8) by $K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x)$, we obtain

$$
\begin{equation*}
K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) * Ł^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *\left(R_{2(k-1)}^{H}(v)\right)^{(m)} \tag{3.10}
\end{equation*}
$$

By properties of convolution

$$
\begin{equation*}
Ł^{k} K(x) * \Delta_{B}^{k}(-1)^{k} S_{2 k}(x) * \square_{B}^{k} R_{2 k}(x) * u(x)=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *\left(R_{2(k-1)}^{H}(v)\right)^{(m)} \tag{3.11}
\end{equation*}
$$

By Lemmas 2.10, 2.5, and 2.6, we obtain

$$
\begin{equation*}
\delta(x) * \delta(x) * \delta(x) * u(x)=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *\left(R_{2(k-1)}^{H}(v)\right)^{(m)} \tag{3.12}
\end{equation*}
$$

Thus

$$
\begin{equation*}
u(x)=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *\left(R_{2(k-1)}^{H}(v)\right)^{(m)} \tag{3.13}
\end{equation*}
$$

is the solution of (3.1).
Theorem 3.2. Given the equation

$$
\begin{equation*}
\otimes^{k} \diamond_{B}^{k} u(x)=f(x) \tag{3.14}
\end{equation*}
$$

where $\otimes^{k}$ is the Otimes operator iterated $k$-times defined by (1.10), and $\diamond_{B}^{k}$ is the Diamond Bessel operator iterated $k$-times defined by (1.7), $f(x)$ is the generalized function, $u(x)$ is an unknown function, $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right) \in \mathbb{R}^{n}$ and $n$ is even,

One obtains that

$$
\begin{equation*}
u(x)=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *\left(R_{2(k-1)}^{H}(v)\right)^{(m)}+G(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) * f(x) \tag{3.15}
\end{equation*}
$$

is a general solution of (3.14) and $G(x)$ is defined by (2.33), $K(x)$ is defined by (2.47), as well as $S_{2 k}(x)$ and $R_{2 k}(x)$ are defined by (2.16) and (2.17) with $\alpha=2 k$ and $\gamma=2 k$, respectively.

Proof. Consider the equation

$$
\begin{equation*}
\otimes^{k} \diamond_{B}^{k} u(x)=f(x) \tag{3.16}
\end{equation*}
$$

or

$$
\begin{equation*}
\otimes^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=f(x) \tag{3.17}
\end{equation*}
$$

Convolving both sides of (3.14) by $G(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x)$, we obtain

$$
\begin{equation*}
G(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) * \otimes^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=G(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) * f(x) \tag{3.18}
\end{equation*}
$$

By properties of convolution,

$$
\begin{equation*}
\otimes^{k} G(x) * \Delta_{B}^{k}(-1)^{k} S_{2 k}(x) * \square_{B}^{k} R_{2 k}(x) * u(x)=G(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) * f(x) \tag{3.19}
\end{equation*}
$$

By Lemmas 2.9, 2.5, and 2.6, we obtain

$$
\begin{equation*}
\delta(x) * \delta(x) * \delta(x) * u(x)=G(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) * f(x) \tag{3.20}
\end{equation*}
$$

Thus

$$
\begin{equation*}
u(x)=G(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) * f(x) \tag{3.21}
\end{equation*}
$$

Consider the homogeneous equation

$$
\begin{equation*}
\otimes^{k} \diamond_{B}^{k} u(x)=0 \tag{3.22}
\end{equation*}
$$

By Theorem 3.1, we have a homogeneous solution

$$
\begin{equation*}
u(x)=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *\left(R_{2(k-1)}^{H}(v)\right)^{(m)} \tag{3.23}
\end{equation*}
$$

Thus, the general solution of (3.14) is

$$
\begin{equation*}
u(x)=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *\left(R_{2(k-1)}^{H}(v)\right)^{(m)}+G(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) * f(x), \tag{3.24}
\end{equation*}
$$

as required.
Theorem 3.3. Consider the nonlinear equation

$$
\begin{equation*}
\otimes^{k} \diamond_{B}^{k} u(x)=f\left(x, \square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)\right) \tag{3.25}
\end{equation*}
$$

where $\otimes^{k}, \vee_{B}^{k}, \square^{k-1}, L^{k}, \Delta_{B^{\prime}}^{k}$ and $\square_{B}^{k}$ are defined by (1.10), (1.7),(1.3),(2.44), and (1.9), respectively. Let $f$ be defined, and having continuous first derivative for all $x \in \Omega \cup \partial \Omega, \Omega$ is an open subset of $R^{n}$ and $\partial \Omega$ denotes the boundary function, that is,

$$
\begin{equation*}
\left|f\left(x, \square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)\right)\right| \leq N \tag{3.26}
\end{equation*}
$$

for all $x \in \Omega$ and the boundary condition

$$
\begin{equation*}
\square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=0 \tag{3.27}
\end{equation*}
$$

for all $x \in \partial \Omega$. Then one obtains

$$
\begin{equation*}
u(x)=R_{2(k-1)}^{H}(x) * G(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) * W(x) \tag{3.28}
\end{equation*}
$$

as a solution of (3.25) with the boundary condition

$$
\begin{equation*}
u(x)=\left(R_{2(k-2)}^{H}(v)\right)^{(m)} * G(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) \tag{3.29}
\end{equation*}
$$

for all $x \in \partial \Omega, m=(n-4) / 2$, and $W(x)$ is a continuous function for $x \in \Omega \cup$ $\partial \Omega$, while $R_{2(k-2)(v)}^{H}, S_{2 k}(x)$, and $R_{2 k}(x)$ are given by (2.2), (2.16), and (2.17) with $\alpha=2(k-2), \alpha=$ $2 k$, and $\gamma=2 k$, respectively. Moreover, for $k=1$ one obtains

$$
\begin{equation*}
M(x)=\left(R_{-4}^{H}(x) *(-1)^{2} R_{-4}^{e}(x)\right) *\left(O^{* 1}(x)\right) *(-1)^{k} S_{-2}(x) * u(x) \tag{3.30}
\end{equation*}
$$

as a solution of the inhomogeneous equation

$$
\begin{equation*}
\square \square_{B} M(x)=W(x) \tag{3.31}
\end{equation*}
$$

whereand $\square_{B}$ are defined by (1.3) and (1.9) with $k=1$, respectively, and $u(x)$ is obtained from (3.28). Furthermore, If one puts $p=k=1$, then the operators $\square^{k}$ and $\square_{B}^{k}$ reduce to

$$
\begin{equation*}
\frac{\partial^{2}}{\partial x_{1}^{2}}-\frac{\partial^{2}}{\partial x_{2}^{2}}-\frac{\partial^{2}}{\partial x_{3}^{2}}-\cdots-\frac{\partial^{2}}{\partial x_{n}^{2}}, \quad B_{x_{1}}-B_{x_{2}}-B_{x_{3}}-\cdots-B_{x_{n}}, \tag{3.32}
\end{equation*}
$$

respectively, and the solution $M(x)=I_{2}^{H}(x) * I_{2}(x) * W(x)$ is the inhomogeneous wave equation

$$
\begin{equation*}
\left(\frac{\partial^{2}}{\partial x_{1}^{2}}-\frac{\partial^{2}}{\partial x_{2}^{2}}-\frac{\partial^{2}}{\partial x_{3}^{2}}-\cdots-\frac{\partial^{2}}{\partial x_{n}^{2}}\right) \cdot\left(B_{x_{1}}-B_{x_{2}}-B_{x_{3}}-\cdots-B_{x_{n}}\right) M(x)=W(x), \tag{3.33}
\end{equation*}
$$

where $I_{2}^{H}(x)$ is defined by (2.6) with $\alpha=2$ and $I_{2}(x)$ is defined by (2.20) with $\gamma=2$.
Proof. Since

$$
\begin{equation*}
\otimes^{k} \triangleleft_{B}^{k} u(x)=\square \square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=f\left(x, \square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)\right), \tag{3.34}
\end{equation*}
$$

$u(x)$ has continuous derivative up to order $6 k$ for $k=1,2,3, \ldots$, and $\square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)$ exists as the generalized function. Thus we can assume that

$$
\begin{equation*}
\square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=W(x), \quad \forall x \in \Omega . \tag{3.35}
\end{equation*}
$$

Then (3.34) can be written in the form

$$
\begin{equation*}
\left.\otimes^{k}\right\rangle_{B}^{k} u(x)=\square W(x)=f(x, W(x)) . \tag{3.36}
\end{equation*}
$$

By(3.26)

$$
\begin{equation*}
|f(x, W(x))| \leq N, \quad x \in \Omega, \tag{3.37}
\end{equation*}
$$

and by(3.27) $W(x)=0, x \in \partial \Omega$, or

$$
\begin{equation*}
\square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=0, \quad \forall x \in \partial \Omega . \tag{3.38}
\end{equation*}
$$

We obtain a unique solution of (3.28) which satisfies (3.27) by Lemma 2.8.
Since $R_{2(k-1)}^{H}(x),(-1)^{k} S_{2 k}(x)$, and $R_{2 k}(x)$ are the elementary solution of the operators $\square^{k-1}, \Delta_{B^{\prime}}^{k}$ and $\square_{B^{\prime}}^{k}$, respectively, and by Lemma 2.10, we have that $K(x)$ is an elementary of the operator $L^{k}$ where $L^{k}=\left((3 / 4) \Delta^{2}+(1 / 4) \square^{2}\right)^{k}$, that is,

$$
\begin{array}{rll}
\square^{k-1} R_{2(k-1)}^{H}(x)=\delta, & \Delta_{B}^{k}(-1)^{k} S_{2 k}(x)=\delta, \\
{ }_{B}^{k} R_{2 k}(x)=\delta, & L^{k} K(x)=\delta . \tag{3.39}
\end{array}
$$

From (3.35), we have

$$
\begin{equation*}
\square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=W(x) \tag{3.40}
\end{equation*}
$$

Convolving the above equation by

$$
\begin{equation*}
R_{2(k-1)}^{H}(x) * K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) \tag{3.41}
\end{equation*}
$$

we obtain

$$
\begin{gather*}
\left(R_{2(k-1)}^{H}(x) * K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x)\right) *\left(\square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)\right)  \tag{3.42}\\
\quad=\left(R_{2(k-1)}^{H}(x) * K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x)\right) * W(x)
\end{gather*}
$$

By properties of convolution, we obtain

$$
\begin{gather*}
\left(\square^{k-1} R_{2(k-1)}^{H}(x)\right) *\left(£^{k} K(x)\right) *\left(\Delta_{B}^{k} *(-1)^{k} S_{2 k}\right) *\left(\square_{B}^{k} R_{2 k}\right) * u(x)  \tag{3.43}\\
=\left(R_{2(k-1)}^{H}(x) * K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x)\right) * W(x)
\end{gather*}
$$

By (3.39) we obtain

$$
\begin{equation*}
\delta * \delta * \delta * \delta * u(x)=\left(R_{2(k-1)}^{H}(x) * K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x)\right) * W(x) \tag{3.44}
\end{equation*}
$$

Thus

$$
\begin{equation*}
u(x)=\left(R_{2(k-1)}^{H}(x) * K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x)\right) * W(x) \tag{3.45}
\end{equation*}
$$

as a solution of (3.25).
Next, consider the boundary condition (3.38). From

$$
\begin{equation*}
\square^{k-1} L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=0 \tag{3.46}
\end{equation*}
$$

by Lemma 2.8, we have

$$
\begin{equation*}
L^{k} \Delta_{B}^{k} \square_{B}^{k} u(x)=\left(R_{2(k-2)}^{H}(v)\right)^{(m)} \tag{3.47}
\end{equation*}
$$

where $m=(n-4) / 2, n \geq 4$ and $n$ is even. Convolving both sides of (3.47) by

$$
\begin{equation*}
K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) \tag{3.48}
\end{equation*}
$$

we obtain

$$
\begin{align*}
& \left(K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x)\right) *\left(L^{k} \Delta_{B}^{k} \square_{B}^{k}\right) * u(x) \\
& \quad=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *\left(R_{2(k-2)}^{H}(v)\right)^{(m)} \tag{3.49}
\end{align*}
$$

By the properties of convolution, we obtain

$$
\begin{align*}
& \left(L^{k} K(x)\right) *\left(\Delta_{B}^{k}(-1)^{k} S_{2 k}\right) *\left(\square_{B}^{k} R_{2 k}\right) * u(x)  \tag{3.50}\\
& \quad=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *\left(R_{2(k-2)}^{H}(v)\right)^{(m)}
\end{align*}
$$

By (3.39), we obtain

$$
\begin{equation*}
\delta * \delta * \delta * u(x)=\left(K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x)\right) *\left(R_{2(k-2)}^{H}(v)\right)^{(m)} \tag{3.51}
\end{equation*}
$$

Thus, for $x \in \partial \Omega$ and $k=2,3,4,5, \ldots$,

$$
\begin{equation*}
u(x)=K(x) *(-1)^{k} S_{2 k}(x) * R_{2 k}(x) *\left(R_{2(k-2)}^{H}(v)\right)^{(m)} \tag{3.52}
\end{equation*}
$$

as required.
Now, for $k=1$ in (3.28), we have

$$
\begin{equation*}
u(x)=\delta(x) * G(x) *(-1) S_{2}(x) * R_{2}(x) * W(x) \tag{3.53}
\end{equation*}
$$

By (2.47), we have

$$
\begin{equation*}
G(x)=\left(R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x)\right) *\left(O^{* 1}(x)\right)^{*-1} \tag{3.54}
\end{equation*}
$$

Taking into account (3.53), we obtain

$$
\begin{equation*}
u(x)=\left(R_{6}^{H}(x) *(-1)^{2} R_{4}^{e}(x)\right) *\left(O^{* 1}(x)\right)^{*-1} *(-1)^{1} S_{2}(x) * R_{2}(x) * W(x) \tag{3.55}
\end{equation*}
$$

as a solution of (3.25) for $k=1$.
Convolving both sides of (3.55) by

$$
\begin{equation*}
\left(R_{-4}^{H}(x) *(-1)^{2} R_{-4}^{e}(x)\right) *\left(O^{* 1}(x)\right) *(-1) S_{-2}(x) \tag{3.56}
\end{equation*}
$$

by Lemma 2.12, we obtain

$$
\begin{equation*}
\left(R_{-4}^{H}(x) *(-1)^{2} R_{-4}^{e}(x)\right) *\left(O^{* 1}(x)\right) *(-1) S_{-2}(x) * u(x)=R_{2}^{H}(x) * R_{2}(x) * W(x) \tag{3.57}
\end{equation*}
$$

By Lemma 2.6, we obtain

$$
\begin{equation*}
M(x)=\left(R_{-4}^{H}(x) *(-1)^{2} R_{-4}^{e}(x)\right) *\left(O^{* 1}(x)\right) *(-1) S_{-2}(x) * u(x) \tag{3.58}
\end{equation*}
$$

as a solution of the inhomogeneous equation

$$
\begin{equation*}
\square \square \square_{B} M(x)=W(x) \tag{3.59}
\end{equation*}
$$

Now, consider the boundary condition for $k=1$ in (3.27); we have

$$
\begin{equation*}
L \Delta_{B} \square_{B} u(x)=0, \quad \text { or } \quad \square_{B} L \Delta_{B} u(x)=0 \tag{3.60}
\end{equation*}
$$

for $x \in \partial \Omega$. Thus by Lemma 2.8, for $k=1$, we have

$$
\begin{equation*}
L \Delta_{B} u(x)=\delta^{(m)}(v) \quad \text { for } x \in \partial \Omega \tag{3.61}
\end{equation*}
$$

where $\delta^{(m)}(x)=R_{0}^{H}(x)$. Convolving the above equation by $K(x) *(-1) S_{2}(x)$ where $K(x)$ is defined by (2.47) with $k=1$ and $S_{2}(x)$ is defined by (2.16) with $\alpha=2$, we obtain

$$
\begin{equation*}
K(x) *(-1) S_{2}(x) *\left(L \Delta_{B} u(x)\right)=\delta^{(m)}(v) * K(x) *(-1) S_{2}(x) \tag{3.62}
\end{equation*}
$$

By properties of convolution,

$$
\begin{equation*}
L K(x) * \Delta_{B}(-1) S_{2}(x) * u(x)=\delta^{(m)}(v) * K(x) *(-1) S_{2}(x) \tag{3.63}
\end{equation*}
$$

By Lemmas 2.10 and 2.5, we obtain

$$
\begin{equation*}
\delta(x) * \delta(x) * u(x)=\delta^{(m)}(v) * K(x) *(-1) S_{2}(x) \tag{3.64}
\end{equation*}
$$

It follows that

$$
\begin{equation*}
u(x)=\delta^{(m)}(v) * K(x) *(-1) S_{2}(x) \tag{3.65}
\end{equation*}
$$

By (2.47) with $k=1$, we have

$$
\begin{equation*}
K(x)=\left(R_{4}^{H}(x) *(-1)^{2} R_{4}^{e}(x)\right) *\left(O^{* 1}(x)\right)^{*-1} \tag{3.66}
\end{equation*}
$$

Taking into account (3.65), we obtain

$$
\begin{equation*}
u(x)=\delta^{(m)}(v) *\left(R_{4}^{H}(x) *(-1)^{2} R_{4}^{e}(x)\right) *\left(O^{* 1}(x)\right)^{*-1} *(-1) S_{2}(x) \text { for } x \in \partial \Omega \tag{3.67}
\end{equation*}
$$

Now consider the case $k=1, p=1$, and $q=n-1$, that is, from (3.59), $R_{2}^{H}(x)$ reduced to $I_{2}^{H}(x)$ where $I_{2}^{H}(x)$ is defined by (2.2) with $\alpha=2$ and $R_{2}(x)$ reduced to $I_{2}(x)$ where $I_{2}(x)$ is defined by (2.17) with $\gamma=2$, and then the operator $\square$ defined by (1.3) reduces to the wave operator

$$
\begin{equation*}
\square^{*}=\frac{\partial^{2}}{\partial x_{1}^{2}}-\frac{\partial^{2}}{\partial x_{2}^{2}}-\frac{\partial^{2}}{\partial x_{3}^{2}}-\cdots-\frac{\partial^{2}}{\partial x_{n}^{2}} \tag{3.68}
\end{equation*}
$$

$\square_{B}$ defined by (1.9) reduces to the Bessel wave operator

$$
\begin{equation*}
\square_{B}^{*}=B_{x_{1}}-B_{x_{2}}-B_{x_{3}}-\cdots-B_{x_{n}} \tag{3.69}
\end{equation*}
$$

and then the solution $M(x)$ reduced to

$$
\begin{equation*}
M(x)=I_{2}^{H}(x) * I_{2}(x) * W(x) \tag{3.70}
\end{equation*}
$$

which is the solution of inhomogeneous wave equation

$$
\begin{equation*}
\square^{*} \square_{B}^{*} M(x)=W(x) \tag{3.71}
\end{equation*}
$$

or

$$
\begin{equation*}
\left(\frac{\partial^{2}}{\partial x_{1}^{2}}-\frac{\partial^{2}}{\partial x_{2}^{2}}-\frac{\partial^{2}}{\partial x_{3}^{2}}-\cdots-\frac{\partial^{2}}{\partial x_{n}^{2}}\right) \cdot\left(B_{x_{1}}-B_{x_{2}}-B_{x_{3}}-\cdots-B_{x_{n}}\right) M(x)=W(x) \tag{3.72}
\end{equation*}
$$

With the boundary condition for $x \in \partial \Omega$,

$$
\begin{equation*}
L^{*} \square_{B}^{*} \Delta_{B} u(x)=0 \tag{3.73}
\end{equation*}
$$

where $L^{*}=(3 / 4) \Delta^{2}+(1 / 4)\left(\square^{*}\right)^{2}$ and $\square^{*}$ is defined by (3.68), or for $x \in \partial \Omega$ and by (3.65), we obtain

$$
\begin{equation*}
u(x)=\delta^{(m)}(s) *\left(I_{4}^{H}(x) *(-1)^{2} R_{4}^{e}(x)\right) *\left(D^{* 1}(x)\right)^{*-1} *(-1) S_{2}(x) \tag{3.74}
\end{equation*}
$$

where $I_{4}(x)$ is defined by (2.20) with $\gamma=4, s=x_{1}^{2}-x_{2}^{2}-x_{3}^{2}-\cdots-x_{n}^{2}$, and $D(x)$ reduced from $O(x)$ where it is defined by $(2.34)$, that is, $D(x)=(3 / 4) I_{4}^{H}(x)+(1 / 2)(-1)^{2} R_{4}^{e}(x)$.

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