

# ON THE $B$ -ANGLE AND $g$ -ANGLE IN NORMED SPACES

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*Key words:* Smooth normed spaces, quasi-inner product spaces, oriented (non-oriented)  $B$ -angle between two vectors, oriented (non-oriented)  $g$ -angle between two vectors.

*Abstract:* It is known that in a strictly convex normed space, the  $B$ -orthogonality (Birkhoff orthogonality) has the property, " $B$ -orthogonality is unique to the left". Using this property, we introduce the definition of the so-called  $B$ -angle between two vectors, in a smooth and uniformly convex space. Also, we define the so-called  $g$ -angle between two vectors. It is demonstrated that the  $g$ -angle in a unilateral triangle, in a quasi-inner product space, is  $\pi/3$ . The  $g$ -angle between a side and a diagonal, in a so-called  $g$ -quadrangle, is  $\pi/4$ .



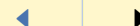
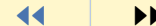
On the  $B$ -angle and  $g$ -angle in normed spaces

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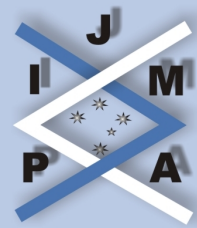
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Let  $X$  be a real smooth normed space of dimension greater than 1. It is well known that the functional

$$(1) \quad g(x, y) := \|x\| \lim_{t \rightarrow 0} \frac{\|x + ty\| - \|x\|}{t} \quad (x, y \in X)$$

always exists (see [5]).

This functional is linear in the second argument and it has the following properties:

$$(2) \quad g(\alpha x, y) = \alpha g(x, y) \quad (\alpha \in \mathbb{R}), \quad g(x, x) = \|x\|^2, \quad |g(x, y)| \leq \|x\| \|y\|.$$

**Definition 1 ([10]).** A normed space  $X$  is a quasi-inner product space (*q.i.p. space*) if the equality

$$(3) \quad \|x + y\|^4 - \|x - y\|^4 = 8 [\|x\|^2 g(x, y) + \|y\|^2 g(y, x)]$$

holds for all  $x, y \in X$ .

The space of sequences  $l^4$  is a *q.i.p. space*, but  $l^1$  is not a *q.i.p. space*.

It is proved in [10] and [11] that a *q.i.p. space*  $X$  is very smooth, uniformly smooth, strictly convex and, in the case of Banach spaces, reflexive.

The orthogonality of the vector  $x \neq 0$  to the vector  $y \neq 0$  in a normed space  $X$  may be defined in several ways. We mention some kinds of orthogonality and their notations:

- $x \perp_B y \Leftrightarrow (\forall \lambda \in \mathbb{R}) \|x\| \leq \|x + \lambda y\|$  (Birkhoff orthogonality),
- $x \perp_J y \Leftrightarrow \|x - y\| = \|x + y\|$  (James orthogonality),
- $x \perp_S y \Leftrightarrow \left\| \frac{x}{\|x\|} - \frac{y}{\|y\|} \right\| = \left\| \frac{x}{\|x\|} + \frac{y}{\|y\|} \right\|$  (Singer orthogonality).



In the papers [8], [6] and [9], by using the functional  $g$ , the following orthogonal relations were introduced:

$$\begin{aligned}x \perp_g y &\Leftrightarrow g(x, y) = 0, \\x \stackrel{g}{\perp} y &\Leftrightarrow g(x, y) + g(y, x) = 0, \\x \perp_g y &\Leftrightarrow \|x\|^2 g(x, y) + \|y\|^2 g(y, x) = 0.\end{aligned}$$

In [6, Theorem 2] the following assertion is proved: If  $X$  is smooth, then  $x \perp_g y \Leftrightarrow x \perp_B y$ .

In [11] we have proved the following assertion: If  $X$  is a  $q.i.p.$  space, then

$$x \perp_g y \Leftrightarrow x \perp_J y \quad \text{and} \quad x \stackrel{g}{\perp} y \Leftrightarrow x \perp_S y.$$

If there exists an inner product  $\langle \cdot, \cdot \rangle$  in  $X$ , ( $i.p.$ ), then it is easy to see that  $x \rho y \Leftrightarrow \langle x, y \rangle = 0$  holds for every

$$\rho \in \left\{ \perp_B, \perp_J, \perp_S, \perp_g, \stackrel{g}{\perp}, \perp_g \right\}.$$

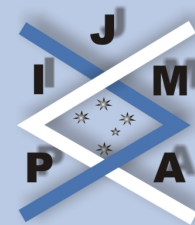
For more on  $B$ -orthogonality and  $g$ -orthogonality, see the papers [1], [2], [13] and [14]. Some additional properties of this orthogonality are quoted below. Denote by  $P_{[x]}y$  the set of the best approximations of  $y$  with vectors from  $[x]$ .

**Theorem 1.** *Let  $X$  be a smooth and uniformly convex normed space, and let  $x, y \in X - \{0\}$  be fixed linearly independent vectors. The following assertions are valid.*

1. *There exists a unique  $a \in \mathbb{R}$  such that*

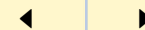
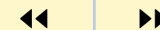
$$\begin{aligned}P_{[x]}y = ax &\Leftrightarrow g(y - ax, x) = 0 \Leftrightarrow \|y - ax\|^2 = g(y - ax, y), \\ \text{sgn } a &= \text{sgn } g(y, x).\end{aligned}$$

2. *If  $z \in \text{span}\{x, y\}$  and  $y \perp_B x \wedge z \perp_B x$ , then there exists  $\lambda \in \mathbb{R}$  such that  $z = \lambda y$ .*



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3. If  $x \perp_B y - \alpha x \wedge x \perp_B y - \beta x$  then  $\alpha = \beta$ .

*Proof.*

1. The proof can be found in [14].
2. Since  $X$  is smooth, the equivalence

$$y \perp_B x \wedge z \perp_B x \Leftrightarrow g(y, x) = 0 \wedge g(z, x) = 0$$

holds.

Hence

$$x = \alpha y + \beta z \Rightarrow g(y, \alpha x + \beta z) = 0 \wedge g(z, \alpha x + \beta z) = 0.$$

We get the system of equations

$$\alpha \|y\|^2 + \beta g(y, z) = 0$$

$$\alpha g(z, x) + \beta \|z\|^2 = 0.$$

This system has a non-trivial solution for  $\alpha$  and  $\beta$  iff

$$g(y, z)g(z, y) = \|y\|^2 \|z\|^2 \Leftrightarrow |g(y, z)| |g(z, y)| = \|y\|^2 \|z\|^2.$$

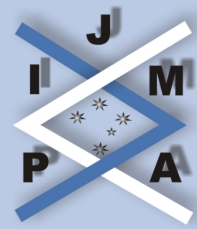
The last equation is not correct if  $|g(y, z)| < \|y\| \|z\|$ . So,  $|g(y, z)| = \|y\| \|z\|$ . Then by Lemma 5 of [3], there exists  $\lambda \in \mathbb{R}$  such that  $z = \lambda y$ .

3. In accordance with 1) we have

$$g(x, y - \alpha x) = 0 \wedge g(x, y - \beta x) = 0$$

$$\Leftrightarrow g(x, y) - \alpha \|x\|^2 = 0 \wedge g(x, y) - \beta \|x\|^2 = 0 \Rightarrow \alpha = \beta.$$

□



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From now on we assume that points  $0, x, y$  are the vertices of the triangle  $(0, x, y)$  and points  $0, x, y, x + y$  are the vertices of the parallelogram  $(0, x, y, x + y)$ . The numbers  $\|x - y\|$ ,  $\|x + y\|$  are the lengths of diagonal of this parallelogram. If  $\|x\| = \|y\|$ , we say that this parallelogram is a rhomb, and if  $x \perp_{\rho} y$ , we say that this parallelogram is a  $\rho$ -rectangle,  $\rho \in \left\{ \perp_B, \perp_J, \perp_S, \perp_g \right\}$ .

From the next theorem, we see the similarity of  $q.i.p.$  spaces to inner-product spaces ( $i.p.$  spaces).

**Theorem 2.** *Let  $X$  be a  $q.i.p.$  space. The following assertions are valid.*

1. *The lengths of the diagonals in parallelogram  $(0, x, y, x + y)$  are equal if and only if the parallelogram is a  $g$ -rectangle, i.e.,  $x \perp_g y$ .*
2. *The diagonals of the rhomb  $(0, x, y, x + y)$  are  $g$ -orthogonal, i.e.,  $(x - y) \perp_g (x + y)$ .*
3. *The parallelogram  $(0, x, y, x + y)$  is a  $g$ -quadrangle if and only if the lengths of its diagonals are equal and the diagonals are  $g$ -orthogonal.*

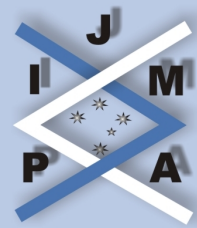
The proof of Theorem 2 can be found in [11].

The angle between two vectors  $x$  and  $y$  in a real normed space was introduced in [7] as

$$\angle(x, y) := \arccos \frac{g(x, y) + g(y, x)}{2 \|x\| \|y\|} \quad (x, y \in X - \{0\}).$$

So,  $x \perp_g y \Leftrightarrow \cos \angle(x, y) = 0$ .

In this paper we introduce several definitions of angles in a smooth normed space  $X$ .



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Let us begin with the following observations. By (2), it is easily seen that we have

$$(4) \quad -1 \leq \frac{\|x\|^2 g(x, y) + \|y\|^2 g(y, x)}{\|x\| \|y\| (\|x\|^2 + \|y\|^2)} \leq 1 \quad (x, y \in X - \{0\}).$$

Hence we define new angle between the vectors  $x$  and  $y$ , denoted as  $\angle_g(x, y)$ .

**Definition 2.** *The number*

$$\angle_g(x, y) := \arccos \frac{\|x\|^2 g(x, y) + \|y\|^2 g(y, x)}{\|x\| \|y\| (\|x\|^2 + \|y\|^2)}$$

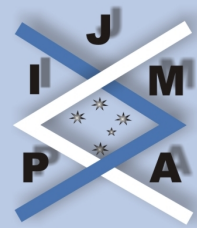
*is called the  $g$ -angle between the vector  $x$  and the vector  $y$ .*

It is very easy to see that :

$$\angle_g(x, y) = \angle_g(y, x), \quad \angle_g(\lambda x, \lambda y) = \angle_g(x, y), \quad x \perp_g y \Leftrightarrow \cos \angle_g(x, y) = 0.$$

**Theorem 3.** *Let  $X$  be a  $q.i.p.$  space. Then the following assertions hold.*

- 1. The  $g$ -angle over the diameter of a circle is  $g$ -right, i.e., if  $c$  is the circle in  $\text{span}\{x, y\}$ , centered at  $\frac{x+y}{2}$  of radius  $\frac{\|x-y\|}{2}$ , then  $z \in c \Rightarrow (x-z) \perp_g (y-z)$ ,  
Figure 1.*
- 2. The centre of the circumscribed circumference about the  $g$ -right triangle is the centre of the  $g$ -hypotenuse.*



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*Proof.*

1. If  $z \in c$ , then  $\|z - \frac{x+y}{2}\| = \frac{\|x-y\|}{2}$ , i.e.  $\|2z - (x+y)\| = \|x-y\|$ . Hence
- $$(x-z) \perp_J (y-z) \Leftrightarrow (x-z) \perp_g (y-z),$$

because  $X$  is a  $q.i.p.$  space.

2. Let  $c$  be the circle defined by the equation  $\|z - \frac{x+y}{2}\| = \frac{\|x-y\|}{2}$ , where  $x \perp_g y$  i.e.  $\|x-y\| = \|x+y\|$ . Then  $0 \in c$ .

□

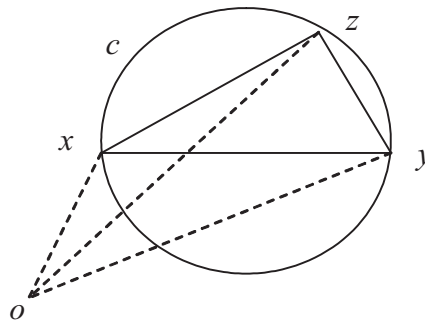


Figure 1:

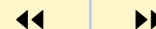
In accordance with  $B$ -orthogonality, now we define the oriented  $B$ -angle between vectors  $x$  and  $y$ .

Firstly, we have the following observation. Let  $P_{[x]}y = ax$ , ( $a = a(x, y)$ ). If  $\|ax\| \leq \|y\|$  for every  $x, y \in X - \{0\}$ , then  $X$  is an  $i.p.$  space (see (18.1) in [4]). So, in a normed (non trivial) space, a  $B$ -catheti may be greater than the hypotenuse.



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**Lemma 4.** Let  $X$  be a smooth and uniformly convex space and  $x, y \in X - \{0\}$  linearly independent. Then there exists a unique  $\tau = \tau(x, y)$  such that  $\|y\| = \|y - \tau x\|$ . If  $X$  is a  $q.i.p.$  space and  $y$  is not  $B$ -orthogonal to  $x$ , then there exist unique  $p \in \mathbb{R}$  such that  $(y - px) \perp_g px$ .

*Proof.* We consider the function

$$f(t) = \|y - tx\| \quad (x, y \in X - \{0\}, \quad t \in \mathbb{R}).$$

Since  $X$  is smooth and uniformly convex, there exists a unique  $a = a(x, y) \in \mathbb{R}$  such that

$$(5) \quad \min_{t \in \mathbb{R}} f(t) = f(a) = \|y - ax\|, \quad g(y - ax, x) = 0, \quad \text{sgn } a = \text{sgn } g(y, x).$$

(The vector  $ax$  is the best approximation of vector  $y$  with vectors of  $[x]$ , i.e.,  $P_{[x]}y = ax$  (see [14]).

On the other hand, the function  $f$  is continuous and convex on  $\mathbb{R}$  and therefore there exists a unique  $\tau = \tau(x, y) \in \mathbb{R}$  (see Figure 2) such that

$$f(a) < \|y\| = \|y - \tau x\|.$$

If  $X$  is a  $q.i.p.$  space, we get  $p = \frac{\tau}{2}$ . In this case, we have  $\|y\| = \|y - 2px\|$ , hence

$$\|(y - px) + px\| = \|(y - px) - px\|,$$

i.e.

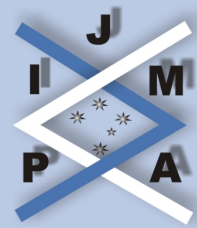
$$(y - px) \perp_J px \Leftrightarrow (y - px) \perp_g px.$$

In this case we shall write  $P_x^g y = px$ . Clearly  $\|y\| = \|y - 2px\| \Rightarrow \|px\| \leq \|y\|$ .

In (5) we have:

$$0 < a < \tau \Leftrightarrow g(y, x) > 0, \quad \tau < a < 0 \Leftrightarrow g(y, x) < 0 \quad (\text{Figure 2}).$$





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Hence, by  $\|y\| = \|y - \tau x\|$  we get  $\|\tau x\| - \|y\| \leq \|y\|$ , i.e.

$$(6) \quad \frac{\|\tau x\|}{2} \leq \|y\|.$$

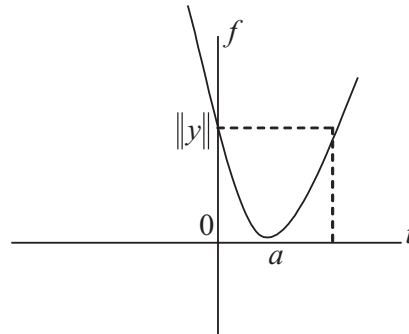


Figure 2:

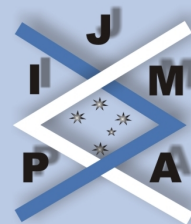
Assume that  $g(y, x) > 0$ . If  $a < \frac{\tau}{2}$ , then by (5) we have  $\|ax\| \leq \frac{\|\tau x\|}{2} \leq \|y\|$ . If  $a \geq \frac{\tau}{2}$ , then  $\tau - a \leq \frac{\tau}{2}$  and we have  $\|(\tau - a)x\| \leq \frac{\|\tau x\|}{2} \leq \|y\|$ . Hence we get  $\min \{a, \tau - a\} \leq \frac{\tau}{2}$ .

Of course, if  $g(y, x) < 0$ , we get  $\min \{|a|, |\tau - a|\} \leq \frac{|\tau|}{2}$ . Thus, we conclude that

$$(7) \quad -1 \leq \frac{\|kx\|}{\|y\|} \operatorname{sgn} g(y, x) \leq 1 \quad (x, y \in X - \{0\}),$$

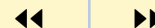
where  $k = \min \{|a|, |\tau - a|\}$  ( $k = k(x, y)$ ). □

Keeping in mind (7) and the characteristics of  $B$ -orthogonality, we introduce the



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following definitions of the oriented  $B$ -angle between the vector  $x$  and the vector  $y$ .

**Definition 3.** Let  $X$  be smooth and uniformly convex. The number

$$(8) \quad \cos_B(x, y) := \frac{\|kx\|}{\|y\|} \operatorname{sgn} g(y, x),$$

$$k = \min \{|a|, |\tau - a|\}, \quad (x, y \in X - \{0\})$$

is called the  $B$ -cosine of the oriented angle between  $x$  and  $y$ .

The number

$$\angle_B(\overrightarrow{x}, \overrightarrow{y}) := \arccos_B(\overrightarrow{x}, \overrightarrow{y})$$

is the oriented  $B$ -angle between the vector  $x$  and the vector  $y$ .

**Definition 4.**

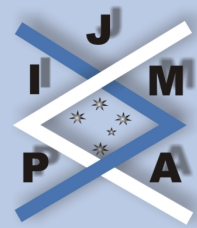
$$\cos_B(x, y) := \sqrt{|\cos_B(\overrightarrow{x}, \overrightarrow{y}) \cos_B(\overrightarrow{y}, \overrightarrow{x})|} \operatorname{sgn} g(x, y) \operatorname{sgn} g(y, x).$$

The number  $\angle_B(x, y) := \arccos_B(x, y)$  is called the  $B$ -angle between the vector  $x$  and the vector  $y$ .

If  $X$  is an *i.p.* space with *i.p.*  $\langle \cdot, \cdot \rangle$ , we have  $a = \frac{g(x, y)}{\|x\|^2} = \frac{\langle x, y \rangle}{\|x\|^2} = \frac{g(y, x)}{\|x\|^2}$  (see [14]).

So, in this case  $\cos_B(x, y) = \frac{\langle x, y \rangle}{\|x\| \|y\|}$ . Observe that  $\cos_B(x, y)$  is not symmetric in  $x$  and  $y$ , so, in the triangle  $(0, x, y)$  we have 6 oriented  $B$ -angles.

Since inequalities  $-1 \leq \frac{|g(x, y)|}{\|x\| \|y\|} \leq 1$  are valid for every  $x, y \in X - \{0\}$  and  $y \perp_B x \Leftrightarrow g(y, x) = 0$  in a smooth space, we may ask whether  $\cos_B(\overrightarrow{x}, \overrightarrow{y}) = \frac{g(y, x)}{\|x\| \|y\|}$  for every  $x, y \in X$ . The answer is no. Namely, in this case we have  $a(x, y) = \frac{g(y, x)}{\|x\|^2}$  and hence, for every  $x, y \in X - \{0\}$ , we get  $\|ax\| = \frac{|g(y, x)|}{\|x\|} \leq \|y\|$ . It follows from 18.1 of [4] that  $X$  is an *i.p.* space.



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**Theorem 5.** Let  $X$  be a smooth and strictly convex space. Then,

- $\cos_B(\overrightarrow{\lambda x, y}) = \cos_B(\overrightarrow{x, y}) \operatorname{sgn} \lambda \quad (\lambda \in \mathbb{R} - \{0\}),$
- $\cos_B(x, \overrightarrow{\lambda y}) = \cos_B(\overrightarrow{x, y}) \operatorname{sgn} \lambda \quad (\lambda \in \mathbb{R} - \{0\}).$

*Proof.*

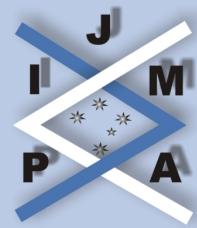
- Assume that  $P_{[x]}y = ax$ ,  $k = \{|a|, |\tau - a|\}$ ,  $\|y\| = \|y - \tau x\|$ ,  $P_{[\lambda x]}y = b\lambda x$ . Then  $b\lambda = a$  and  $\min\{|b\lambda|, |\tau - b\lambda|\} = \min\{|a|, |\tau - a|\} = k$ . Hence, by Definition 3, we have

$$\begin{aligned} \cos_B(\overrightarrow{\lambda x, y}) &= \frac{\min\{|\lambda b|, |\tau - \lambda b|\} \|x\|}{\|y\|} \operatorname{sgn} g(y, \lambda x) \\ &= \frac{\|kx\|}{\|y\|} \operatorname{sgn} \lambda g(y, x) = \cos_B(\overrightarrow{x, y}) \operatorname{sgn} \lambda. \end{aligned}$$

- Let be  $P_{[x]}y = ax$ ,  $\|y\| = \|y - \tau x\|$  and  $\|\lambda y\| = \|\lambda y - \tau_\lambda x\|$ . Then  $P_{[x]}\lambda y = \lambda ax$  and by  $\|\lambda y\| = \|\lambda y - \tau_\lambda x\|$  we get  $\tau_\lambda = \lambda\tau$  and  $k_\lambda = \min\{|\lambda a|, |\lambda\tau - \lambda a|\} = |\lambda| k$ . Thus

$$\begin{aligned} \cos_B(\overrightarrow{x, \lambda y}) &= \frac{\|k_\lambda x\|}{\|\lambda y\|} \operatorname{sgn} g(\lambda y, x) \\ &= \frac{\|kx\|}{\|y\|} \operatorname{sgn} \lambda g(y, x) \\ &= \cos_B(\overrightarrow{x, y}) \operatorname{sgn} \lambda. \end{aligned}$$

□



**Theorem 6.** Let  $X$  be smooth,  $x, y \in X - \{0\}$  linearly independent,  $\|y - x\| = \|y\|$ . Then  $(\angle_B(\overrightarrow{x, y})) = \angle_B(\overrightarrow{-x, y - x})$ , (Figure 3).

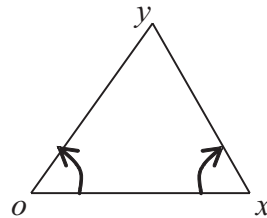


Figure 3:

*Proof.* In a smooth space  $X$  (see [12]), for  $x, y \in X$ , we have

$$(9) \quad \|x\| (\|x\| - \|x - y\|) \leq g(x, y) \leq \|x\| (\|x + y\| - \|x\|).$$

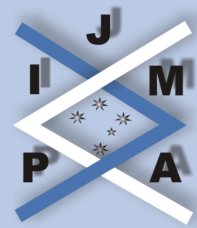
Since  $\|y - x\| = \|y\|$ , we get  $g(y, x) > 0$  and  $g(y - x, -x) > 0$ . Let  $P_{[x]}y = ax$  and  $P_{[x]}(y - x) = b$ . Then:  $a > 0$ ,  $b > 0$  (see [14]),  $g(y - ax, x) = 0$  and

$$g(y - x - bx, x) = 0 \Leftrightarrow g(y - (1 + b)x, x) = 0.$$

By virtue of 2) in Theorem 1, we get  $1 + b = a$  such that  $P_{[x]}(y - x) = (a - 1)x$ . From this and Definition 3, we have

$$\begin{aligned} \cos_B(\overrightarrow{-x, y - x}) &= \frac{\|kx\|}{\|y - x\|} \operatorname{sgn} g(y - x, -x) \\ &= \frac{\min\{a, 1 - a\} \|x\|}{\|y\|} = \cos_B(\overrightarrow{x, y}). \end{aligned}$$

□



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We now assume that  $X$  is a *s.i.p.* space.

Analogous to Definition 3 and Definition 4, in a *q.i.p.* space, we will introduce a new definition of an oriented  $g$ -angle and the corresponding non oriented  $g$ -angle.

**Definition 5.** Let  $x \neq 0, y \in X$  and  $p = \frac{\tau}{2}$  (see Lemma 4). Then

$$\cos_g(\overrightarrow{x}, \overrightarrow{y}) := \frac{\|px\|}{\|y\|} \operatorname{sgn}(\|x\|^2 g(x, y) + \|y\|^2 g(y, x)).$$

The number  $\angle_g(\overrightarrow{x}, \overrightarrow{y}) := \arccos_g(\overrightarrow{x}, \overrightarrow{y})$  is the oriented  $g$ -angle between vector  $x$  and vector  $y$ .

We observe that, for all  $\lambda \neq 0$ ,

$$y - px \underset{g}{\perp} px \Rightarrow \lambda y - \lambda px \underset{g}{\perp} \lambda px,$$

i.e.,  $P_x^g y = a \Rightarrow P_{\lambda x}^g \lambda y = ax$ . Hence we have

$$(10) \quad \cos_g(\overrightarrow{\lambda x}, \overrightarrow{\lambda y}) = \cos_g(\overrightarrow{x}, \overrightarrow{y}) \operatorname{sgn} \lambda \quad (\lambda \neq 0).$$

**Definition 6.**

$$\cos_g(x, y) := \sqrt{\cos_g(\overrightarrow{x}, \overrightarrow{y}) \cos_g(\overrightarrow{y}, \overrightarrow{x})} \operatorname{sgn}(\|x\|^2 g(x, y) + \|y\|^2 g(y, x)).$$

The number  $\angle_g(x, y) := \arccos_g(x, y)$  is the non-oriented  $g$ -angle between  $x$  and  $y$ .

Clearly, in a *q.i.p.* space we have  $\cos_g(x, y) = \cos_g(y, x)$ .



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If  $X$  is an  $i.p.$  space with  $i.p.$   $\langle \cdot, \cdot \rangle$  we have

$$\begin{aligned} (y - px) \perp_g px &\Leftrightarrow \|y - px\|^2 g(y - px, px) + \|px\|^2 g(px, y - px) = 0 \\ &\Leftrightarrow (\|y - px\|^2 + \|px\|^2) \langle x, y - px \rangle = 0 \\ &\Leftrightarrow p = \frac{\langle x, y \rangle}{\|x\|^2} \\ &\Rightarrow \|px\| = \frac{|\langle x, y \rangle|}{\|x\|} \\ &\Rightarrow \cos_g(\overrightarrow{x, y}) = \frac{\|px\|}{\|y\|^2} \operatorname{sgn}((\|x\|^2 + \|y\|^2) \langle x, y \rangle) = \frac{\langle x, y \rangle}{\|x\| \|y\|}. \end{aligned}$$

Thus, Definition 5 and Definition 6 are correct.

**Theorem 7.** Let  $X$  be a  $q.i.p.$  space and  $\|x\| = \|y\| = \|x - y\|$ , i.e., let triangle  $(0, x, y)$  be equilateral. Then

$$\angle_g(\overrightarrow{x, y}) = \angle_g(x, y) = \angle_g(y, x) = \frac{\pi}{3}.$$

*Proof.* At first, from equations  $\|x\| = \|y\| = \|y - x\|$  and inequalities (9) we get inequalities  $0 < g(x, y)$  and  $0 < g(y, x)$ . By this  $\operatorname{sgn}(\|x\|^2 g(x, y) + \|y\|^2 g(y, x)) = 1$ .

Let  $c$  be the circle centred at  $\frac{x}{2}$  with diameter  $\|x\|$ , (see Figure 4). Then  $\frac{y}{2}, \frac{x+y}{2} \in c$ . According to 1), Theorem 3, we have  $(x - \frac{y}{2}) \perp_g \frac{y}{2}$  and  $\frac{x+y}{2} \perp_g \frac{x-y}{2}$ . That is, we have

$P_x^g y = \frac{x}{2}$  and  $P_y^g x = \frac{y}{2}$ . By Definition 5 we get  $\cos_g(\overrightarrow{x, y}) = \cos_g(y, x) = \frac{1}{2}$ . Hence, by Definition 6, we have  $\angle_g(x, y) = \frac{\pi}{3}$ .  $\square$

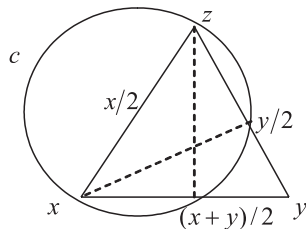


Figure 4:

**Theorem 8.** Let  $(0, x, y, x + y)$  be a  $g$ -quadrangle, i.e. let  $\|x\| = \|y\| \wedge x \perp_g y$ . Then  $\angle_g(x, x + y) = \frac{\pi}{4}$ , i.e., the non-oriented  $g$ -angle between a diagonal and a side is  $\frac{\pi}{4}$ .

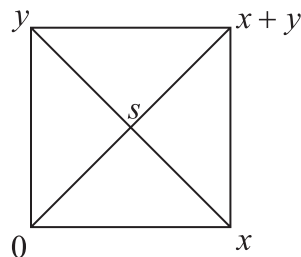


Figure 5:

*Proof.* We observe that in a  $q.i.p.$  space

$$\operatorname{sgn}(\|x\|^2 g(x, y) + \|y\|^2 g(y, x)) = \operatorname{sgn}(\|x + y\| - \|x - y\|)$$



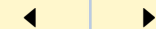
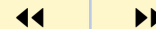
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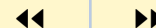
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and that

$$\|2x + y\| - \|x\| \geq \|2x\| - \|y\| - \|y\| = 0.$$

Now consider Figure 5. Since  $P_x^g(x + y) = x$ , we have

$$\cos_g(\overrightarrow{x, x + y}) = \frac{\|x\|}{\|x + y\|} \operatorname{sgn}(\|2x + y\| - \|y\|) = \frac{\|x\|}{\|x + y\|}.$$

Let  $s$  be the crossing point of the diagonal  $[0, x + y]$  and the diagonal  $[x, y]$ . Then, by Theorem 3,  $P_{x+y}^g x = s$ . It follows, by Definition 5, that

$$\begin{aligned} \cos_g(\overrightarrow{x + y, x}) &= \frac{\|s\|}{\|x\|} \operatorname{sgn}(\|s + x\| - \|s - x\|) \\ &= \frac{\|x + y\|}{2\|x\|} \operatorname{sgn}(\|2x\| - \|x\|) \\ &= \frac{\|x + y\|}{2\|x\|}. \end{aligned}$$

So, by Definition 6, we have

$$\begin{aligned} \cos_g(x, x + y) &= \sqrt{\cos_g(\overrightarrow{x, x + y}) \cos_g(\overrightarrow{x + y, x}) \operatorname{sgn}(\|2x + y\| - \|y\|)} \\ &= \sqrt{\frac{1}{2}} = \frac{\sqrt{2}}{2}. \end{aligned}$$

Hence  $\angle_g(x, x + y) = \frac{\pi}{4}$ . □



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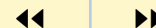
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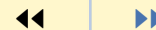
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