# POSITIVE SOLUTIONS OF INEQUALITY WITH $p$-LAPLACIAN IN EXTERIOR DOMAINS 

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(Received March 8, 2001)

Abstract. In the paper the differential inequality

$$
\Delta_{p} u+B(x, u) \leqslant 0,
$$

where $\Delta_{p} u=\operatorname{div}\left(\|\nabla u\|^{p-2} \nabla u\right), p>1, B(x, u) \in C\left(\mathbb{R}^{n} \times \mathbb{R}, \mathbb{R}\right)$ is studied. Sufficient conditions on the function $B(x, u)$ are established, which guarantee nonexistence of an eventually positive solution. The generalized Riccati transformation is the main tool.

Keywords: p-Laplacian, oscillation criteria
MSC 2000: 35B05

## 1. Introduction

In the paper we study positive solutions of the partial differential inequality

$$
\begin{equation*}
\Delta_{p} u+B(x, u) \leqslant 0 \tag{1}
\end{equation*}
$$

where $\Delta_{p} u=\operatorname{div}\left(\|\nabla u\|^{p-2} \nabla u\right)$ is the $p$-Laplace operator, $p>1, B(x, u): \mathbb{R}^{n} \times \mathbb{R} \rightarrow$ $\mathbb{R}$ is a continuous function, $\|\cdot\|$ is the usual Euclidean norm in $\mathbb{R}^{n}$. Inequality (1) covers several equations and inequalities studied in literature. If $p=2$ then (1) reduces to the semilinear Schrödinger inequality

$$
\begin{equation*}
\Delta u+B(x, u) \leqslant 0 \tag{2}
\end{equation*}
$$

Supported by the grant No. 923/2000 of Foundation for Development of Czech Universities.
studied in [6], [7]. Another important special case of (1) is the half-linear differential equation

$$
\begin{equation*}
\Delta_{p} u+c(x)|u|^{p-1} \operatorname{sgn} u=0 \tag{3}
\end{equation*}
$$

studied in [2], [3]. For important applications of equations with $p$-Laplacian see [1].
The aim of this paper is to introduce sufficient conditions for nonexistence of a solution which would be eventually positive (i.e., positive outside of some ball in $\mathbb{R}^{n}$ ). Remark that in a similar way one can study also negative solutions of the inequality

$$
\Delta_{p} u+B(x, u) \geqslant 0
$$

and a combination of these results produces criteria for nonexistence of a solution of the inequality

$$
\begin{equation*}
u\left[\Delta_{p} u+B(x, u)\right] \leqslant 0 \tag{4}
\end{equation*}
$$

which would have no zero outside of some ball in $\mathbb{R}^{n}$, the so called weak oscillation criteria. A simple version of this procedure is used in Corollary 6. A more elaborated version of this procedure can be found in [6].

The following notation is used throughout the paper: $\langle\cdot, \cdot\rangle$ denotes the scalar product, $q=\frac{p}{p-1}$ is the conjugate number to the number $p$,

$$
\begin{aligned}
\Omega(a, b) & =\left\{x \in \mathbb{R}^{n}: a \leqslant\|x\| \leqslant b\right\}, \\
\Omega_{a} & =\Omega(a, \infty)=\left\{x \in \mathbb{R}^{n}: a \leqslant\|x\|\right\}, \\
S_{a} & =\partial \Omega_{a}=\left\{x \in \mathbb{R}^{n}:\|x\|=a\right\},
\end{aligned}
$$

and $\omega_{1}=\int_{S_{1}} 1 \mathrm{~d} \sigma$ is the measure of the $n$-dimensional unit sphere in $\mathbb{R}^{n}$.

## 2. Riccati transformation

The main tool used for the study of positive solutions is the generalized Riccati transformation. The special case of this transformation has been used in [6], where inequality (2) is studied. A simple version of this transformation, convenient for the half-linear equation, has been introduced in [2].

Our approach combines both these methods. We use the transformation

$$
\begin{equation*}
\vec{w}(x)=-\alpha(\|x\|) \frac{\|\nabla u(x)\|^{p-2} \nabla u(x)}{\varphi(u(x))} \tag{5}
\end{equation*}
$$

$\alpha \in C^{1}\left(\left[a_{0}, \infty\right), \mathbb{R}^{+}\right), \varphi \in C^{1}\left(\mathbb{R}^{+}, \mathbb{R}^{+}\right)$which maps a positive $C^{1}$ function $u(x)$ into an $n$-vector function $\vec{w}(x)$.

Lemma 1. Let $u$ be a positive solution of (1) on $\Omega_{a_{0}}$. The $n$-vector function $\vec{w}(x)$ is well-defined by (5) and satisfies the Riccati-type inequality

$$
\begin{align*}
\operatorname{div} \vec{w}(x) \geqslant & \frac{\alpha(\|x\|) B(x, u(x))}{\varphi(u(x))}+\frac{\alpha^{\prime}(\|x\|)}{\alpha(\|x\|)}\langle\vec{\nu}(x), \vec{w}(x)\rangle  \tag{6}\\
& +\alpha^{1-q}(\|x\|) \varphi^{q-2}(u(x)) \varphi^{\prime}(u(x))\|\vec{w}(x)\|^{q}
\end{align*}
$$

on $\Omega_{a_{0}}$, where $\vec{\nu}(x)=\frac{x}{\|x\|}$ is the outward unit normal vector to the sphere $S_{\|x\|}$.
Proof. Let $u(x) \geqslant 0$ be a solution of (1) on $\Omega_{a_{0}}$ and let $\vec{w}(x)$ be defined by (5).
From (5) it follows that

$$
\operatorname{div} \vec{w}=\frac{\alpha}{\varphi(u)} \Delta_{p} u-\|\nabla u\|^{p-2}\left\langle\nabla u, \nabla\left(\frac{\alpha}{\varphi(u)}\right)\right\rangle
$$

and in view of (1)

$$
\operatorname{div} \vec{w} \geqslant \frac{\alpha B(x, u)}{\varphi(u)}-\frac{\alpha^{\prime}\|\nabla u\|^{p-2}}{\varphi(u)}\langle\nabla u, \vec{\nu}\rangle+\frac{\alpha \varphi^{\prime}(u)}{\varphi^{2}(u)}\|\nabla u\|^{p}
$$

holds (the dependence on $x \in \Omega_{a_{0}}$ is suppressed in the notation). In view of (5) this inequality is equivalent to (6).

## 3. Nonexistence of positive solution

The main result of the paper is the following

Theorem 1. Let $a_{0} \geqslant 0$. Suppose that there exist functions

$$
\alpha \in C^{1}\left(\left[a_{0}, \infty\right), \mathbb{R}^{+}\right), \quad \varphi \in C^{1}\left(\mathbb{R}^{+}, \mathbb{R}^{+}\right), \quad c \in C\left(\mathbb{R}^{n}, \mathbb{R}\right),
$$

and numbers $k, l, k>0, l>1$, such that
(i) $B(x, u) \geqslant c(x) \varphi(u)$ for $x \in \mathbb{R}^{n}, u>0$,
(ii) $\varphi^{\prime}(u) \varphi^{q-2}(u) \geqslant k$ for $u>0$,
(iii) $\lim _{r \rightarrow \infty} \int_{\Omega\left(a_{0}, r\right)}\left[\alpha(\|x\|) c(x)-\frac{1}{p}\left(\frac{l}{k q}\right)^{p-1}\left|\alpha^{\prime}(\|x\|)\right|^{p} \alpha^{1-p}(\|x\|)\right] \mathrm{d} x=+\infty$,
(iv) $\lim _{r \rightarrow \infty} \int_{a_{0}}^{r} \alpha^{\frac{1}{1-p}}(r) r^{\frac{1-n}{p-1}} \mathrm{~d} r=+\infty$.

Then (1) has no positive solution on $\Omega_{a}$ for arbitrary $a>0$.

Proof. Suppose, by contradiction, that $u$ is a solution of (1) positive on $\Omega_{a}$ for some $a>a_{0}$. Lemma 1 and the assumptions (i), (ii) imply

$$
\begin{aligned}
\operatorname{div} \vec{w} & \geqslant \alpha c+\frac{\alpha^{\prime}}{\alpha}\langle\vec{\nu}, \vec{w}\rangle+\alpha^{1-q} k\|\vec{w}\|^{q} \\
& =\alpha c+\alpha^{1-q} \frac{k q}{l}\left[\frac{\|w\|^{q}}{q}+\left\langle\vec{w} \frac{l \alpha^{q-2} \alpha^{\prime}}{k q} \vec{\nu}\right\rangle\right]+\alpha^{1-q} \frac{k}{l^{*}}\|\vec{w}\|^{q}
\end{aligned}
$$

where $l^{*}=\frac{l}{l-1}$ is the conjugate number to the number $l$. The Young inequality implies

$$
\frac{\|\vec{w}\|^{q}}{q}+\left\langle\vec{w} \frac{l \alpha^{q-2} \alpha^{\prime}}{q k} \vec{\nu}\right\rangle+\frac{1}{p}\left(\frac{l \alpha^{q-2}\left|\alpha^{\prime}\right|}{q k}\right)^{p} \geqslant 0
$$

Combining both these inequalities we obtain

$$
\begin{aligned}
\operatorname{div} \vec{w} & \geqslant \alpha c-\alpha^{1-q} \frac{k q}{l p}\left(\frac{l \alpha^{q-2}\left|\alpha^{\prime}\right|}{q k}\right)^{p}+\alpha^{1-q} \frac{k}{l^{*}}\|\vec{w}\|^{q} \\
& =\alpha c-\frac{1}{p}\left(\frac{l}{q k}\right)^{p-1}\left|\alpha^{\prime}\right|^{p} \alpha^{1-p}+\alpha^{1-q} \frac{k}{l^{*}}\|\vec{w}\|^{q} .
\end{aligned}
$$

Integration of the last inequality over $\Omega(a, r)$ and the Gauss-Ostrogradski divergence theorem gives

$$
\begin{aligned}
\int_{S_{r}}\langle\vec{w}, \vec{\nu}\rangle \mathrm{d} \sigma & -\int_{S_{a}}\langle\vec{w}, \vec{\nu}\rangle \mathrm{d} \sigma \geqslant \frac{k}{l^{*}} \int_{\Omega(a, r)} \alpha^{1-q}\|\vec{w}\|^{q} \mathrm{~d} x \\
& +\int_{\Omega(a, r)}\left[\alpha c-\frac{1}{p}\left(\frac{l}{q k}\right)^{p-1} p\left|\alpha^{\prime}\right|^{p} \alpha^{1-p}\right] \mathrm{d} x
\end{aligned}
$$

By assumption (iii) there exists $r_{0}, r_{0}>a$, such that

$$
\int_{\Omega(a, r)}\left[\alpha c-\frac{1}{p}\left(\frac{l}{q k}\right)^{p-1}\left|\alpha^{\prime}\right|^{p} \alpha^{1-p}\right] \mathrm{d} x+\int_{S_{a}}\langle\vec{w}, \vec{\nu}\rangle \mathrm{d} \sigma \geqslant 0 \quad \text { for } r>r_{0}
$$

Hence

$$
\begin{equation*}
\int_{S_{r}}\langle\vec{w}, \vec{\nu}\rangle \mathrm{d} \sigma \geqslant \frac{k}{l^{*}} g(r) \tag{7}
\end{equation*}
$$

holds for $r>r_{0}$, where

$$
g(r)=\int_{\Omega(a, r)} \alpha^{1-q}(\|x\|)\|\vec{w}(x)\|^{q} \mathrm{~d} x
$$

The Hölder inequality gives

$$
\begin{equation*}
\int_{S_{r}}\langle\vec{w}, \vec{\nu}\rangle \mathrm{d} \sigma \leqslant\left(\int_{S_{r}}\|w\|^{q} \mathrm{~d} \sigma\right)^{\frac{1}{q}}\left(\int_{S_{r}} 1 \mathrm{~d} \sigma\right)^{\frac{1}{p}}=\alpha^{\frac{1}{p}}(r)\left(g^{\prime}(r)\right)^{\frac{1}{q}} \omega_{1}^{\frac{1}{p}} r^{\frac{n-1}{p}} \tag{8}
\end{equation*}
$$

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From (7) and (8) we obtain

$$
\left(g^{\prime}(r)\right)^{\frac{1}{q}} \alpha^{\frac{1}{p}}(r) \omega_{1}^{\frac{1}{p}} r^{\frac{n-1}{p}} \geqslant \frac{k}{l^{*}} g(r) \quad \text { for } \quad r \geqslant r_{0}
$$

and equivalently

$$
\frac{g^{\prime}(r)}{g^{q}(r)} \omega_{1}^{\frac{q}{p}} \geqslant\left(\frac{k}{l^{*}}\right)^{q} \alpha^{-\frac{q}{p}}(r) r^{(1-n) \frac{q}{p}}=\left(\frac{k}{l^{*}}\right)^{q} \alpha^{\frac{1}{1-p}}(r) r^{\frac{1-n}{p-1}} \quad \text { for } \quad r \geqslant r_{0}
$$

Integration of this inequality over the interval $\left(r_{0}, \infty\right)$ gives a convergent integral on the left-hand side and a divergent integral on the right-hand side of this inequality, by virtue of the assumption (iv). This contradiction completes the proof.

Remark 1. For $\varphi(u)=u^{p-1}$ we have $\varphi^{\prime}(u) \varphi^{q-2}(u)=p-1$ and the assumption (ii) holds with $k=p-1$. Conversely, $\varphi(u) \geqslant\left(\frac{k}{p-1}\right)^{p-1} u^{p-1}$ is necessary for (ii) to be satisfied. Remark also that neither sign restrictions, nor radial symmetry, are supposed for the function $c(x)$ in (i).

Corollary 2 (Leighton type criterion). Let $p \geqslant n$. Suppose that there exists a continuous function $c(x)$ such that

$$
\begin{equation*}
B(x, u) \geqslant c(x) u^{p-1} \quad \text { for } u>0 \tag{9}
\end{equation*}
$$

and

$$
\begin{equation*}
\lim _{r \rightarrow \infty} \int_{\Omega(1, r)} c(x) \mathrm{d} x=+\infty \tag{10}
\end{equation*}
$$

Then (1) has no positive solution on $\Omega_{a}$ for arbitrary $a>0$.
Proof. Follows from Theorem 1 for $\alpha(r) \equiv 1$ and $\varphi(u)=u^{p-1}$.
Remark2. Remark that (10) is known to be a sufficient condition for oscillation of (3) provided $p \geqslant n$, see [2]. It is also known that the condition $p \geqslant n$ in this criterion cannot be omitted.

Corollary 3. Suppose that (9) holds and there exists $m>1$ such that

$$
\begin{equation*}
\lim _{r \rightarrow \infty} \int_{\Omega(1, r)}\left[\|x\|^{p-n} c(x)-m\left|\frac{p-n}{p}\right|^{p} \frac{1}{\|x\|^{n}}\right] \mathrm{d} x=+\infty . \tag{11}
\end{equation*}
$$

Then (1) has no positive solution on $\Omega_{a}$ for arbitrary $a>0$.
Proof. Follows from Theorem 1 for $\alpha(r)=r^{p-n}$ and $\varphi(u)=u^{p-1}, m=l^{p-1}$.

Remark 3. If the limit $\lim _{r \rightarrow \infty} \frac{1}{\ln r} \int_{\Omega(1, r)}\|x\|^{p-n} c(x) \mathrm{d} x$ exists, or if this limit equals $+\infty$, then (11) is equivalent to the condition

$$
\lim _{r \rightarrow \infty} \frac{1}{\ln r} \int_{\Omega(1, r)}\|x\|^{p-n} c(x) \mathrm{d} x>\omega_{1}\left|\frac{p-n}{p}\right|^{p}
$$

This condition is very close to the criterion for oscillation of the half-linear equation [5, Corollary 2.1], which contains "lim sup" instead of "lim" and one additional condition

$$
\liminf _{r \rightarrow \infty}\left[r^{p-1}\left(C_{0}-\int_{\Omega(1, r)}\|x\|^{1-n} c(x) \mathrm{d} x\right)\right]>-\infty
$$

where

$$
C_{0}=\lim _{r \rightarrow \infty} \frac{p-1}{r^{p-1}} \int_{1}^{r} t^{p-2} \int_{\Omega(1, t)}\|x\|^{1-n} c(x) \mathrm{d} x \mathrm{~d} t
$$

Among other, the constant $\left|\frac{p-n}{p}\right|^{p}$ is here shown to be optimal.
Corollary 4. Let $p \geqslant n, p>2$, (9) and

$$
\lim _{r \rightarrow \infty} \int_{\Omega(\cdot, r)} \ln (\|x\|) c(x) \mathrm{d} x=+\infty
$$

Then (1) has no positive solution on $\Omega_{a}$ for arbitrary $a>0$.
Proof. Let $a>e, p \geqslant n, p>2, \alpha(r)=\ln r$. Since

$$
\lim _{r \rightarrow \infty} \frac{\alpha^{\frac{1}{1-p}}(r) r^{\frac{1-n}{p-1}}}{\frac{1}{r \ln r}}=\lim _{r \rightarrow \infty} r^{\frac{p-n}{p-1}} \ln ^{\frac{p-2}{p-1}} r \geqslant 1
$$

the condition (iv) of Theorem 1 holds. Further,

$$
\begin{aligned}
\int_{\Omega(e, r)}\left|\alpha^{\prime}(\|x\|)\right|^{p} \alpha^{1-p}(\|x\|) \mathrm{d} x & =\omega_{1} \int_{e}^{r} \xi^{n-1-p} \ln ^{1-p} \xi \mathrm{~d} \xi \\
& \leqslant \omega_{1} \int_{e}^{r} \xi^{-1} \ln ^{1-p} \xi \mathrm{~d} \xi=\omega_{1} \frac{1}{p-2}\left[1-\ln ^{2-p} r\right] .
\end{aligned}
$$

Hence $\lim _{r \rightarrow \infty} \int_{\Omega(e, r)}\left|\alpha^{\prime}(\|x\|)\right|^{p} \alpha^{1-p}(\|x\|) \mathrm{d} x$ exists and (12) is equivalent to the condition (iii) of Theorem 1. Now Theorem 1 implies the conclusion.

The choice $\alpha(r)=\ln ^{\beta} r$ leads to
Corollary 5. Let $p \geqslant n$, let (9) hold and suppose that there exists $\beta, \beta \in(0, p-1)$ such that

$$
\lim _{r \rightarrow \infty} \int_{\Omega(\cdot, r)} \ln ^{\beta}(\|x\|) c(x) \mathrm{d} x=+\infty
$$

Then (1) has no positive solution on $\Omega_{a}$ for arbitrary $a>0$.
Proof. The proof is a complete analogue of the proof of Corollary 4.

Following terminology in [6], a function $f: \Omega \rightarrow \mathbb{R}$ is called weakly oscillatory if and only if $f(x)$ has a zero in $\Omega \cap \Omega_{a}$ for every $a>0$. The inequality (4) is called weakly oscillatory in $\Omega$ whenever every solution $u$ of the inequality is oscillatory in $\Omega$.

Corollary 6. Let $B(x, u): \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ be a continuous function which is odd with respect to the variable $u$, i.e. let $B(x,-u)=-B(x, u)$. Let the assumptions of Theorem 1 be satisfied. Then inequality (4) is weakly oscillatory in $\mathbb{R}^{n}$.

Proof. Suppose that there exists $a>0$ such that inequality (4) has a solution $u$ without zeros on $\Omega_{a}$. If $u$ is a positive function, then Theorem 1 yields a contradiction. Further, if $u$ is a negative solution on $\Omega_{a}$, then $v(x):=-u(x)$ is a positive solution of (4) on $\Omega_{a}$ and the same argument as in the first part of this proof leads to a contradiction.
3.1. Perturbed half-linear differential inequality. Let us consider a perturbed half-linear differential inequality

$$
\begin{equation*}
\Delta_{p} u+c(x)|u|^{p-1} \operatorname{sgn} u+\sum_{i=1}^{m} q_{i}(x) \psi_{i}(u) \leqslant 0 \tag{13}
\end{equation*}
$$

where $c(x), q_{i}(x)$ are continuous functions, $\psi_{i}(u)$ are continuously differentiable, positive and nondecreasing for $u>0$. Define

$$
q(x)=\min \left\{c(x), q_{1}(x), q_{2}(x), \ldots, q_{m}(x)\right\}
$$

and

$$
\varphi(u)=u^{p-1}+\sum_{i=1}^{m} \psi_{i}(u) .
$$

Then

$$
c(x)|u|^{p-1} \operatorname{sgn} u+\sum_{i=1}^{m} q_{i}(x) \psi_{i}(u) \geqslant q(x) \varphi(u), \quad \varphi^{\prime}(u) \varphi^{q-2}(u) \geqslant p-1
$$

and hence Theorem 1 can be applied. Remark that since $q_{i}$ may change sign, a standard argument based on the Sturmian majorant and a comparison with halflinear differential equation (3) cannot be applied (as has been explained for $p=2$ already in [6]).

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